

Algebraic structures in exceptional geometry

Martin Cederwall

Based on:

D. Berman, MC, A. Kleinschmidt, D. Thompson, JHEP 1301 (2013) 64 [arXiv:1208.5884];

MC, J. Edlund, A. Karlsson, JHEP 1307 (2013) 028 [arXiv:1302.6736];

MC, JHEP 1307 (2013) 025 [arXiv:1302.6737];

MC, J. Palmkvist, JHEP 1508 (2015) 036 [arXiv:1503.06215]; MC, JHEP 1606 (2016) 006 [arXiv:1603.04684];

L. Carbone, MC, J. Palmkvist, to appear;

G. Bossard, MC, A. Kleinschmidt, J. Palmkvist, H. Samtleben, to appear;

D. Berman, MC, C. Strickland-Constable, work in progress;

and work by others (Hull, Hohm, Zwiebach,...)

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Duality symmetries in string theory/M-theory mix gravitational and non-gravitational fields. Manifestation of such symmetries calls for a generalisation of the concept of geometry.

It has been proposed that the compactifying space (torus) is enlarged to accommodate momenta (representing momenta and brane charges) in modules of a duality group.

This leads to *double geometry*

in the context of T-duality

[Hull et al.; Hitchin;...]

and *exceptional geometry*

in the context of U-duality.

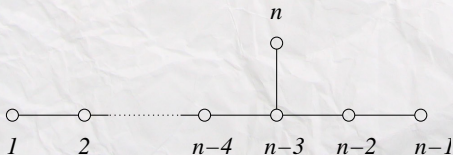
[Hull; Berman et al.; Coimbra et al.;...]

In the present talk, I will

- Describe the basics of extended geometry, with focus on the gauge transformations;
- Describe the appearance of Borcherds superalgebras and Cartan-type superalgebras (tensor hierarchy superalgebras);
- Indicate why L_∞ algebras provide a good framework for describing the gauge symmetries.

Compactify from 11 to $11 - n$ dimensions on T^n . As is well known, all fields and charges fall into modules of $E_{n(n)}$.

n	$E_{n(n)}$	
3	$SL(3) \times SL(2)$	
4	$SL(5)$	
5	$Spin(5, 5)$	
6	$E_{6(6)}$	
7	$E_{7(7)}$	
8	$E_{8(8)}$	
9	$E_{9(9)}$	



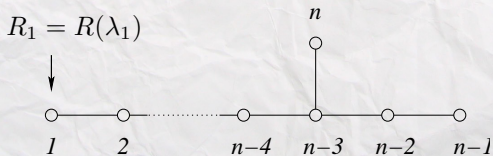
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I will focus on diffeomorphisms, and how they generalise. The ordinary diffeomorphisms go together with gauge transformations for the 3-form and (dual) 6-form fields (and for high enough n also gauge transformations for dual gravity) in an $E_{n(n)}$ module R_1 . This is the “coordinate module”. The derivative transforms in \overline{R}_1 .

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n	$E_{n(n)}$	R_1
3	$SL(3) \times SL(2)$	(3, 2)
4	$SL(5)$	10
5	$Spin(5, 5)$	16
6	$E_{6(6)}$	27
7	$E_{7(7)}$	56
8	$E_{8(8)}$	248
9	$E_{9(9)}$	fund



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Note that the duality group is not to be seen as a global symmetry.

Discrete duality transformations in $O(d, d; \mathbb{Z})$ or $E_{n(n)}(\mathbb{Z})$ should arise as symmetries in certain backgrounds, just as the mapping class group $SL(n; \mathbb{Z})$ arises as discrete isometries of a torus.

The rôle of the continuous versions of the duality groups should be analogous to that of $GL(n)$ in ordinary geometry (gravity).

Generalised diffeomorphisms

One has to decide how tensors transform.

The generic recipe is to mimic the Lie derivative for ordinary diffeomorphisms:

$$L_U V^m = U^n \partial_n V^m - \partial_n U^m V^n$$

$\uparrow \qquad \qquad \uparrow$

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In the case of U-duality, the role of GL is assumed by $E_{n(n)} \times \mathbb{R}^+$, and

$$\begin{array}{ccc} \mathcal{L}_U V^M \\ = U^N \partial_N V^M + Z^{MN}{}_{PQ} \partial_N U^P V^Q \\ \uparrow \qquad \qquad \qquad \uparrow \\ \text{transport term} \qquad \mathfrak{e}_{n(n)} \oplus \mathbb{R} \text{ transformation} \end{array}$$

where $Z^{MN}{}_{PQ} = -\alpha_n P_{\text{adj}Q}^M,{}^N_P + \beta_n \delta_Q^M \delta_P^N$.

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where $Z^{MN}{}_{PQ} = -\alpha_n P_{\text{adj}Q}^M,{}^N_P + \beta_n \delta_Q^M \delta_P^N = Y^{MN}{}_{PQ} - \delta_P^M \delta_Q^N$.

The transformations form an “algebra” for $n \leq 7$:

$$[\mathcal{L}_U, \mathcal{L}_V]W^M = \mathcal{L}_{[U,V]}W^M$$

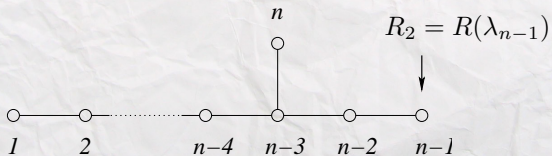
where the “Courant bracket” is $[U, V]^M = \frac{1}{2}(\mathcal{L}_U V^M - \mathcal{L}_V U^M)$, provided that the derivatives fulfil a “*section condition*”.

The *section condition* ensures that fields locally depend only on an n -dimensional subspace of the coordinates, on which a $GL(n)$ subgroup acts. It reads $Y^{MN}{}_{PQ}\partial_M \dots \partial_N = 0$, or

$$(\partial \otimes \partial)|_{\overline{R}_2} = 0$$

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n	R_1	R_2
3	$(\mathbf{3}, \mathbf{2})$	$(\overline{\mathbf{3}}, \mathbf{1})$
4	$\mathbf{10}$	$\overline{\mathbf{5}}$
5	$\mathbf{16}$	$\mathbf{10}$
6	$\mathbf{27}$	$\overline{\mathbf{27}}$
7	$\mathbf{56}$	$\mathbf{133}$
8	$\mathbf{248}$	$\mathbf{1} \oplus \mathbf{3875}$



The interpretation of the section condition is that the momenta locally are chosen so that they may span a linear subspace of cotangent space with maximal dimension, such that any pair of covectors p, p' in the subspace fulfil $(p \otimes p')|_{\overline{R}_2} = 0$.

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The corresponding statement in T-duality is $\eta^{MN} \partial_M \otimes \partial_N = 0$, where η is the $O(d, d)$ -invariant metric. The maximal linear subspace is a d -dimensional isotropic subspace, and it is determined by a pure spinor Λ . Once a Λ is chosen, the section condition can be written $\Gamma^M \Lambda \partial_M = 0$.

An analogous linear construction can be performed in the exceptional setting.

I will skip the detailed description of the generalised gravity. It effectively provides the local dynamics of gravity and 3-form, which are encoded by a vielbein E_M^A in the coset $(E_{n(n)} \times \mathbb{R})/K(E_{n(n)})$.

n	$E_{n(n)}$	$K(E_{n(n)})$
3	$SL(3) \times SL(2)$	$SO(3) \times SO(2)$
4	$SL(5)$	$SO(5)$
5	$Spin(5, 5)$	$(Spin(5) \times Spin(5))/\mathbb{Z}_2$
6	$E_{6(6)}$	$USp(8)/\mathbb{Z}_2$
7	$E_{7(7)}$	$SU(8)/\mathbb{Z}_2$
8	$E_{8(8)}$	$Spin(16)/\mathbb{Z}_2$
9	$E_{9(9)}$	$K(E_{9(9)})$

The T-duality case is described by a generalised metric or vielbein in the coset $O(d, d)/(O(d) \times O(d))$, parametrised by the ordinary metric and B -field.

With some differences from ordinary geometry, one can go through the construction of connection, torsion, metric compatibility &c., and arrive at generalised Einstein's equations encoding the equations of motion for all fields. (Done for $n \leq 8$.)

For $n = 8, 9$, the coset $E_{n(n)}/K(E_{n(n)})$ contains higher mixed tensors that do not carry independent physical degrees of freedom. They are removed by “extra” local transformations that arise in the commutator between gen. diffeomorphisms.

[Hohm, Samtleben 2014; MC, Rosabal 2015]

[Bossard, MC, Kleinschmidt, Palmkvist, Samtleben 2017 (in prep.)]

One may introduce (local) supersymmetry. In the case of T-duality, the superspace is based on the fundamental representation of an orthosymplectic supergroup $OSp(d, d|2s)$. The exceptional cases are unexplored, but will be based on ∞ -dimensional superalgebras.

[MC 2016]

Reducibility and Borchersd's superalgebras

The generalised diffeomorphisms do not satisfy a Jacobi identity. On general grounds, it can be shown that the “Jacobiator”

$$[[U, V], W] + \text{cycl} \neq 0 ,$$

but is proportional to $([U, V], W) + \text{cycl}$, where $(U, V) = \frac{1}{2}(\mathcal{L}_U V + \mathcal{L}_V U)$.

It is important to show that the Jacobiator in some sense is trivial. It turns out that $\mathcal{L}_{(U,V)} W = 0$ (for $n \leq 7$), and the interpretation is that it is a gauge transformation with a parameter representing reducibility (for $n \leq 6$).

In double geometry, this reducibility is just the scalar reducibility of a gauge transformation: $\delta B_2 = d\lambda_1$, with the reducibility $\delta\lambda_1 = d\lambda'_0$.

In exceptional geometry, the reducibility turns out to be more complicated, leading to an infinite (but well defined) reducibility, containing the modules of tensor hierarchies, and providing a natural generalisation of forms (having connection-free covariant derivatives).

The reducibility continues, and there are ghosts at all levels > 0 . The representations are those of a “tensor hierarchy”, the sequence of representations R_n of n -form gauge fields in the dimensionally reduces theory.

$$R_1 \xleftarrow{\partial} R_2 \xleftarrow{\partial} R_3 \xleftarrow{\partial} \dots$$

Example, $n = 5$:

$$\mathbf{16} \xleftarrow{\partial} \mathbf{10} \xleftarrow{\partial} \overline{\mathbf{16}} \xleftarrow{\partial} \mathbf{45} \xleftarrow{\partial} \overline{\mathbf{144}} \xleftarrow{\partial} \dots$$

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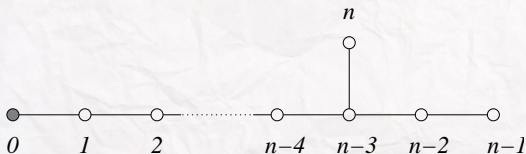
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$$16 - 10 + 16 - 45 + 144 - \dots = 11 ,$$

(suitably regularised) which is the number of degrees of freedom of a pure spinor.

The representations $\{R_n\}_{n=1}^\infty$ agree with

- The ghosts for a “pure spinor” constraint (a constraint implying an object lies in the minimal orbit);
- The positive levels of a Borcherds superalgebra $\mathcal{B}(E_n)$.



Indeed, the denominator appearing in the denominator formula for $\mathcal{B}(E_n)$ is identical to the partition function of a “pure spinor”.

[MC, Palmkvist 2015]

$$\mathcal{B}(D_n) \approx \mathfrak{osp}(n, n|2)$$

$$\mathcal{B}(A_n) \approx \mathfrak{sl}(n+1|1)$$

$$\dots \xleftarrow{\partial} R_{-1} \xleftarrow{\partial} R_0 \xleftarrow{\partial} \underbrace{R_1 \xleftarrow{\partial} R_2 \xleftarrow{\partial} \dots \xleftarrow{\partial} R_{8-n}}_{\text{covariant}} \xleftarrow{\partial} R_{9-n} \xleftarrow{\partial} R_{10-n} \xleftarrow{\partial} \dots$$

The modules R_1, \dots, R_{8-n} behave like forms. The “exterior derivative” is connection-free (for a torsion-free connection), and there is a wedge product.

[MC, Edlund, Karlsson 2013]

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[MC, Edlund, Karlsson 2013]

“Symmetry”: $R_{9-n} = \overline{R}_n$.

There is another extension to negative levels that respects this symmetry, and seems more connected to geometry: tensor hierarchy algebras.

[Palmkvist 2013]

In the classification of superalgebras by Kac, there is a special class, “Cartan-type superalgebras”.

The Cartan-type superalgebra $W(n)$, which I prefer to call $W(A_{n-1})$, is asymmetric between positive and negative levels, and (therefore) not defined through generators corresponding to simple roots and Serre relations.

$W(A_{n-1})$ is the superalgebra of derivations on the superalgebra of (pointwise) forms in n dimensions.

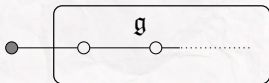
Any operation $\omega \rightarrow \Omega \wedge \iota_V \omega$, where Ω is a form and V a vector, belongs to $W(A_{n-1})$. A basis is given by

level = 1	ι_a
0	$e^b \iota_a$
-1	$e^{b_1} e^{b_2} \iota_a$
-2	$e^{b_1} e^{b_2} e^{b_3} \iota_a$
...	...

A subalgebra $S(A_{n-1})$ contains traceless tensors.

The positive levels agree with $\mathcal{B}(A_{n-1}) \approx \mathfrak{sl}(n|1)$

In spite of the absence of a Cartan involution, there is a way to give a systematic Chevalley–Serre presentation of the superalgebra, based on the same Dynkin diagram as the Borchers superalgebra.



[Carbone, MC, Palmkvist 2017 (in prep.)]

Note that the representations of torsion and torsion Bianchi identity appear at levels -1 and -2 .

The construction can be extended to $W(D_n)$, and, most interestingly, $W(E_n)$ (and the corresponding $S(\mathfrak{g})$).

The statements about torsion and Bianchi identities remain true (but we still lack a geometric argument).

Back to the Jacobi identity. Expressed in terms of a fermionic ghost in R_1 ,

$$[[c, c], c] \neq 0$$

How is this remedied? The most general formalism for gauge symmetries is the Batalin–Vilkovisky formalism, where everything is encoded in the master equation $(S, S) = 0$.

If transformations are field-independent, one may consider the ghost action consistently. An L_∞ algebra is a (super)algebraic structure which provides a perturbative solution to the master equation.

If C denotes *all* ghosts, then the master equation states the nilpotency of a transformation

$$\delta C = (S, C) = \partial C + [C, C] + [C, C, C] + [C, C, C, C] + \dots$$

The identities that need to be fulfilled are:

$$\partial^2 C = 0 ,$$

$$\partial[C, C] + 2[\partial C, C] = 0 ,$$

$$\partial[C, C, C] + 2[[C, C], C] + 3[\partial C, C, C] ,$$

...

Assuming $\partial c = 0$, the non-vanishing of $[[c, c], c]$ can be compensated by the derivative of an element in R_2 (representing reducibility). One needs to introduce a 3-bracket

$$[c, c, c] \in R_2 .$$

Then, there are more identities to check.

For double field theory, a 3-bracket is enough. [Hohm, Zwiebach 2017]

For exceptional field theory, there are signs, that one will in fact obtain arbitrarily high brackets. There are also other issues concerning the non-covariance outside the “form window”. I will not go into detail. [Berman, MC, Strickland-C, in progr.]

- Can the formalism be continued to $n > 9$? The transformations work for E_9 , and there seems to be no reason (other than mathematical difficulties) that it stops there. Is there a connection to the “ E_{10} proposal” with emergent space?
- *Geometry from algebra?* What is the precise geometric relation between the tensor hierarchy algebra and the generalised diffeomorphisms?
- *Superspace/supergeometry?* And some formalism generalising that of pure spinor superfields, that manifests supersymmetry?
- *The section condition:* Can it be lifted, or dynamically generated?
- ...

Thank you!