

On dynamical equations in non-linear models

A. A. Zheltukhin

Kharkov Institute of Physics and Technology,
1, Akademicheskaya St., Kharkov, 61108, Ukraine

AAZ, arXiv: 1106.4842[hep-th]

- 1 P-brane dynamics for any (D, p)
- 2 $U(1) \times U(1) \times \dots \times U(1)$ invariant p-branes
- 3 Equations of \mathcal{U} invariant p-branes
- 4 \mathcal{U} invariant p -branes and p -dimensional anharmonic oscillators
- 5 Elliptic and hyperelliptic solutions
- 6 Summary

P-brane dynamics for any (D, p)

The Dirac action for a p -brane

$$S = T \int \sqrt{|G|} d^{p+1} \xi,$$

G is the determinant of the induced metric

$$G_{\alpha\beta} := \partial_\alpha x_m \partial_\beta x^m.$$

The Euler-Lagrange equations and $p + 1$ primary constraints

$$\partial_\tau \mathcal{P}^m = -T \partial_r (\sqrt{|G|} G^{r\alpha} \partial_\alpha x^m), \quad \mathcal{P}^m = T \sqrt{|G|} G^{\tau\beta} \partial_\beta x^m, \quad (1)$$

$$\tilde{T}_r := \mathcal{P}^m \partial_r x_m \approx 0, \quad \tilde{U} := \mathcal{P}^m \mathcal{P}_m - T^2 |\det G_{rs}| \approx 0. \quad (2)$$

We use the orthogonal gauge

$$L\tau = x^0 \equiv t, \quad G_{\tau r} = -L(\dot{\vec{x}} \cdot \partial_r \vec{x}) = 0, \quad (3)$$

$$g_{rs} := \partial_r \vec{x} \cdot \partial_s \vec{x}, \quad G_{\alpha\beta} = \begin{pmatrix} L^2(1 - \dot{\vec{x}}^2) & 0 \\ 0 & -g_{rs} \end{pmatrix}$$

with $\dot{\vec{x}} := \partial_t \vec{x} = L^{-1} \partial_\tau \vec{x}$.

The solution of constraint \tilde{U}

$$\mathcal{P}_0 = \sqrt{\vec{\mathcal{P}}^2 + T^2 |g|}, \quad g = \det(g_{rs}). \quad (4)$$

\mathcal{P}_0 becomes Hamiltonian density \mathcal{H}_0 since $\dot{\mathcal{P}}_0 = 0$.

Definition of \mathcal{P}_0 (1) and $G^{\tau\tau} = 1/L^2(1 - \dot{\vec{x}}^2)$ results in

$$\mathcal{P}_0 := TL \sqrt{|\det G|} G^{\tau\tau} = T \sqrt{\frac{|g|}{1 - \dot{\vec{x}}^2}}. \quad (5)$$

Density $\vec{\mathcal{P}}$ and its evolution are

$$\vec{\mathcal{P}} = \mathcal{P}_0 \dot{\vec{x}}, \quad \dot{\vec{\mathcal{P}}} = T^2 \partial_r \left(\frac{|g|}{\mathcal{P}_0} g^{rs} \partial_s \vec{x} \right). \quad (6)$$

PDE for \vec{x}

$$\ddot{\vec{x}} = \frac{T}{\mathcal{P}_0} \partial_r \left(\frac{T}{\mathcal{P}_0} |g| g^{rs} \partial_s \vec{x} \right). \quad (7)$$

The canonical Hamiltonian generates

$$\dot{\vec{x}} = \{H_0, \vec{x}\}, \quad \dot{\vec{\mathcal{P}}} = \{H_0, \vec{\mathcal{P}}\}, \quad \{\mathcal{P}_i(\sigma), x_j(\tilde{\sigma})\} = \delta_{ij} \delta^{(2)}(\sigma^r - \tilde{\sigma}^r)$$

with integrated density $\mathcal{H}_0 (= \mathcal{P}_0)$

$$H_0 = \int d^p \sigma \sqrt{\vec{\mathcal{P}}^2 + T^2 |g|}. \quad (8)$$

Residual symmetry of orthonormal gauge

$$\tilde{t} = t, \quad \tilde{\sigma}^r = f^r(\sigma^s). \quad (9)$$

Reduced constraints \tilde{T}_r

$$T_r := \vec{\mathcal{P}} \partial_r \vec{x} = 0 \quad \Leftrightarrow \quad \dot{\vec{x}} \partial_r \vec{x} = 0, \quad (r = 1, 2, \dots, p). \quad (10)$$

$U(1) \times U(1) \times \dots \times U(1)$ invariant p-branes

We consider p-branes evolving in $D = (2p + 1)$ -dimensional Minkowski space-time and assume that their shape is invariant under the direct product $\mathcal{U} := \prod_{a=1}^p U_a(1)$. Each of these $U(1)$ symmetries is locally isomorphic to one of the $O(2)$ subgroups of the $SO(2p, 1)$ group of rotations.

Anzats for \vec{x}

$$\vec{x}^T = (q_1 \cos \theta_1, q_1 \sin \theta_1, q_2 \cos \theta_2, q_2 \sin \theta_2, \dots, q_p \cos \theta_p, q_p \sin \theta_p), \quad (11)$$

$$q_a = q_a(t), \quad (a = 1, \dots, p); \quad \theta_r = \theta_r(\sigma^s), \quad (r, s = 1, \dots, p).$$

Vector \vec{x} lies in $2p$ -dim subspace and satisfies $\dot{\vec{x}} \partial_r \vec{x} = 0$. Anzats (11) originates from realization of a $2p$ -dimensional vector \vec{x} defined by p pairs of its "polar" coordinates

$$\vec{x}^T(t, \sigma^r) = (q_1 \cos \theta_1, q_1 \sin \theta_1, \dots, q_p \cos \theta_p, q_p \sin \theta_p) \quad (12)$$

with q_a, θ_a depending on $t, \sigma^1, \dots, \sigma^p$.

Our ansatz (11) is obtained by excluding the time dependence for all "polar" angles $\theta_a = \theta_a(\sigma^r)$ as well as the σ^r dependence for all "radial" coordinates $m_a = m_a(t)$.

At any moment t vector \vec{x}^T (11) is produced from $\vec{x}_0^T = (q_1, 0, q_2, 0, \dots, q_p, 0)$ by rotations of the diagonal subgroup $\mathcal{U} \in SO(2p)$, parametrized by the angles θ_a and rotating the planes $x_1 x_2, x_3 x_4, \dots, x_{2p-1} x_{2p}$.

World-volume metric $G_{\alpha\beta}$ becomes

$$G_{tt} = 1 - \dot{\mathbf{q}}^2, \quad \mathbf{q} := (q_1, \dots, q_p), \quad g_{rs} = \sum_{a=1}^p q_a^2 \theta_{a,r} \theta_{a,s}, \quad (13)$$

where $\theta_{s,r} := \partial_r \theta_s$ and $\dot{\mathbf{q}} \equiv \partial_t \mathbf{q}$ and yields ds^2 on Σ_{p+1}

$$ds_{p+1}^2 = (1 - \dot{\mathbf{q}}^2) dt^2 - \sum_{a=1}^p q_a^2(t) d\theta_a d\theta_a \quad (14)$$

independent of σ^r .

Change of σ^r by new parameters $\theta_a(\sigma^r)$ makes metric independent of σ^r with Killing vectors $\frac{\partial}{\partial \theta_a}$ on Σ_p .

It shows that Σ_p has zero curvature and is isomorphic to a flat p-dimensional torus $S^1 \times S^1 \times \dots \times S^1$ at any moment.

Canonical components $\pi_a = \frac{\partial \mathcal{L}}{\partial \dot{q}_a} = \vec{\mathcal{P}} \frac{\partial \vec{x}}{\partial \dot{q}_a}$ or $\boldsymbol{\pi} := (\pi_1, \dots, \pi_p)$ for \mathbf{q} are

$$\boldsymbol{\pi} = \mathcal{P}_0 \dot{\mathbf{q}}, \quad \mathcal{P}_0 = T \sqrt{\frac{|g|}{1 - \dot{\mathbf{q}}^2}}, \quad g = \det\left(\sum_{a=1}^p q_a^2 \theta_{a,r} \theta_{a,s}\right) \quad (15)$$

and $\vec{x}^2 = \mathbf{q}^2$, $\dot{\vec{x}}^2 = \dot{\mathbf{q}}^2$.

Hamiltonian density in $(\mathbf{q}, \boldsymbol{\pi})$ phase space

$$\mathcal{H}_0 = \mathcal{P}_0 = \sqrt{\boldsymbol{\pi}^2 + T^2|g|}, \quad \dot{\mathcal{P}}_0 = 0. \quad (16)$$

Hamiltonian equations

$$\dot{\mathbf{q}} = \{H_0, \mathbf{q}\} = \frac{1}{\mathcal{P}_0} \boldsymbol{\pi}, \quad \dot{\boldsymbol{\pi}} = \{H_0, \boldsymbol{\pi}\}. \quad (17)$$

Canonical PB's and Hamiltonian

$$\{\pi_a, q_b\} = \delta_{ab}, \quad H_0 = \int d^p \sigma \sqrt{\boldsymbol{\pi}^2 + T^2|g|}. \quad (18)$$

Equations of \mathcal{U} invariant p-branes

To simplify equations of motion we simplify Ansatz by fixing gauge for residual symmetry (9): $\theta_a = \delta_{ar} \sigma^r$

$$\theta_1(\sigma^r) = \sigma^1, \quad \theta_2(\sigma^r) = \sigma^2, \dots, \theta_p(\sigma^r) = \sigma^p. \quad (19)$$

Then Ansatz and g_{rs} are expressed

$$\vec{x}^T(t) = (q_1 \cos \sigma^1, q_1 \sin \sigma^1, \dots, q_p \cos \sigma^p, q_p \sin \sigma^p), \quad (20)$$

$$g_{rs}(t) = q_r^2(t) \delta_{rs}, \quad g = (q_1 q_2 \dots q_p)^2 \quad (21)$$

with diagonalized metric $g_{rs}(t)$ depending on t .

In gauge (19) interval and g^{rs} on Σ_p are

$$ds_p^2 = \sum_{r=1}^p q_r^2(t) (d\sigma^r)^2, \quad g^{rs}(t) = \frac{1}{q_r^2} \delta_{rs}. \quad (22)$$

This gauge clarifies sense of coordinates $\mathbf{q}(t) = (q_1, q_2, \dots, q_p)$ as time dependent radii $\mathbf{R}(t) = (R_1, R_2, \dots, R_p)$ of flat hypertorus Σ_p .

Hamiltonian density \mathcal{H}_0 becomes independent of σ^r

$$\mathcal{H}_0 = \mathcal{P}_0 = \sqrt{\pi^2 + T^2 \prod_{r=1}^p q_r^2} = C, \quad \dot{\mathcal{P}}_0 = 0, \quad \frac{\partial}{\partial \sigma^r} \mathcal{P}_0 = 0. \quad (23)$$

This property yields condition for the initial data

$$\mathcal{P}_0 = C \rightarrow T \sqrt{\frac{|g|}{1 - \dot{\mathbf{q}}^2}} \equiv T \sqrt{\frac{(q_1 q_2 \dots q_p)^2}{1 - \dot{\mathbf{q}}^2}} = C. \quad (24)$$

Eqs. (6) for \vec{x} are simplified

$$\ddot{\vec{x}} - \left(\frac{T}{C}\right)^2 g g^{rs} \partial_{rs} \vec{x} = 0. \quad (25)$$

Taking into account

$$g g^{rs} = \frac{\delta_{rs}}{q_r^2} \prod_{t=1}^p q_t^2, \quad \partial^r \partial_r \vec{x} = -\vec{x} \quad (26)$$

we present Eqs. (25) in terms of \mathbf{q}

$$\ddot{q}_r + \left(\frac{T}{C}\right)^2 (q_1 \dots q_{r-1} q_{r+1} \dots q_p)^2 q_r = 0, \quad r = (1, 2, \dots, p). \quad (27)$$

Multiplication (27) by q_r results in the first integral

$$\dot{\mathbf{q}}^2 + \left(\frac{T}{C}\right)^2 (q_1 q_2 \dots q_p)^2 = c \quad (28)$$

which coincides with initial data (24) if $c = 1$. Eqs. (27) are presented as

$$C\ddot{\mathbf{q}} = -\frac{\partial V}{\partial \mathbf{q}}, \quad (29)$$

where elastic energy density $V(\mathbf{q})$ turns out to be proportional to g

$$V(\mathbf{q}) := \frac{T^2}{2C} g \equiv \frac{T^2}{2C} (q_1 \dots q_p)^2. \quad (30)$$

\mathcal{U} invariant p-branes and p-dimensional anharmonic oscillators

General equations of elastic non relativistic media with mass density ρ

$$\rho \ddot{u}_i = \frac{\partial \sigma_{ik}}{\partial x_k}. \quad (31)$$

We observe that Eqs. (29) have form of relativistic generalization (31)

$$C \ddot{q}_r = -\frac{T^2}{2C} \delta_{rs} \frac{\partial g}{\partial q_s} \quad (32)$$

with stress tensor σ_{rs}

$$\sigma_{rs} := -p \delta_{rs}, \quad p := \frac{T^2}{2C} g \equiv \frac{T^2}{2C} \prod_{s=1}^p q_s^2, \quad r = (1, 2, \dots, p). \quad (33)$$

Eqs. (33) shows that p is isotropic pressure per unit area of its p-brane hypersurface, and C is a relativistic generalization of mass density ρ .

Pressure p is created by forces F_r

$$F_r(t) := -\frac{\partial V}{\partial q_r} \equiv -\frac{T^2}{C} (q_1 \dots q_{r-1} q_{r+1} \dots q_p)^2 q_r \quad (34)$$

associated with p-brane potential V (30).

It is instructive to note that the discussed equations are generated by Hamiltonian H free from the square root present in H_0 (18).

Constant C can be used to write square root free Hamiltonian density

$$\mathcal{H} = \frac{\mathcal{H}_0^2}{2C} = C/2$$

and Hamiltonian H

$$H := \int d^p \sigma \mathcal{H}, \quad \mathcal{H} = \frac{1}{2C} (\pi^2 + T^2 \prod_{s=1}^p q_s^2), \quad (35)$$

with standard PB's

$$\{\pi_a, q_b\} = \delta_{ab}, \quad \{q_a, q_b\} = 0, \quad \{\pi_a, \pi_b\} = 0.$$

Hamiltonian H describes p -dimensional anharmonic oscillators without quadratic terms, and reproduces Eqs. (27).

The set of Hamiltonians (35) contains quartic potential energy for $p=2$ or the higher degree monomials in components of \mathbf{q} for $p > 2$ respectively.

Cyclic "frequency" ω_r of a coordinate q_r is proportional to products of remaining coordinates

$$\omega_r(t) = \frac{T}{c} |q_1 \dots q_{r-1} q_{r+1} \dots q_p|, \quad r = (1, 2, \dots, p). \quad (36)$$

These frequencies ω_r in Eqs. (27) can not be infinitely large because of the initial data (28) with $c = 1$

$$\sqrt{1 - \dot{\mathbf{q}}^2} = \frac{T}{C} |q_1 q_2 \dots q_p|, \quad (37)$$

which shows that

$$0 \leq |\dot{\mathbf{q}}| \leq 1, \quad 0 \leq \frac{T}{C} |q_1 q_2 \dots q_p| \leq 1 \quad (38)$$

i.e. velocity $|\dot{\mathbf{q}}|$ grows when hypervolume $\sim |q_1 q_2 \dots q_p|$ diminishes and achieves velocity of light.

If $T = 0$ nonlinear system (27) reduces to equations

$$T = 0 : \Rightarrow \ddot{\mathbf{q}} = 0, \quad |\dot{\mathbf{q}}| = 1, \quad (39)$$

similar to equations of free massless particles in effective p -dimensional space. In general case the system (27) is rather complicate because of monomial entanglement of coordinates q_r in interaction potential V (35). However, there is a special solvable case that we discuss below.

Elliptic and hyperelliptic solutions

Degenerate case is characterized by coincidence $q_1 = q_2 = \dots = q_p \equiv q$.
System (27) reduces to nonlinear diff. eqn.

$$\ddot{q} + \left(\frac{T}{C}\right)^2 q^{(2p-1)} = 0 \quad (40)$$

equivalent to initial data constraint (37) for $q(t)$

$$p\dot{q}^2 + \left(\frac{T}{C}\right)^2 q^{2p} = 1. \quad (41)$$

After change of q by $y = \Omega^{\frac{1}{p}} \sqrt{p} q$, and introduction of frequency $\Omega := \frac{T}{C} p^{-\frac{p}{2}}$, Eq. (41) takes form

$$\left(\frac{dy}{d\tilde{t}}\right)^2 = \frac{1}{2}(1 - y^p)(1 + y^p), \quad (42)$$

with new variable $\tilde{t} := \sqrt{2}\Omega^{\frac{1}{p}} t$.

In membrane case ($p = 2$) Eq. (42) coincides with eqn. defining Jacobi elliptic cosine $cn(x; k)$

$$\left(\frac{dy}{dx}\right)^2 = (1 - y^2)(1 - k^2 + k^2 y^2), \quad (43)$$

if elliptic modulus $k = \frac{1}{\sqrt{2}}$.

Thus, $y(t) = cn(\sqrt{2\omega}t; \frac{1}{\sqrt{2}})$ with $2\omega = T/C$.

Using relation $q \equiv y / \sqrt{2\omega}$ we obtain elliptic cosine solution

$$q(t) = \frac{1}{\sqrt{2\omega}} cn(\sqrt{2\omega}(t + t_0); \frac{1}{\sqrt{2}}) \equiv \sqrt{\frac{C}{T}} cn\left(\sqrt{\frac{T}{C}}(t + t_0); \frac{1}{\sqrt{2}}\right). \quad (44)$$

If initial data are $\dot{q}(t_0) > 0$ then solution (44) describes expanding torus which at some point reaches the maximal size $q_{max} = \sqrt{\frac{C}{T}}$ and then shrinks to a point after a finite time $\mathbf{K}(1/\sqrt{2}) \sqrt{\frac{C}{T}}$ (where $\mathbf{K}(1/\sqrt{2}) = 1,8451$ is quarter period of elliptic cosine).

Equation of surface $\Sigma_2(t)$ of contracting torus (44) in $D = 5$ is

$$x_1^2 + x_2^2 + x_3^2 + x_4^2 = 4 \frac{C}{T} \operatorname{cn} \left(\sqrt{\frac{T}{C}} (t + t_0), \frac{1}{\sqrt{2}} \right)^2, \quad x_1 x_4 = x_2 x_3.$$

For $p > 2$ integration of Eq. (42) defines implicit dependence of q on time

$$\tilde{t} = \pm \sqrt{2} \int \frac{dy}{\sqrt{1 - y^{2p}}} + \text{const.} \quad (45)$$

The integral (45) is an hyperelliptic integral, thus general solution of Eq. (41) is expressed in terms of hyperelliptic functions.

After change of variable $z = y^{2p}$ hyperelliptic solution takes form

$$\tilde{t} - \tilde{t}_0 = \pm \frac{1}{\sqrt{2p}} \int_0^z z^{\frac{1}{2p}} dz z^{(\frac{1}{2p}-1)} \cdot (1-z)^{-\frac{1}{2}}. \quad (46)$$

Using (46) one can find the time of contraction $\Delta \tilde{t}_c$ of p-torus from the maximal value of the radii $q_{max} = (\frac{C}{T})^{\frac{1}{p}}$ to $q_{min} = 0$

$$\Delta \tilde{t}_c = \frac{1}{\sqrt{2p}} \int_0^1 dz z^{(\frac{1}{2p}-1)} \cdot (1-z)^{\frac{1}{2}-1} = \frac{1}{\sqrt{2p}} B\left(\frac{1}{2p}, \frac{1}{2}\right), \quad (47)$$

where $B(\frac{1}{2p}, \sqrt{2})$ is the Euler beta function $B(\alpha, \beta)$.

Coming back to the real time t we obtain

$$\Delta t_c \equiv \frac{1}{\sqrt{2}} \Omega^{-\frac{1}{p}} \Delta \tilde{t}_c = \frac{1}{2\sqrt{p}} \left(\frac{2E}{T}\right)^{\frac{1}{p}} B\left(\frac{1}{2p}, \frac{1}{2}\right).$$

So, the case of degenerate p-torus with coinciding radii q turns out to be integrable and reveals connection of p-brane equations with (hyper)elliptic curves and Euler beta function.

Summary

Exact solvability of brane equations is studied, and a new $U(1) \times U(1) \times \dots \times U(1)$ invariant ansatz for the solution of p-brane equations in $D = (2p + 1)$ -dimensional Minkowski space is proposed.

The reduction of the p-brane Hamiltonian to the Hamiltonian of p-dimensional relativistic anharmonic oscillator with the monomial potential of the degree equal to $2p$ is revealed.

It is shown that the case of degenerate p-torus with equal radii is integrable and that the p-brane solutions are expressed in terms of elliptic ($p = 2$) or hyperelliptic ($p > 2$) functions.



P. K. Townsend, *The eleven-dimensional supermembrane revisited*, Phys. Lett. B350 (1995) 184; E. Witten, *String Theory Dynamics In Various Dimensions*, Nucl. Phys. B443 (1995) 85; T. Banks, W. Fishler, S.H. Shenker, L. Susskind, *M theory as a Matrix Mode: A conjecture* Phys. Rev. D55(8):5112; M. J. Duff, *The world in Eleven Dimensions: Supergravity, Supermembranes and M-theory* (IOP, Bristol 1999).



C. Rebbi, *Dual models and relativistic strings*, Phys. Rep. 12 (1974) 1.



R. W. Tucker, *Extended Particles and the Exterior Calculus*, Lectures given at the Rutherford Laboratory, Feb 1976.



J. Hoppe, MIT PhD Thesis, 1982, and in Proc. Int. Workshop on Constraints Theory and Relativistic Dynamics. G. Longhi, L. Lusanna (eds), Singapore: World Scientific 1987.




E. Bergshoeff, E. Sezgin, P.K. Townsend, Phys. Lett. B189 (1987) 75.



M. Duff, P. Howe, T. Inami, K. Stelle, Phys. Lett. B191 (1987) 70.



E. Floratos, J. Illipoulos, Phys. Lett. B201 (1988) 237.

-  B. de Witt, J. Hoppe, G. Nicolai, Nucl. Phys. B305 [FS23] (1988) 545.
-  A.A. Zheltukhin, Sov. J. Nucl. Phys. 48 (1988) 375.
-  B. de Witt, M. Lusher, G. Nicolai, Nucl. Phys. B320 (1989) 135.
-  I.A. Bandos and A.A. Zheltukhin, Fortsch. Phys. 41 (1993) 619.
-  M. Bordemann, J. Hoppe, Phys. Lett. B317 (1993) 315 ; ibid. B325 (1994) 359.
-  J. Polchinski, Phys. Rev. Lett. 75 (1995) 4729.
-  D.V. Uvarov and A.A. Zheltukhin, Phys. Lett. B545 (2002) 183.
-  J. Arnlind, J. Hoppe, S. Theisen, Phys. Lett. B 599 (2004) 118.
-  J. Hoppe, Compl. Anal. Oper. Theory 3 (2009) 419.
-  M. Trzetrzelewski and A.A. Zheltukhin, Phys. Lett. B679 (2009) 523.
-  A.A. Zheltukhin and M. Trzetrzelewski, J. Math. Phys. 51 (2010) 062303.

Outline

P-brane dynamics for any (D, p)

$U(1) \times U(1) \times \dots \times U(1)$ invariant p-branes

Equations of \mathcal{U} invariant p-branes

\mathcal{U} invariant p-branes and p-dimensional anharmonic oscillators

Elliptic and hyperelliptic solutions

Summary

Bibliography



L.D. Landau and E.M. Lifshits, *Theory of Elasticity* Moscow, "Science", 1987.