

# Interactions for massive mixed symmetry field

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# Outlook

- 1 Massive fields interactions a la Fradkin-Vasiliev
- 2 Electromagnetic interactions for massive hook
- 3 Gravitational interactions for massive hook

## Massless fields in a flat space

- Any attempt to switch on minimal gravitational interaction spoils gauge invariance

$$e_{\mu}^a \Rightarrow e_{\mu}^a + h_{\mu}^a, \quad D_{\mu} \Rightarrow D_{\mu} - \omega_{\mu} \quad \Longrightarrow \quad \delta S \sim R$$

where  $R$  stands for Riemann tensor and for massless fields in a flat space it can not be restored by non-minimal corrections to Lagrangian and/or gauge transformations.

- Similarly, any attempt to switch on minimal electromagnetic interactions spoils gauge invariance

$$D_{\mu} \Rightarrow D_{\mu} + e_0 A_{\mu} \quad \Longrightarrow \quad \delta S \sim F$$

where  $F$  stands for electromagnetic field strength and for massless fields in a flat space it also can not be restored by non-minimal corrections to Lagrangian and/or gauge transformations.

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## Massless fields in anti de Sitter space

- Fradkin and Vasiliev showed that in  $AdS$  space it is possible to restore broken invariance with the non-minimal corrections

$$\delta S \sim \sum \frac{1}{\Lambda^n} R^n$$

so that the flat limit  $\Lambda \rightarrow 0$  is impossible.

- Similarly, for the e/m interactions it is possible to restore broken invariance with the non-minimal corrections

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- The procedure can be reversed: starting with massless particle in flat space and non-minimal interactions with highest number of derivatives one can reproduce minimal gravitational or electromagnetic interactions by  $AdS$  deformation.

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# Frame-like formalism

- Frame-like formalism for spin 2:

$$h_{\mu\nu} \Rightarrow h_\mu^a \oplus \omega_\mu^{ab}, \quad \xi_\mu \Rightarrow \xi^a \oplus \eta^{ab}$$

On shell:  $\omega \sim Dh$ ,  $\eta \sim D\xi$

- Spin 3:

$$\begin{aligned} \Phi_{\mu\nu\alpha} &\Rightarrow \Phi_\mu^{ab} \oplus \Omega_\mu^{ab,c} \oplus \Sigma_\mu^{ab,cd} \\ \xi_{\mu\nu} &\Rightarrow \xi^{ab} \oplus \eta^{ab,c} \oplus \zeta^{ab,cd} \end{aligned}$$

On shell:  $\Omega \sim D\Phi$ ,  $\Sigma \sim D^2\Phi$ ,  $\eta \sim D\xi$ ,  $\zeta \sim D^2\xi$

- Arbitrary spin:

$$\begin{aligned} \Phi &\Rightarrow \Phi \oplus \Omega \oplus \Sigma_1 \oplus \cdots \oplus \Sigma_{s-2} \\ \xi &\Rightarrow \xi \oplus \eta \oplus \zeta_1 \oplus \cdots \oplus \zeta_{s-2} \end{aligned}$$



## Fradkin-Vasiliev approach — spin 2 example

- Free Lagrangian for massless spin 2 in  $AdS$ :

$$\mathcal{L}_0 = \frac{1}{2} \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} \omega_\mu{}^{ac} \omega_\nu{}^{bc} - \frac{1}{2} \left\{ \begin{matrix} \mu\nu\alpha \\ abc \end{matrix} \right\} \omega_\mu{}^{ab} D_\nu h_\alpha{}^c - \frac{\Lambda(d-2)}{2} \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} h_\mu{}^a h_\nu{}^b$$

- It is invariant under the following gauge transformations:

$$\delta_0 h_\mu{}^a = D_\mu \xi^a + \eta_\mu{}^a, \quad \delta_0 \omega_\mu{}^{ab} = D_\mu \eta^{ab} + \Lambda e_\mu{}^{[a} \xi^{b]}$$

- Gauge invariant objects (linearized curvature and torsion):

$$\begin{aligned} R_{\mu\nu}{}^{ab} &= D_{[\mu} \omega_{\nu]}{}^{ab} + \Lambda e_{[\mu}{}^{[a} h_{\nu]}{}^{b]} \\ T_{\mu\nu}{}^a &= D_{[\mu} h_{\nu]}{}^a - \omega_{[\mu,\nu]}{}^a \end{aligned}$$

- Free Lagrangian in terms of curvatures:

$$\mathcal{L}_0 = -\frac{1}{32\Lambda(d-3)} \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} R_{\mu\nu}{}^{ab} R_{\alpha\beta}{}^{cd}$$

## Spin 2 example (cont.)

- Deformations for curvatures:

$$\begin{aligned}\hat{R}_{\mu\nu}{}^{ab} &= D_{[\mu}\omega_{\nu]}{}^{ab} + \Lambda e_{[\mu}{}^{[a}h_{\nu]}{}^{b]} + \omega_{[\mu}{}^{ac}\omega_{\nu]}{}^{bc} - \Lambda h_{[\mu}{}^a h_{\nu]}{}^b \\ \hat{T}_{\mu\nu}{}^a &= D_{[\mu}h_{\nu]}{}^a - \omega_{[\mu,\nu]}{}^a - \omega_{[\mu}{}^{ab}h_{\nu]}{}^b\end{aligned}$$

- Corrections to gauge transformations:

$$\delta\omega_{\mu}{}^{ab} = \eta^{c[a}\omega_{\mu}{}^{b]c} - \Lambda h_{\mu}{}^{[a}\xi^{b]}, \quad \delta h_{\mu}{}^a = \eta^{ab}h_{\mu}{}^b - \omega_{\mu}{}^{ab}\xi^b$$

- Transformations for deformed curvatures:

$$\delta\hat{R}_{\mu\nu}{}^{ab} = \eta^{c[a}R_{\mu\nu}{}^{b]c} - \Lambda T_{\mu\nu}{}^{[a}\xi^{b]}, \quad \delta\hat{T}_{\mu\nu}{}^a = \eta^{ab}T_{\mu\nu}{}^b - R_{\mu\nu}{}^{ab}\xi^b$$

- Interacting Lagrangian:

$$\mathcal{L}_0 = -\frac{1}{32\Lambda(d-3)} \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} \hat{R}_{\mu\nu}{}^{ab} \hat{R}_{\alpha\beta}{}^{cd}$$

# Fradkin-Vasiliev approach for massive fields

- Two main ingredients — gauge invariance and frame-like formalism.
- There exists frame-like gauge invariant description for massive fields (both symmetric and mixed symmetry ones) that nicely works in  $(A)dS$  spaces and flat Minkowski space including all possible massless and partially massless limits.
- It seems natural to apply Fradkin-Vasiliev approach to such frame-like gauge invariant formalism for investigation of possible interactions for any combination of massive and/or massless particles.

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# Frame-like formalism for massive hook

- Free Lagrangian for massive hook in  $AdS$ :

$$\begin{aligned}
 \mathcal{L}_0 = & -\frac{3}{4} \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} \Omega_\mu{}^{acd} \Omega_\nu{}^{bcd} - \frac{3}{8} \left\{ \begin{matrix} \mu\nu\alpha \\ abc \end{matrix} \right\} \Omega_\mu{}^{abd} D_\nu \Omega_\alpha{}^{cd} - \\
 & -\frac{1}{6} C_{abc}{}^2 - \frac{1}{4} e^\mu{}_a C^{abc} D_\mu B^{bc} - \\
 & -m_2 e^\mu{}_a \left[ \frac{3}{2} \Omega_\mu{}^{abc} B^{bc} + C^{abc} \Omega_\mu{}^{bc} \right] - \\
 & -\frac{m_1^2}{2} \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} \Omega_\mu{}^{ac} \Omega_\nu{}^{bc} - \frac{\tilde{m}_1^2}{4} B_{ab}{}^2
 \end{aligned}$$

where  $3m_2^2 - m_1^2 \sim \Lambda$

- It is invariant under the following gauge transformations:

$$\begin{aligned}
 \delta \Omega_\mu{}^{abc} &= D_\mu \eta^{abc} + \frac{4m_1^2}{3(d-3)} e_\mu{}^{[a} \eta^{bc]}, & \delta \Omega_\mu{}^{ab} &= D_\mu \eta^{ab} - 2\eta_\mu{}^{ab} \\
 \delta C^{abc} &= 6m_2 \eta^{abc}, & \delta B^{ab} &= -4m_2 \eta^{ab}
 \end{aligned}$$

# Gauge invariant objects and free Lagrangian

- Gauge invariant objects (curvatures):

$$\mathcal{R}_{\mu\nu}{}^{abc} = D_{[\mu}\Omega_{\nu]}{}^{abc} + \frac{4m_2}{3(d-3)} e_{[\mu}{}^{[a} C_{\nu]}{}^{bc]} + \frac{4m_1^2}{3(d-3)} e_{[\mu}{}^{[a} \Omega_{\nu]}{}^{bc]}$$

$$\mathcal{F}_{\mu\nu}{}^{ab} = D_{[\mu}\Omega_{\nu]}{}^{ab} + 2\Omega_{[\mu,\nu]}{}^{ab} - \frac{2m_2}{(d-3)} e_{[\mu}{}^{[a} B_{\nu]}{}^{b]}$$

$$C_{\mu}{}^{abc} = D_{\mu} C^{abc} - 6m_2 \Omega_{\mu}{}^{abc} - \frac{2m_1^2}{(d-3)} e_{\mu}{}^{[a} B^{bc]}$$

$$B_{\mu}{}^{ab} = D_{\mu} B^{ab} + \frac{4}{3} C_{\mu}{}^{ab} + 4m_2 \Omega_{\mu}{}^{ab}$$

- Free Lagrangian in terms of curvatures:

$$\begin{aligned} \mathcal{L}_0 = & \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} [a_1 \mathcal{R}_{\mu\nu}{}^{abe} \mathcal{R}_{\alpha\beta}{}^{cde} + a_2 \mathcal{F}_{\mu\nu}{}^{ab} \mathcal{F}_{\alpha\beta}{}^{cd}] + \\ & + \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} [a_3 C_{\mu}{}^{acd} C_{\nu}{}^{bcd} + a_4 B_{\mu}{}^{ac} B_{\nu}{}^{bc}] \end{aligned}$$

where  $a_1, a_3 \sim \frac{1}{m_1^2}$ ,  $a_2, a_4 \sim 1$ .

## Deformations for curvatures

- Deformations for hook's curvatures correspond to standard minimal substitution  $D_\mu \Rightarrow D_\mu + e_0 A_\mu$ . After that they transform as follows:

$$\delta \hat{R}_{\mu\nu}{}^{abc,i} = e_0 \varepsilon^{ij} F_{\mu\nu} \eta^{abc,j}, \quad \delta \hat{\mathcal{F}}_{\mu\nu}{}^{ab,i} = e_0 \varepsilon^{ij} F_{\mu\nu} \eta^{ab,j}$$

- Deformations from e/m field strength turns out to be:

$$\begin{aligned} \hat{F}_{\mu\nu} = & F_{\mu\nu} + a_0 \varepsilon^{ij} [\Omega_{[\mu}{}^{abc,i} \Omega_{\nu]}{}^{abc,j} - \frac{2}{3(d-3)} C_{[\mu}{}^{ab,i} C_{\nu]}{}^{ab,j} + \\ & + \frac{2m_1^2}{(d-3)} \Omega_{[\mu}{}^{ab,i} \Omega_{\nu]}{}^{ab,j} - \frac{2m_1^2}{(d-3)^2} B_{[\mu}{}^{a,i} B_{\nu]}{}^{a,j}] \end{aligned}$$

- Transformations for deformed field strength:

$$\delta \hat{F}_{\mu\nu} = 2a_0 \varepsilon^{ij} [\mathcal{R}_{\mu\nu}{}^{abc,i} + \frac{2m_1^2}{(d-3)} \mathcal{F}_{\mu\nu}{}^{ab,i} \eta^{ab,j}]$$



# Interaction

- Interacting Lagrangian:

$$\mathcal{L} = \left\{ \begin{matrix} \mu\nu\alpha\beta \\ abcd \end{matrix} \right\} [a_1 \hat{\mathcal{R}}_{\mu\nu}{}^{abe} \hat{\mathcal{R}}_{\alpha\beta}{}^{cde} + a_2 \hat{\mathcal{F}}_{\mu\nu}{}^{ab} \hat{\mathcal{F}}_{\alpha\beta}{}^{cd}] + \\ + \left\{ \begin{matrix} \mu\nu \\ ab \end{matrix} \right\} [a_3 \hat{\mathcal{C}}_{\mu}{}^{acd} \hat{\mathcal{C}}_{\nu}{}^{bcd} + a_4 \hat{\mathcal{B}}_{\mu}{}^{ac} \hat{\mathcal{B}}_{\nu}{}^{bc}] - \frac{1}{4} \hat{\mathcal{F}}_{\mu\nu}{}^2$$

- Gauge invariance requires that

$$e_0 \sim a_0 m_1^2$$

- This includes in particular:
  - ▶ massless limit in *AdS*:  $m_2 \rightarrow 0$ ,  $m_1^2 \sim -\Lambda$
  - ▶ flat limit:  $m_2^2 \rightarrow m_1^2/3$ ,  $\Lambda \rightarrow 0$

but it is impossible to take massless limit in *dS*  $m_1 \rightarrow 0$  without switching off e/m interaction

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# Deformations for hook's curvatures

- Correspond to standard minimal substitution rules:

$$e_\mu^a \Rightarrow e_\mu^a + h_\mu^a, \quad D_\mu \Rightarrow D_\mu - \omega_\mu$$

both in curvatures as well as gauge transformations

- Transformations for deformed curvatures:

$$\begin{aligned} \delta \hat{\mathcal{R}}_{\mu\nu}{}^{abc} &= R_{\mu\nu}{}^{d[a\eta bc]d} - \frac{4m_1^2}{3(d-3)} T_{\mu\nu}{}^{[a\eta bc]} \\ \delta \hat{\mathcal{F}}_{\mu\nu}{}^{ab} &= 2\eta^{abc} T_{\mu\nu}{}^c - R_{\mu\nu}{}^{c[a\eta b]c} \\ \delta \hat{\mathcal{C}}_\mu{}^{abc} &= 0, \quad \delta \hat{\mathcal{B}}_\mu{}^{ab} = 0 \end{aligned}$$

# Deformations for gravitational curvatures

- Deformed Riemann tensor:

$$\hat{R}_{\mu\nu}{}^{ab} = R_{\mu\nu}{}^{ab} + a_0[\Omega_{[\mu}{}^{acd}\Omega_{\nu]}{}^{bcd} + \frac{4}{9(d-3)}C_{[\mu}{}^{ca}C_{\nu]}{}^{bc} - \frac{4m_1^2}{3(d-3)}\Omega_{[\mu}{}^{ca}\Omega_{\nu]}{}^{bc} - \frac{m_1^2}{3(d-3)^2}B_{[\mu}{}^aB_{\nu]}{}^b]$$

- Its transformations:

$$\delta\hat{R}_{\mu\nu}{}^{ab} = -a_0\eta^{cd[a}\mathcal{R}_{\mu\nu}{}^{b]cd} + \frac{4m_1^2a_0}{3(d-3)}\eta^{c[a}\mathcal{F}_{\mu\nu}{}^{b]c}$$

# Interaction

- Interacting Lagrangian:

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- Gauge invariance requires that

$$a_0 = \frac{9(d-3)\Lambda}{32m_1^2}$$

## Particular limits

- Massless limit in  $AdS$  space ( $m_2 \rightarrow 0$ ) is non-singular. Stueckelberg fields completely decouple and we obtain massless hook in ASV formalism interacting with gravity.
- Flat limit is non-trivial due to massless graviton:

$$\mathcal{L}_g \sim \frac{1}{\Lambda} \hat{R}^2, \quad \delta \hat{R} \sim \frac{\Lambda}{m_1^2} \mathcal{R}(\mathcal{F})$$

but at least for cubic interactions it is non-singular.

- Similarly to electromagnetic case, it is impossible to take massless limit in  $dS$  space ( $m_1 \rightarrow 0$ ) without switching off minimal interactions.

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# Conclusion

- Fradkin-Vasiliev approach with frame-like gauge invariant formalism allows one effectively investigate possible interactions for any set of massive and/or massless fields both in  $AdS$  as well as flat Minkowski space.
- One of the questions that deserves further study — flat limit for interactions of massive higher spin particles with massless gravity.
- Also it is would be interesting to understand striking difference between massless limits in  $AdS$  and  $dS$  spaces as far as possibility to switch on interactions is concerned.

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