# Cubic Interactions of Symmetric Higher-Spin Gauge Fields in $A d S_{d}$ 

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## Higher-Spin interactions

Higher spins: $s>2$
Higher-spin interactions
A.Bengtsson, I.Bengtsson, Brink (1983), Berends, Burgers, van Dam (1984)

$$
\begin{gathered}
S=S^{2}+S^{3}+\ldots \\
S^{3}=\sum_{p, q, r}\left(D^{p} \varphi\right)\left(D^{q} \varphi\right)\left(D^{r} \varphi\right) \rho^{p+q+r+\frac{1}{2} d-3}
\end{gathered}
$$

$s$ derivatives in interactions.
String: $\quad \rho \sim \sqrt{\alpha^{\prime}}$
HS Gauge Theories $(m=0): \quad$ Fradkin, M.V. (1987)

$$
A d S_{4}:\left(X^{0}\right)^{2}+\left(X^{4}\right)^{2}-\left(X^{1}\right)^{2}-\left(X^{2}\right)^{2}-\left(X^{3}\right)^{2}=\rho^{2}, \quad \rho=\lambda^{-1}
$$

The $\rho \rightarrow \infty$ limit is ill-defined at the interaction level
Cubic vertices in Minkowski space of any dimension Metsaev (2005)

$$
s_{1}+s_{2}-s_{3} \leq 2 N \leq s_{1}+s_{2}+s_{3}
$$

Manvelyan, Mkrtchyan, Ruhl; Sagnotti, Taronna; Fotopoulos, Tsulaya; (2010)

## Cartan gravity in the $A d S_{d}$ covariant formalism

$w^{A B}=-w^{B A}=d x^{\underline{n}} w_{\underline{n}}^{A B}$ connection of $A d S_{d}$
$o(d-1,2)$-curvature

$$
\begin{gathered}
r^{A B}=d w^{A B}+w^{A C} \wedge w_{C}^{B} \\
w=w^{A B} t_{A B}=\omega^{L a b} L_{a b}+\lambda e^{a} P_{a}
\end{gathered}
$$

Provided that $e^{a}$ is nondegenerate

$$
r^{A B}(w)=0
$$

implies that $\omega^{L a b}$ and $e^{a}$ describe $A d S_{d} . \lambda^{-1}$ is radius of $A d S_{d}$.
Covariant definitions: compensator field $V^{A}(x)$ normalized to $V^{A} V_{A}=\lambda^{-2}$. Lorentz algebra is the stability subalgebra of $V^{A}$. Convenient choice is the standard gauge $V^{A}=\lambda^{-1} \delta_{d}^{A}$. It leads to standard formulae from covariant definitions

$$
E^{A}=D V^{A} \equiv d V^{A}+w^{A B} V_{B}, \quad \omega^{L A B}=w^{A B}-\lambda^{2}\left(E^{A} V^{B}-E^{B} V^{A}\right) .
$$

## Action

$$
S=\frac{(-1)^{d+1}}{4 \lambda^{2} \kappa^{d-2}} \int_{M^{d}} G_{A_{1} A_{2} A_{3} A_{4}} \wedge r^{A_{1} A_{2}} \wedge r^{A_{3} A_{4}}
$$

where

$$
\begin{gathered}
G^{A_{1} \ldots A_{q}}=\epsilon^{A_{0} \ldots A_{d} V_{A_{0}} E_{A_{q+1}} \wedge \ldots \wedge E_{A_{d}}} \\
D G^{A_{1} \ldots A_{q}} \simeq(-1)^{q} q \lambda^{2} V^{\left[A_{1}\right.} G^{\left.A_{2} \ldots A_{q}\right]}, \quad t^{A}:=D E^{A} \equiv r^{A B} V_{B}=0 \\
G^{A_{1} \ldots A_{q}} \wedge E^{C}=\frac{q}{d+1-q} G^{\left[A_{1} \ldots A_{q-1}\right.}\left(\eta^{\left.A_{q}\right] C}-\lambda^{2} V^{C} V^{\left.A_{q}\right]}\right) .
\end{gathered}
$$

## Generalized Einstein equations

$$
\left(G_{A_{1} A_{2} A_{3}}-\frac{(d-4)}{4 \lambda^{2}} G_{A_{1} A_{2} A_{3} A_{4} A_{5}} \wedge r^{A_{4} A_{5}}\right) \wedge r^{A_{1} A_{2}}=0
$$

## Symmetric higher-spin gauge fields

A spin $s \geq 2$ massless field can be described (2001) by a one-form
$d x^{\underline{n}} \omega_{\underline{n}} A_{1} \ldots A_{s-1}, B_{1} \ldots B_{s-1}$ carrying the irreducible representation of $o(d-1,2)$ described by the traceless two-row rectangular Young diagram of length $s-1$

$$
\omega^{\left(A_{1} \ldots A_{s-1}, A_{s}\right) B_{2} \ldots B_{s-1}}=0, \quad \omega^{A_{1} \ldots A_{s-3} C}{ }_{C},{ }^{B_{1} \ldots B_{s-1}}=0 .
$$

Linearized HS curvature $R_{1}$ has simple form

$$
\begin{aligned}
& R_{1}^{A_{1} \ldots A_{s-1}, B_{1} \ldots B_{s-1}}=D_{0}\left(\omega^{A_{1} \ldots A_{s-1}, B_{1} \ldots B_{s-1}}\right)=d \omega_{1}^{A_{1} \ldots A_{s-1}, B_{1} \ldots B_{s-1}} \\
& \quad+(s-1)\left(w_{0}^{\left(A_{1}\right.} C \wedge \omega_{1}^{\left.C A_{2} \ldots A_{s-1}\right), B_{1} \ldots B_{s-1}}+w_{0}^{\left(B_{1}\right.} C \wedge \omega_{1}^{\left.A_{1} \ldots A_{s-1}, C B_{2} \ldots B_{s-1}\right)}\right),
\end{aligned}
$$

$A d S_{d}$ background gauge field $w_{0}^{A B}$ satisfies the zero curvature condition $D_{0}^{2}=0$.
Bianchi identities: $D_{0} R_{1}=0$.

Lorentz covariant irreducible fields $d x^{\underline{n}} \omega_{\underline{\underline{n}}} a_{1} \ldots a_{s-1}, b_{1} \ldots b_{t}$ identify with those components of $d x^{\underline{n}} \omega_{\underline{\underline{n}}} A_{1} \ldots A_{s-1}, B_{1} \ldots B_{s-1}$, that are parallel to $V^{A}$ in some $s-t-1$ indices and transversal in the rest $t$ indices. The dynamical frame-like and auxiliary Lorentz-like fields are those with $t=0$ and $t=1$

$$
\begin{gathered}
e^{A_{1} \ldots A_{s-1}}=\omega^{A_{1} \ldots A_{s-1}, B_{1} \ldots B_{s-1}} V_{B_{1}} \ldots V_{B_{s-1}} \\
\omega^{A_{1} \ldots A_{s-1}, C}=\Pi_{V} \omega^{A_{1} \ldots A_{s-1}, C B_{2} \ldots B_{s-1}} V_{B_{2}} \ldots V_{B_{s-1}}
\end{gathered}
$$

The HS gauge fields with $t>1$ are called extra fields.
The free action that describes properly HS gauge fields is

$$
\begin{aligned}
& S_{2}=\frac{1}{2} \int_{M^{d}} \sum_{p=0}^{s-2} a(s, p) V_{C_{1}} \ldots V_{C_{2(s-2-p)}} G_{A_{1} A_{2} A_{3} A_{4}} \wedge \\
& R_{1}^{A_{1} B_{1} \ldots B_{s-2}},_{2} C_{1} \ldots C_{s-2-p} D_{1} \ldots D_{p} \wedge R_{1}^{A_{3}} B_{1} \ldots B_{s-2},{ }_{4} C_{s-1-p \ldots C_{2(s-2-p)} D_{1} \ldots D_{p}}, \\
& \quad a(s, p)=b(s) \lambda^{-2(p+1)} \frac{(d-5+2(s-p-2))!!(s-p-1)}{(s-p-2)!},
\end{aligned}
$$

The coefficients are chosen so that the variation of the action over all extra fields is identically zero: at the linearized level, only the frame-like and Lorentz-like fields contribute to the action

## First On-Shell Theorem

$$
R_{1}^{A_{1} \ldots A_{s-1}, B_{1} \ldots B_{s-1}} \sim E_{0 A_{s}} \wedge E_{0 B_{s}} C^{A_{1} \ldots A_{s}, B_{1} \ldots B_{s}}
$$

Generalized Weyl tensors $C^{A_{1} \ldots A_{s}, B_{1} \ldots B_{s}}$ parametrize those components of the curvatures that may remain nonzero when the field equations and constraints on extra fields are imposed. $C^{A_{1} \ldots A_{s}, B_{1} \ldots B_{s}}$ is described by a traceless $V^{A}$-transversal two-row rectangular Young diagram of length s $C^{\left(A_{1} \ldots A_{s}, A_{s+1}\right) B_{2} \ldots B_{s}}=0, C^{A_{1} \ldots A_{s-2} C D, B_{1} \ldots B_{s}} \eta_{C D}=0, C^{A_{1} \ldots A_{s-1} C, B_{1} \ldots B_{s}} V_{C}=0$

## Consequences:

$$
R_{1 A \ldots} V^{A} \sim 0, \quad R_{1 A \ldots} \wedge E^{A} \sim 0, \quad G^{\left[A_{1} \ldots A_{q}\right.} \wedge R_{1}^{\left.A_{q+1}\right]} \ldots \sim 0
$$

Dual curvature ( $d-2$ )-form

$$
R_{A_{1} \ldots A_{s-1}, B_{1} \ldots B_{s-1}}^{\prime}=G_{A_{s-1} B_{s-1}}{ }^{F G} R_{F A_{1} \ldots A_{s-2}, G B_{1} \ldots B_{s-2}} .
$$

Important property: any $d$-form $F\left(R^{\prime}, R\right)$ bilinear in $R$ and $R^{\prime}$ is symmetric

$$
F\left(R^{\prime}, R\right) \sim F\left(R, R^{\prime}\right)
$$

## Cubic interactions

Current $\Omega^{\Phi}$ defined via

$$
\delta S^{3}=\int_{M^{d}} \delta \omega_{\Phi} \wedge \Omega^{\Phi}(\omega), \quad \Omega^{\Phi}(\omega)=\frac{\delta S^{3}}{\delta \omega_{\Phi}}
$$

respects gauge invariance under $\delta \omega_{\Phi}=D_{0} \omega_{\Phi}$ if it obeys the conservation condition

$$
D_{0} \Omega^{\Phi} \sim 0
$$

in the case with several gauge fields the integrability condition should be respected

$$
\frac{\delta \Omega^{\wedge}}{\delta \omega_{\Phi}}=(-1)^{p_{\Phi} p_{\wedge}} \frac{\delta \Omega^{\Phi}}{\delta \omega_{\Lambda}} .
$$

It is this condition that makes difficult to introduce Noether current interactions for a system of gauge fields of different types

## Different types of vertices

## Abelian vertices

$$
\begin{gathered}
S^{3}=\int_{M^{d}} V^{\Phi_{1} \Phi_{2} \Phi_{3}} \wedge R_{1 \Phi_{1}} \wedge R_{2 \Phi_{2}} \wedge R_{3 \Phi_{3}}, \quad R_{1 \Phi}=D_{0} \omega_{\Phi} \\
S^{3}=\int_{M^{d}} U C_{s_{1}} C_{s_{2}} C_{s_{3}}
\end{gathered}
$$

$C$ : generalized Weyl tensors which parametrize on-shell nontrivial components of the linearized curvatures $R_{1 \Phi}$

Current vertices

$$
S^{3}=\int_{M^{d}} \omega_{\Phi} \wedge \tilde{\Omega}^{\Phi}(C), \quad D_{0} \tilde{\Omega}^{\Phi}(C) \sim 0
$$

for a $p$-form $\omega_{\Phi}$ and a $D_{0}$ on shell-closed $(d-p)$-form $\widetilde{\Omega}^{\Phi}(C)(d-p)$ bilinear in the HS Weyl zero-forms

## Non-Abelian curvatures

are typical for the actions constructed from bilinears of some non-Abelian curvatures $R=R_{1}+\omega^{2}$ since the cubic part of the lagrangian $L=\frac{1}{2} R R$ has the structure $R_{1} \omega^{2}$.

For the curvature

$$
R^{\alpha}=d \omega^{\alpha}+f_{\beta \gamma}^{\alpha} \omega^{\beta} \omega^{\gamma}
$$

$f_{\beta \gamma}^{\alpha}$ contribute linearly to the action while the on-shell analysis involves only Abelian ( free) gauge transformation law.

For the cubic order analysis it does not matter whether or not $f_{\beta \gamma}^{\alpha}$ satisfy the Jacobi identities.

What does matter is the symmetry property of the coefficients: the existence of such an metric $g_{\alpha \beta}$ that the structure coefficients $f_{\alpha \beta \gamma}=$ $g_{\alpha \rho} f_{\beta \gamma}^{\rho}$ are totally (graded) antisymmetric

$$
f_{\alpha \beta \gamma}=-f_{\alpha \gamma \beta}=-f_{\beta \alpha \gamma}
$$

Chern-Simons vertices
$\omega^{3}$-type vertices we call Chern-Simons vertices.

Except for the case of true Chern-Simons vertices where $\omega^{3}$ is a $d$ form, all other Chern-Simons vertices in $A d S_{d}$ are equivalent up to tota derivatives to some curvature-dependent vertices

Being true in $A d S$, this property may not be true in Minkowski geometry where nontrivial Chern-Simons vertices can exist.

## Minkowski versus $A d S$

The situation in $A d S_{d}$ geometry is different because of presence of the dimensionfull parameter $\rho=\lambda^{-1}$.
Let $V_{A d S}$ be a deformation of a Minkowski vertex $V_{M}$. It may happen that it admits a representation

$$
V_{A d S} \sim \lambda^{-2}\left(d U_{A d S}+\tilde{V}_{A d S}\right)
$$

with $U$ and $\tilde{V}_{A d S}$ containing, respectively, $N+1$ and $N+2$ derivatives of the dynamical fields. This implies that $V_{A d S}$ is equivalent to $\tilde{V}_{A d S}$ for al $\lambda \neq 0$.
$A d S_{d}$ vertices that contain different numbers of derivatives can belong to the same equivalence class

## Vertex tri-complex

## Consider a differential form

$F\left(\omega, R_{1} \mid V, E\right)=G^{A_{1} \ldots A_{q}} V^{C_{1}} \ldots V^{C_{p}} F_{\left[A_{1} \ldots A_{q}\right], C_{1} \ldots C_{p}}\left(\omega, R_{1}\right)=G^{A_{1} \ldots A_{q}} F_{\left[A_{1} \ldots A_{q}\right]}(\omega, I$
Direct computation gives $d F=Q F$

$$
\begin{aligned}
& Q=Q^{t o p}+\lambda^{2} Q^{s u b}+Q^{c u r}, \\
& Q^{t o p} F=(-1)^{d-q} \frac{q}{d+1-q} G^{A_{1} \ldots A_{q-1}} \frac{\partial}{\partial V_{A_{q}}} F_{A_{1} \ldots A_{q}}\left(\omega, R_{1} \mid V\right), \\
& Q^{\text {sub }} F=(-1)^{d} \frac{q}{d+1-q} G^{A_{2} \ldots A_{q}} \wedge V^{A_{1}}\left(d+1-q+V^{E} \frac{\partial}{\partial V^{E}}\right) F_{A_{1} \ldots A_{q}}\left(\omega, R_{1} \mid V\right) \\
& Q^{c u r} F=(-1)^{d-q} R_{1}^{\alpha} \frac{\partial}{\partial \omega^{\alpha}} F\left(\omega, R_{1} \mid V\right) . \\
& \left(Q^{t o p}\right)^{2}=0, \quad\left(Q^{\text {sub }}\right)^{2}=0, \quad\left(Q^{\text {cur }}\right)^{2}=0, \\
& \left\{Q^{\text {top }}, Q^{\text {sub }}\right\}=0, \quad\left\{Q^{\text {top }}, Q^{\text {cur }}\right\}=0, \quad\left\{Q^{\text {cur }}, Q^{\text {sub }}\right\}=0 .
\end{aligned}
$$

$Q^{t o p}, Q^{\text {sub }}$ and $Q^{\text {cur }}$ form tri-complex.

## Vertex cohomology

Let $F\left(\omega, R_{1}\right)$ be a $d$-form. Consider the action

$$
S=\int_{M^{d}} F\left(\omega, R_{1}\right) .
$$

Using convention $\varepsilon^{\alpha} \frac{\partial}{\partial \omega^{\alpha}}\left(R_{1}\right)=0$ gauge variation is

$$
\delta \int_{M^{d}} F\left(\omega, R_{1}\right)=\int_{M^{d}} \varepsilon^{\alpha} \frac{\partial}{\partial \omega^{\alpha}}\left(Q F\left(\omega, R_{1}\right)\right),
$$

Gauge invariance requires

$$
Q F\left(\omega, R_{1}\right) \sim G\left(R_{1}\right) .
$$

Gauge invariant vertices: $H^{d}(Q)$.

## Flat limit

$$
Q=F^{f l}+\lambda^{2} Q^{s u b}, \quad Q^{f l}=Q^{t o p}+Q^{c u r}
$$

$\lambda^{2}$ iin front of $Q^{s u b}$ signals that $Q^{s u b} F$ contains at least two less space-time derivatives than $Q^{t o p} F$ and $Q^{c u r} F$. Since the term with $Q^{s u b}$ disappears in the flat limit, vertices in Minkowski space are controlled by $Q^{f l}$.

Gauge invariant vertices in Minkowski space: $H^{d}\left(Q^{f l}\right)$.

Vertex $F$ is pure iff

$$
F \in H^{d}\left(Q^{f l}\right), \quad Q^{s u b} F=0 \quad \Rightarrow Q F=0
$$

In terms of HS connections, pure vertices have the same form in Minkows and $A d S_{d}$.

## Spin two

Two $Q$-closed vertices

$$
\begin{gathered}
B_{1}=G^{A_{1} \ldots A_{5}} V^{C} R_{A_{1}, A_{2}} R_{A_{3}, A_{4}} \omega_{A_{5}, C} \\
B_{2}=G^{A_{1} \ldots A_{4}} R_{A_{1}, A_{2} \omega_{A_{3}}{ }^{B} \omega_{A_{4}, B}}
\end{gathered}
$$

$B_{1}$ can be represented in the form

$$
\begin{gathered}
B_{1}=Q^{s u b} U, \quad U=-\frac{1}{2}(-1)^{d} G^{A_{1} \ldots A_{6}} R_{A_{1}, A_{2}} R_{A_{3}, A_{4}} \omega_{A_{5}, A_{6}} \\
Q^{t o p} U=0, \quad Q^{c u r} U=-\frac{1}{2} G^{A_{1} \ldots A_{6}} R_{A_{1}, A_{2}} R_{A_{3}, A_{4}} R_{A_{5}, A_{6}}
\end{gathered}
$$

$B_{1}$ is $Q^{f l}$-closed. Since $B_{1}$ is $Q^{s u b}-e x a c t$, it is pure hence being gauge invariant both in Minkowski space and $\operatorname{AdS} S_{d}$.
$B_{2}$ is also pure. Both $B_{1}$ and $B_{2}$ contain up to four space-time derivatives of the vielbein: some combination of $B_{1}$ and $B_{2}$ should be $Q^{f l}$ exact.

$$
\left.(d-4) B_{1}-3 B_{2} \sim(-1)^{d} Q^{f l}\left(E_{2}-(d-4) E_{1}\right)\right)
$$

$$
E_{1}=G^{A_{1} \ldots A_{5}} V^{C} R_{A_{1}, A_{2}} \omega_{A_{3}, A_{4}} \omega_{A_{5}, C}, \quad E_{2}=G^{A_{1} \ldots A_{4}} \omega_{A_{1}}{ }^{B} R_{A_{2}, A_{3}} \omega_{A_{4}, B}
$$

However, being equivalent in Minkowski space, $B_{1}$ and $B_{2}$ are not equivalent in $A d S_{d}$. Indeed,

$$
(d-4) B_{1}-3 B_{2} \sim(-1)^{d}\left(Q-\lambda^{2} Q^{s u b}\right)\left(E_{2}-(d-4) E_{1}\right),
$$

$A d S$ deformation of $(d-4) B_{1}-3 B_{2}$, that was trivial in Minkowski case gives rise to the vertex

$$
V_{3}=\frac{1}{2}(-1)^{d} Q^{s u b}\left(E_{2}-(d-4) E_{1}\right) .
$$

$V_{3}$ is $Q$-closed since $B_{1}$ and $B_{2}$ are. Being $Q^{s u b}$-closed, $V_{3}$ is pure. Its explicit form is
$V_{3}=(d-3) G^{A_{1} \ldots A_{4}} V^{C} V^{C} R_{A_{1} A_{2}} \omega_{A_{3} C} \omega_{A_{4} C}+G^{A_{1} A_{2} A_{3}} V^{C}\left(\omega_{C}{ }^{D} \omega_{A_{1} A_{2}} \omega_{A_{3} D}+\omega_{A_{1}}{ }^{D} \omega\right.$
$V_{3}$ contains two derivatives, reproducing cubic part of the Einstein action with the cosmological term.

Spin two example illustrates the general phenomenon that $A d S$ deformation of a higher-derivative vertex trivial in flat space may become nontrivial in $A d S_{d}$.

## Spin three

## Two pure vertices

$$
\begin{aligned}
F^{3} & =G^{A_{1} A_{2} A_{3}} V^{C(3)} \operatorname{tr}\left(\omega _ { A _ { 1 } B , A _ { 2 } E } \left(-2\left\{\omega_{A_{3}}{ }^{B}, C D, \omega^{E D}, C(2)\right\}-\left\{\omega_{A_{3} D, C^{B}}, \omega^{E D},\right.\right.\right. \\
& \left.+\omega_{A_{1} B, F C}\left(2\left\{\omega_{A_{2}}{ }^{B}, C G, \omega_{A_{3}}{ }^{F},{ }^{G} C\right\}+\frac{4}{3}\left\{\omega_{A_{2} G,}{ }^{B}{ }_{C}, \omega_{A_{3}}{ }^{F},{ }^{G}{ }_{C}\right\}\right)\right) .
\end{aligned}
$$

$F^{3}$ contains three spin three fields that carry at most three derivatives.

$$
\left.\left.\left.\begin{array}{rl}
H^{5}= & G^{A_{1} A_{2} A_{3} A_{4}} V^{C} V^{C} \operatorname{tr}\left(R _ { A _ { 1 } } { } ^ { G } { } _ { , A _ { 2 } } { } ^ { D } \left(2\left\{\omega_{A_{3} C, A_{4} E}, \omega_{C D, G}{ }^{E}\right\}-3\left\{\omega_{A_{3} D D, G}{ }^{E}, \omega_{A_{4} I}\right.\right.\right. \\
& +6\left\{\omega_{A_{3} G, C}{ }^{E}, \omega_{A_{4} D, C E}\right\}+8\left\{\omega_{A_{3}}{ }^{E}, C G\right.
\end{array}, \omega_{A_{4} D, C E}\right\}+\left\{\omega_{A_{3}}{ }^{E}, C G, \omega_{A_{4} E, C}^{D}\right\}\right)\right)
$$

$H^{5}$ contains up to five derivatives. Using the on shell condition it is straightforward, although somewhat lengthy, to check that

$$
Q^{t o p} H^{5} \sim 0, \quad Q^{s u b} H^{5} \sim 0, \quad Q^{c u r} H^{5} \sim 0
$$

That $H^{5}$ is not $Q^{t o p}-$ exact is easy to see.
$F^{3}$ is of Chern-Simons type. Hence it is equivalent to a higher-derivative vertex.

## Higher-spin algebra

Generic element

$$
A(\widehat{Y})=\sum_{n} A_{A_{1} \ldots A_{n}, B_{1} \ldots B_{n}} T^{A_{1} \ldots A_{n}, B_{1} \ldots B_{n}}
$$

where the coefficients are projected to two-row traceless Young diagrams

$$
\begin{gathered}
A^{\left\{A_{1} \ldots A_{n}, A_{n+1}\right\} B_{2} \ldots B_{n}}=0, \quad A^{A_{1} \ldots A_{n-2} C_{C}}{ }_{C}^{B_{1} \ldots B_{n}}=0 . \\
(A \circ B)^{A(n), B(n)}=\sum_{k l} f_{C(k), D(k) ; F(l), G(l)}^{A(n), B(n)}(h) A^{C(k), D(k)} B^{F(l), G(l)}
\end{gathered}
$$

HS algebra possesses the invariant trace operation

$$
\begin{gathered}
\operatorname{tr}(A \circ B)=\operatorname{tr}(B \circ A), \quad \operatorname{tr}(A)=A_{0}, \quad A_{0}=A_{A(0), B(0)} . \\
R_{A(n), B(n)}=d \omega_{A(n), B(n)}(x)+(\omega(x) \circ \wedge \omega(x))_{A(n), B(n)},
\end{gathered}
$$

## Cubic Action

$$
\begin{aligned}
& S=\frac{1}{2} \int_{M^{d}} \sum_{s} \sum_{p=0}^{s-2} a(s, p) V_{C_{1}} \ldots V_{C_{2(s-2-p)}} \wedge \\
& \operatorname{tr}\left(R^{B_{1} \ldots B_{s-1}},{ }_{1} \ldots C_{s-2-p} D_{1} \ldots D_{p+1} \wedge R_{B_{1} \ldots B_{s-1}}^{\prime}, A_{4} C_{s-1-p} \ldots C_{2(s-2-p)} D_{1} \ldots D_{p+1}\right)
\end{aligned}
$$

$t r$ is the trace over matrix indices in the case of HS algebras with nonAbelian Yang-Mills symmetries.

Choosing the coefficients in such a way that the on-shell ( $V^{A_{-i n d e p e n d e n} \text {-indepen }}$ takes the form

$$
S \sim \frac{1}{2} \int_{M^{d}} \operatorname{Tr}\left(R \wedge \circ R^{\prime}\right)
$$

implies its gauge invariance under the HS gauge transformations

$$
\delta R=[R, \epsilon]_{\circ}
$$

due to the cyclic property of trace and on-shell property

$$
F\left(R^{\prime}, R\right) \sim F\left(R, R^{\prime}\right)
$$

## $s p(2)$ invariance

In terms of generating functions

$$
A(Y)=\sum_{n} A_{A_{1} \ldots A_{n}, B_{1} \ldots B_{n}} Y_{1}^{A_{1}} \ldots Y_{1}^{A_{n}} Y_{2}^{B_{1}} \ldots Y_{2}^{B_{n}}
$$

That $A_{A_{1} \ldots A_{n}, B_{1} \ldots B_{n}}$ obeys the properties of two-row traceless Young diagrams is encoded by the constraints

$$
\begin{gathered}
\tau_{i j} A(Y)=0, \quad \Delta^{i j} A(Y)=0 \\
\tau_{i}^{j}=Y_{i}^{A} \frac{\partial}{\partial Y_{j}^{A}}-\frac{1}{2} \delta_{i}^{j} Y_{k}^{A} \frac{\partial}{\partial Y_{k}^{A}}, \quad \Delta^{i j}=\frac{\partial^{2}}{\partial Y_{i}^{A} \partial Y_{A j}} \\
i, j, \ldots=1,2, \quad a^{i}=\epsilon^{i j} a_{j}, \quad a_{i}=a^{j} \epsilon_{j i}, \quad \epsilon_{i j} \epsilon_{i j}=-\epsilon_{j i}, \quad \epsilon_{12}=1
\end{gathered}
$$

$\tau_{i j}=\tau_{j i}$ generate $\operatorname{sp}(2)$ with the invariant symplectic form $\epsilon_{i j}$.

Non-zero vertices are represented by $s p_{\mu}(2)$ singlets for all $\mu$

## Vertex generating functions

It is convenient to replace $G^{A_{1} \ldots A_{q}}$ by a product of anticommuting variables $\psi^{A_{1}} \ldots \psi^{A_{q}}$. All $o(d-1,2)$ invariant contractions are represented by operators

$$
\Delta^{i^{\mu} j^{\nu}}=\Delta^{j^{\nu} i^{\mu}}=\frac{\partial^{2}}{\partial Y_{i^{\mu}}^{A} \partial Y_{A j^{\nu}}}, \quad p_{i}=V^{A} \frac{\partial}{\partial Y^{A^{i \mu}}}, \quad \sigma_{i^{\mu}}=\psi^{A} \frac{\partial}{\partial Y^{A^{i^{\mu}}}}
$$

General vertex

$$
F(A)=\left.F(\Delta, p, \sigma) \prod_{\rho=1}^{N} A_{\rho}\left(Y_{\rho}\right)\right|_{Y_{\sigma}=0}
$$

That $A_{\nu}\left(Y_{\nu}\right)$ describes traceless tensors implies $\Delta^{i^{\mu} j^{\mu}} A_{\mu}\left(Y_{\mu}\right)=0$.
$F(\Delta, p, \sigma)$ should be $s p_{\mu}(2)$ invariant for any $\mu$.
Using labels $\bar{\nu}$ for $A\left(Y_{\nu}\right)=R_{1}\left(Y_{\nu}\right)$, the on-shell conditions are

$$
p_{i^{\nu}} F \sim 0, \quad \frac{\partial}{\partial Y^{A_{i^{\nu}}}} \frac{\partial}{\partial \psi_{A}} F \sim 0
$$

## Non-Abelian and current vertices

In terms of generating functions pure non-Abelian vertex
$L(V)=\left.V_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta) R_{\alpha^{1}}^{\prime}\left(Y_{1}\right) \omega_{\alpha^{2}}\left(Y_{2}\right) \omega_{\alpha^{3}}\left(Y_{3}\right)\right|_{Y_{i}=0}, \quad V_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta)=-V_{132}^{\alpha^{1} \alpha^{3} \alpha^{2}}$ $R^{\prime}(Y)$ is the dual curvature ( $d-2$ )-form.
$L(V)$ is $Q^{t o p}$ and $Q^{s u b_{-}}$closed because it does not contain the compensator

$$
Q^{c u r} L=\left.(-1)^{d}\left(V_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta)-V_{231}^{\alpha^{2} \alpha^{3} \alpha^{1}}(\Delta)\right) R_{\alpha^{1}}^{\prime}\left(Y_{1}\right) R_{\alpha^{2}}\left(Y_{2}\right) \omega_{\alpha^{3}}\left(Y_{3}\right)\right|_{Y_{i}=0},
$$

$Q^{\text {cur }} L(V)=0$ with totally antisymmetric $V_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}$ in which case $L(V)$ is pure: $Q^{f l} L(V)=0, Q^{\text {sub }} L(V)=0$

Pure current vertices
$F(\tilde{U})=-Q^{s u b} T(\tilde{U})=\left.\sigma_{i^{1}} \sigma^{i^{i}} \sigma_{j^{2}} \sigma^{j^{2}} \sigma_{k^{3}} k^{k^{3}} \tilde{U}_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta) R_{\alpha^{1}}\left(Y_{1}\right) R_{\alpha^{2}}\left(Y_{2}\right) \omega_{\alpha^{3}}\left(Y_{3}\right)\right|_{Y_{i}=}$

All non-Abelian vertices $L(V)$ and current vertices $F(\tilde{U})$ are pure vertices with $s_{1}+s_{2}+s_{3}-2$ derivatives. Since there exists just one nontrivial Minkowski vertex of this order of derivatives, most of vertices $L(V)$ and $F(\tilde{U})$ should be quasi exact.
Consider

$$
\begin{aligned}
I & \left.=-w_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta) \sigma_{i^{1}}{\sigma^{i}}^{1} \sigma_{j^{2}} \sigma^{j^{2}} \sigma_{k^{3}} p^{k^{3}} R_{\alpha^{1}}\left(Y_{1}\right) R_{\alpha^{2}}\left(Y_{2}\right) \omega_{\alpha^{3}}\left(Y_{3}\right)\right)\left.\right|_{Y=0} \\
J & =\frac{3}{d-4} w_{(123)}^{\left(\alpha^{1} \alpha^{2} \alpha^{3}\right)}(\Delta) \sigma_{i^{1}}{\sigma^{i^{1}} \sigma_{j^{2}} \sigma_{k^{3}} \Delta^{j^{2} k^{3}} R_{\alpha^{1}}\left(Y_{1}\right) \omega_{\alpha^{2}}\left(Y_{2}\right) \omega_{\alpha^{3}}\left(Y_{3}\right)}
\end{aligned}
$$

with arbitrary $w_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta)$ and $w_{(123)}^{\left(\alpha^{1} \alpha^{2} \alpha^{3}\right)}(\Delta)=\frac{1}{6} \sum_{\mu \neq \nu \neq \rho} w_{\mu \nu \rho}^{\alpha^{\mu} \alpha^{\nu} \alpha^{\rho}}(\Delta)$.
One can see that

$$
\begin{gathered}
I+J=(-1)^{d} Q^{f l}(H+W) \\
H=\left.w_{(123)}^{\left(\alpha^{1} \alpha^{2} \alpha^{3}\right)}(\Delta)(\Delta) \sigma_{i 1} \sigma^{i^{1}} \sigma_{j^{2}} \sigma_{k^{3}} \Delta^{j^{2} k^{3}} \omega_{\alpha^{1}}\left(Y_{1}\right) \omega_{\alpha^{2}}\left(Y_{2}\right) \omega_{\alpha^{3}}\left(Y_{3}\right)\right|_{Y=0} \\
W=\left.w_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta) \sigma_{1 i} \sigma_{1}^{i} \sigma_{2 j} \sigma_{2}^{j} \sigma_{k^{3}} p^{k^{3}} R_{\alpha^{1}}\left(Y_{1}\right) \omega_{\alpha^{2}}\left(Y_{2}\right) \omega_{\alpha^{3}}\left(Y_{3}\right)\right|_{Y=0}
\end{gathered}
$$

## This implies that the sum of the current vertex $I$ and non-Abelian vertex

 $J$ is quasi exact. (cf the case of spin two).To perform further reduction more tricky consequences of the on-shell conditions should be used

$$
\begin{gathered}
Q^{t o p} N \sim \frac{(-1)^{d}}{d-5} \sigma_{k^{1}} \sigma^{k^{1}} \sigma_{j^{2}} \sigma^{j^{2}} \sigma_{l^{3}} p^{l^{3}}\left(2 \Phi_{12} \Phi_{13} \Phi_{23}+\Phi^{2}\right) N_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta) R_{\alpha^{1}}\left(Y_{1}\right) R_{\alpha^{2}}(Y \\
N=\Phi_{12} N_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta) \sigma_{i^{1}} \sigma^{i^{1}} \sigma_{j^{2}} \sigma^{j^{2}} \sigma_{k^{3}} \sigma^{k^{3}} p_{n^{3}} p_{m^{3}} \Delta^{n^{3} u^{1}} \Delta_{u^{1} v^{2}} \Delta^{v^{2} m^{3}} R_{\alpha^{1}}\left(Y_{1}\right) R_{\alpha^{2}}\left(Y_{2}\right) \\
\Phi_{\mu \nu}=\Delta_{\mu^{\mu}} j^{\nu} \Delta_{j^{\nu}} i^{\mu} \quad \mu \neq \nu, \quad \Phi \equiv \Phi_{123}=\Delta_{i^{1}}^{j^{2}} \Delta_{j^{2}}^{k^{3}} \Delta_{k^{3}} .
\end{gathered}
$$

As a result any vertex $I$ with

$$
w_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta)=\left(2 \Phi_{12} \Phi_{13} \Phi_{23}+\Phi^{2}\right) v_{123}^{\alpha^{1} \alpha^{2} \alpha^{3}}(\Delta)
$$

is quasi-exact and, hence, is equivalent some lower derivative vertex. Similarly one proceeds with further reductions of derivatives.

This mechanism works for $d \geq 6$. In $d=4$ quasi exact current vertices do not exist. Hence $4 d$ triangle vertices result from non-Abelian vertices. Indeed, the list of independent $4 d$ vertices is shorter than for any $d$.

## Comparison with flat space results

Minkowski vertices

$$
s_{1}+s_{2}-s_{3} \leq 2 N \leq s_{1}+s_{2}+s_{3}
$$

The vertices obtained in $A d S_{d}$ require $s_{i}-1$ satisfy triangle inequalities

$$
s_{i}+s_{j}-s_{k}-1 \geq 0, \quad i \neq j \neq k
$$

Vertices, that can be constructed in terms of connection one-forms and curvature two-forms, should respect the triangle inequalities otherwise otherwise contraction of indices between two-row Young diagrams gives zero. The reason why some of vertices were missed is that we did not consider vertices that contain Weyl 0-forms directly.

## Particular examples:

The vertex with maximal number of derivatives $s_{1}+s_{2}+s_{3}$ is not on the list since all vertices considered considered so far contain at most $s_{1}+s_{2}+s_{3}-2$ derivatives since all $R^{3}$ vertices are quasi exact.
interactions of a spin- $s$ gauge field with two spin zero scalar fields. Scalar is described by the zero-form $C(x)$ and its derivatives $=$ elements of the Weyl module for the spin zero field. In this case of current interactions between a spin-s gauge field and HS currents built from (derivatives) ol the scalar field the triangle inequalities are not respected.

To incorporate vertices of general type into the scheme it is necessary extend First-On-Shell Theorem to the Central on-shell theorem that contains the equations on zero-forms in the Weyl module $C(x)$

$$
\tilde{D} C=0
$$

## Towards full nonlinear action

Extension to the full system of fields that enter the free unfolded formulation of massless HS fields, including Weyl zero-forms, reduces analysis of cubic HS interactions to the analysis of vertices that are on-shellclosed by virtue of unfolded field equations. The idea is to look for a nonlinear action

$$
S=\int L,
$$

where $d$-form $L$ is on-shell closed

$$
d L \sim 0
$$

by virtue of the nonlinear unfolded equations and such that the quadratic part of the action coincides with the standard free action of massless fields.

Lagrangians of this type will describe HS dynamics modulo local field redefinitions.

Vertices with different numbers of derivatives are related in $A d S$

Vertex tri-complex classifies nontrivial vertices in $A d S_{d}$
$A d S$-tri-complex contains a Minkowski sub-bicomplex
Vertex tri-complex applies to mixed symmetry type of general type and higher-order vertices

HS vertices for symmetric fields are uniformally formulated as nonAbelian and current interactions that carry $s_{1}+s_{2}+s_{3}-2$ derivatives

Missed vertices do not respect triangle inequalities for spins, requiring explicit appearance of the Weyl tensor and its derivatives

Full nonlinear Lagrangian as a on-shell closed form $d L \sim 0$ by virtue of full nonlinear unfolded equations

The novel feature of our proposal is that the analysis of the nonlinear action is (and, in fact, should be) on-shell beyond its free field part. This suggestion changes the strategy of the action construction: instead of looking for an action, that gives rise to the unfolded equations, having unfolded equations one should find a lagrangian that is on-shell closed by virtue of unfolded equations.

Such an approach fits very well the analysis of HS theory performed by Giombi and X.Yin 2009, in the context of AdS/CFT interpretation of HS theory, which is solely based on the unfolded dynamics approach.

Remarkably, this construction gets very similar to the effective action construction of QFT.

