Dilatation operator: general structures

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SQS'11: July 18, 2011

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Outline



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- 3 General case
 - 4D theory
 - 3D theory
- 4 Conclusion & Outlook

based on (ArXiv): 1003.5272, 0811.2669, 0804.1835, 0707.3517, hep-th/0701089, hep-th/0611274, hep-th/0608028, hep-th/0411261, hep-th/0410010, hep-th/0409086, hep-th/0408102, hep-th/0404066

General Motivation

- Known examples of solvable gauge models bring to geometric description Examples:
 - Matrix models
 - Seiberg–Witten model
 - Chiral model for strongly coupled QCD
 - ▶ etc...

General Motivation

- Macroscopic description: introduce collective variables taking the values in the phase/moduli space of the model.
- Non-trivial symmetries of the microscopic model (apart from gauge invariance) translate to the symmetries of the macroscopic one
- The description can not depend on the parametrization of the space of collective modes ⇒ The effective theory should be geometric, i.e. phase/moduli space reparametrization invariant
- The scale appears as a (thermo)dynamical parameter

$({\tt non}){\sf AdS}/({\tt non}){\sf CFT}$

- Most striking example of such a description is provided by AdS/CFT correspondence.
- Originally it was formulated as a property of the string theory, but in the present it extended outside the string theory framework.
- It is a two-way weak/strong coupling correspondence
- Most studied case: correspondence between 4D ${\cal N}=4$ super Yang–Mills theory and string/gravity on AdS₅ \times S^5
- Intensively studied: correspondence between 3D Chern–Simons–matter conformal theory and $AdS_4 \times S^7/\mathbb{Z}_k$ and relative theories...

AdS/CFT correspondence ingredients $(\mathcal{N} = 4 \text{ SYM})$

In the limit of large gauge group rank *N*, we have the correspondence [Maldacena]

$$(\mathcal{N} = 4 \text{ SYM})_{\mathcal{M}_{1,3}} \Leftrightarrow (\text{string theory})_{\mathrm{AdS}_5 \times S^5}$$

Identification of symmetry groups $PSU(2,2|4) \supset SO(2,4) \times SO(6)$; The correspondence between operators of SYM and states of ST. Dilatations correspond to time shifts

For $N<\infty$ the string interactions should be included with the rate $\sim N^{-1}$.

 $g_s \sim J^2/N, \qquad J-{
m classical}~{
m dimension}/{
m length}$

SYM: $N \rightarrow \infty$ — invariance of single trace operators. Single trace operators do not mix with multi-trace ones under renormalization. Integrability [Minahan-Zarembo,Beisert-Staudacher, etc] \rightarrow "AdS/CFT dictionary"

"AdS/CFT dictionary"

$AdS_5 imes S^5$ strings	$\mathcal{N}=4$ SYM
quantum states	Local gauge invariant composite operators (LGICO)
AdS isometry	Conformal symmetry
Sphere isometry	<i>R</i> -symmetry
Time shift	Dilatation, RG-flow
Hamiltonian, <i>H</i>	Dilatation operator, Mixing matrix, Δ

This *dictionary* was checked in various regimes, but there is (will be?) *no* mathematical proof.

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Explicit construction of the dynamical system

 $\mathcal{N} = 4$ SYM field content: A_{μ} , ψ , ϕ^{i} , i = 1, ..., 6"Alphabet": $\{W_{A}\} = \{F_{\mu\nu}, \phi, \psi, \nabla F, \nabla \phi, \nabla \psi ...\}$ "Language": gauge invariant combinations of letters "Words": simplest gauge invariants, one-trace composite operators,

$$\mathcal{O}_{A_1A_2...A_L} = \operatorname{tr} W_{A_1}W_{A_2}\ldots W_{A_L}$$

"Phrases" (LGICO):

$$\mathcal{O}_{A_1A_2\dots A_{L_1}}\mathcal{O}_{B_1B_2\dots B_{L_2}}\dots \mathcal{O}_{C_1C_2\dots C_{L_r}}$$

Operator mixing: as $N \rightarrow \infty$ the trace structure becomes invariant: linear combinations of *words* form invariant spaces

Scale dependence: Renormalization & Operator mixing

Scale dependence is induced by the renormalization Consider a set of composite operators $\{O_J\}$ closed under renormalization (mixing)

$$\mathcal{O}_J^{Ren} = Z(\Lambda)_J{}^J \mathcal{O}_J$$

Dilatation Operator (Generator of RG-flows, now our Hamiltonian)

$$\Delta = Z^{-1} \cdot \frac{\partial Z}{\partial \log \Lambda}$$

Anomalous dimensions

$$\Delta \mathcal{O}_{\lambda} = \lambda \mathcal{O}_{\lambda}$$

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General case

- So far we considered the case of $\mathcal{N}=4$ in 4D. Generalizations to other cases are possible.
- Various deformations of $\mathcal{N} = 4$ SYM in 4d; Chern-Simons-matter theories (ABJM & friends) in 3d were considered since that...
- How about the general case?
 - Can we construct a corresponding model in the general case of a renormalizable theory?
 - What are the necessary ingredients?
 - And which are the universal structures?
 - What are the model dependent features?

One can construct a quantum theory model from the original field theory. The new quantum theory is defined by,

• Hilbert space of States:

space of LGICO (Local gauge invariant composite operators)

- Hamiltonian: Dilatation Operator, (RG-flow generator)
- Observables: Automorphisms of the algebra of LGICOs.

- The states should form a Hilbert space!
- Hermitian Hamiltonian...
- etc...

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Hermitian product and Hamiltonian for a CFT

Consider first a Conformal Field Theory. The primary operators $\mathcal{O}_1(x)$ and $\mathcal{O}_2(x)$ of dimensions Δ_1 and Δ_2 have the following correlator,

$$\langle \mathcal{O}_1(x)\mathcal{O}_2(0)
angle = rac{C\delta_{\Delta_1\Delta_2}}{x^{\Delta_1+\Delta_2}}$$

The identification $\mathcal{O}\mapsto |\mathcal{O}\rangle$ with $\langle \mathcal{O}_1 \mid \mathcal{O}_2 \rangle = C \delta_{\Delta_1 \Delta_2}$ and

$$H | \mathcal{O}_i \rangle = \Delta_i | \mathcal{O}_i \rangle$$

solves the problem...

Hermitian product and Hamiltonian for a generic QFT

We can extend this for a generic renormalizable theory: Hermitian product and Hamiltonian can be introduced through the correlators

$$\begin{split} \langle \mathcal{O}^{\dagger}(x)\mathcal{O}'(0)\rangle &= \langle \mathcal{O}|\,(\mu^{2}x^{2})^{-\mathbf{D}}\,\big|\mathcal{O}'\rangle \equiv \langle \mathcal{O}|\,\mathrm{e}^{-\tau\mathbf{D}}\,\big|\mathcal{O}'\rangle\\ \bar{\tau} &= \log(\mu^{2}x^{2})\\ \langle \mathcal{O}\,|\,\mathcal{O}'\rangle &= \langle \mathcal{O}^{\dagger}(x)\mathcal{O}'(0)\rangle|_{\mu^{2}x^{2}=1}\\ \langle \mathcal{O}|\,\mathbf{D}\,\big|\mathcal{O}'\rangle &= -\frac{1}{2}\mu\frac{\partial}{\partial\mu}\langle \mathcal{O}^{\dagger}(x)\mathcal{O}'(0)\rangle|_{\mu^{2}x^{2}=1} \end{split}$$

 τ

... as soon as we identify local operators with quantum states

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General Construction for Hermitian product and Hamiltonian

We have to analyze the RG-transformation of a composite operator \mathcal{O} in perturbation theory. Mixing matrix $Z(\Lambda)$ can be found considering divergent terms in correlators of two probe operators \mathcal{O} and \mathcal{O}' ,

$$\langle : \mathcal{O}'_{\mathcal{Y}}(\phi) :: \mathcal{O}_{0} : \rangle = \langle : \mathcal{O}'_{\mathcal{Y}} : e^{-\int : V(\phi) :} : \mathcal{O}_{0} : \rangle_{0}$$

The source of relevant divergences is the Wick expansion of products

$$e^{-\int :V(\phi):}:\mathcal{O}_0:=\left(1-\int :V(\phi):+rac{1}{2!}\iint :V(\phi)::V(\phi):+\ldots
ight):\mathcal{O}_0:$$

So, we should modify \mathcal{O}_0 in such a way to cancel divergences and find the scale dependence after the cancelation.

Wick expansion

Wick expansion in functional form can be cast into [see one of the Kleinert's books]

$$:\mathcal{O}_y'::\mathcal{O}_x:=\mathrm{e}^{\check{\phi}_{A_y}D_{AB}(y-x)\check{\phi}_{Bx}}\mathcal{O}_y'\mathcal{O}_x\equiv\mathcal{O}'*\mathcal{O}(x,y)$$

* — star product resembles one in noncommutative theories, but is different

$$\check{\phi}_{Ax}=rac{\partial}{\partial \phi_A(x)}$$
 Not a functional derivative!

e.g. Euclidean massless propagator Functional Wick expansion can be generalized to the product of 3, 4,...factors

A note on Notations

We have to deal with complicate expressions $\sqrt[4]{2}$ notations are important.

Condensed (multi-index)

$$\mu_1\mu_2\ldots\mu_n\to\mathbf{n},\qquad \phi_{\mathbf{n}}=\partial_{\mathbf{n}}\phi(\mathbf{0})$$

• A traceless set of indices,

$$(\mu_1\mu_2\ldots\mu_n) \to (\mathbf{n}): \qquad \phi_{(\mathbf{n})}$$

In general, treat space-time indices as sets,

$$\mathbf{n} + \mathbf{m} \rightarrow \mu_1 \mu_2 \dots \mu_n \nu_1 \nu_2 \dots \nu_m$$

$$\mathbf{n} \setminus \mathbf{r} \to \mu_1 \dots \check{\mu}_{i_1} \dots \check{\mu}_{i_r} \dots \mu_n, \quad \mathbf{r} \to \mu_{i_1} \dots \mu_{i_r}, \quad \mathbf{r} \subset \mathbf{n}$$

summation over intersecting sets. . .

The 4D theory

The scale dependence of the two-point function is dimension (and model) dependent

$$S = \int \mathrm{d}x \, \left(-\frac{1}{2}\phi \cdot D^{-1} \cdot \phi + V(\phi) \right)$$

The basic propagators in four-dimensions are

$$D(x) = egin{cases} \sim rac{1}{4\pi^2}rac{1}{x^2} & ext{scalars, gauge bosons, etc,} \ \sim \gamma^\mu \partial_\mu rac{1}{4\pi^2}rac{1}{x^2}, & ext{fermions,} \end{cases}$$

- LGICOs are polynomials in fundamental letter and their derivatives.
- LGICOs are defined modulo EoM [™] can eliminate the traces of derivatives

Tools: differential renormalization

Differential regularization/renormalization scheme in real space allows to regularize singular expressions like [Freedman-Johnson-Latorre],

$$\frac{1}{x^{2k}} = -\frac{1}{4^{k-1}(k-1)!(k-2)!} \Box^{k-1} \frac{\ln \mu^2 x^2}{x^2}, \qquad k \ge 2$$

introduces a scale dependence:

$$\mu \frac{\partial}{\partial \mu} \left[\frac{1}{x^{2k}} \right]_{\text{reg}} \equiv \left[\frac{1}{x^{2k}} \right] = \frac{8\pi^2}{4^{k-1}(k-1)!(k-2)!} \Box^{k-2} \delta(x)$$

where we used the property

$$\Box \frac{1}{x^2} = -4\pi^2 \delta(x)$$

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One vertex level

In the leading one-loop approximation the contribution comes only from one- and two-vertex Feynman diagrams. Consider first the one-vertex level Regularizing the terms in the Wick Expansion we get for the first order in interaction potential

$$\begin{split} &-\int \mathrm{d}y \left[V_{\mathrm{int}}(y) * \right] = -\int \mathrm{d}y \, \left[\mathrm{e}^{\check{\phi}_y \cdot D_y \cdot \check{\phi}} \right] V_y \\ &= -\int \mathrm{d}y \left(\check{\phi}_y \cdot [D_y] \cdot \check{\phi} + \frac{1}{2} (\check{\phi}_y \otimes \check{\phi}_y) \cdot [D_y \otimes D_y] \cdot (\check{\phi} \otimes \check{\phi}) \right. \\ &+ \frac{1}{3!} (\check{\phi}^{\otimes 3}) \cdot [D_y^{\otimes 3}] \cdot (\check{\phi}^{\otimes 3}) + \frac{1}{4!} (\check{\phi}^{\otimes 4}) \cdot [D_y^{\otimes 4}] \cdot (\check{\phi}^{\otimes 4}) + \dots \right) V_y, \end{split}$$

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Two vertex level

Second level yields

$$\begin{split} \frac{1}{2!} \int \mathrm{d}y_1 \int \mathrm{d}y_2 [V_{\mathrm{int}}(y_1) * V_{\mathrm{int}}(y_2) *] \\ &= \frac{1}{2} \int \mathrm{d}y_1 \int \mathrm{d}y_2 \times \\ &\left\{ (\check{\phi}_{y_1} \otimes \check{\phi}_{y_1} \otimes \check{\phi}_{y_2}) \cdot [D_{y_1} \otimes D_{y_1 - y_2} \otimes D_{y_2}] \cdot (\check{\phi} \otimes \check{\phi}_{y_2} \otimes \check{\phi}) + \right. \\ &\left. (\check{\phi}_{y_1}^{\otimes 3} \otimes \check{\phi}_{y_2}) \cdot [D_{y_1}^{\otimes 2} \otimes D_{y_1 - y_2} \otimes D_{y_2}] \cdot (\check{\phi}^{\otimes 2} \otimes \check{\phi}_{y_2} \otimes \check{\phi}) + \ldots \right\} V_{y_1} V_{y_2}. \end{split}$$

3

The The 3D theory

The leading contribution in 3*D* comes from the two loop level Basic propagators

$$D(x) = \begin{cases} \frac{1}{4\pi x}, & \text{for scalars, gauge bosons, etc,} \\ \gamma^{\mu} \partial_{\mu} \frac{1}{4\pi x}, & \text{for fermions,} \\ \epsilon_{\mu\nu\lambda} \partial_{\lambda} \frac{1}{4\pi x}, & \text{for Chern-Simons fields.} \end{cases}$$

Basic objects are still LGICO $O(\Phi)$, depending on fundamental fields $\phi(x)$ and their derivatives

$$\phi_{\mu_1\mu_2\ldots\mu_n}\equiv\partial_{\mu_1}\partial_{\mu_2}\ldots\partial_{\mu_n}\phi(0)$$

EoMs can be used to eliminate the dependence on CS gauge fields traces of derivatives

"Functional Wick Expansion"

Functional form of Wick expansion can be introduced through the following equations

$$: \mathcal{O}_1 :: \mathcal{O}_2 := e^{\check{D}_{12}} : \mathcal{O}_1 \mathcal{O}_2 :$$

$$: \mathcal{O}_1 :: \mathcal{O}_2 :: \mathcal{O}_3 := e^{\check{D}_{12} + \check{D}_{13} + \check{D}_{23}} : \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 :$$

$$: \mathcal{O}_1 :: \mathcal{O}_2 :: \mathcal{O}_3 :: \mathcal{O}_4 := e^{\check{D}_{12} + \check{D}_{13} + \check{D}_{23} + \check{D}_{14} + \check{D}_{24} + \check{D}_{34}} : \mathcal{O}_1 \mathcal{O}_2 \mathcal{O}_3 \mathcal{O}_4 :$$

$$: \mathcal{O}_1 :: \mathcal{O}_2 : \cdots : \mathcal{O}_k := e^{\left(\sum_{l < m} \check{D}_{lm}\right)} : \mathcal{O}_1 \mathcal{O}_2 \dots \mathcal{O}_k :$$

where \check{D}_{xy} is a two-point differential operator

$$\check{D}_{xy} = \check{\Phi}_{x} \cdot \mathbf{D}_{xy} \cdot \check{\Phi}_{y} = \sum_{(\mathbf{n})} D_{xy}^{(\mathbf{n})} \check{s}_{xy}^{(\mathbf{n})},$$

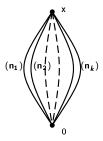
$$\check{s}_{xy}^{(\mathbf{n})} = \sum_{\substack{\mathbf{r},\mathbf{s}\\\mathbf{r}+\mathbf{s}=\mathbf{n}}} (-1)^{s} \check{\phi}_{x}^{(\mathbf{r})} \cdot \check{\phi}_{y}^{(\mathbf{s})} + \sum_{\substack{\mathbf{r},\mathbf{s}\\\mathbf{r}+\mathbf{s}+1=\mathbf{n}}} (-1)^{s} \check{\psi}_{x}^{(\mathbf{r})} \gamma^{1} \check{\psi}_{y}^{(\mathbf{s})} + \sum_{\substack{\mathbf{r},\mathbf{s}\\\mathbf{r}+\mathbf{s}+1\widetilde{1}'=\mathbf{n}}} (-1)^{s} \check{A}_{1x}^{(\mathbf{r})} \check{A}_{1y}^{(\mathbf{s})}$$

$$\check{\Phi}_{x} = \frac{\partial}{\partial \Phi_{x}}$$

One vertex lever (two point function)

The first non-trivial contribution comes from the first term of the expansion of interaction exponent,

$$\int_{y} \left[e^{\check{D}_{y0}} \right] V_{y} = \sum_{k} \frac{1}{k!} \left[D_{y0}^{(n_{1})} \dots D_{y0}^{(n_{k})} \right] \check{s}_{y0}^{(n_{1})} \dots \check{s}_{y0}^{(n_{k})} V_{y}$$



Two loops
$$\Rightarrow k = 3$$
.

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Evaluation of divergencies: 1-vertex level; two loops

$$\Delta_{(\mathbf{n})(\mathbf{m})(\mathbf{k})} \equiv \left[D_x^{(\mathbf{n})} D_x^{(\mathbf{m})} D_x^{(\mathbf{k})} \right] = \frac{1}{(4\pi)^3} \left[\partial_{(\mathbf{n})} \frac{1}{x} \partial_{(\mathbf{m})} \frac{1}{x} \partial_{(\mathbf{k})} \frac{1}{x} \right]$$

From general considerations we have,

$$\Delta_{(\mathbf{n}),(\mathbf{m}),(\mathbf{k})}(x) = \frac{1}{(4\pi)^3} \sum_{\mathbf{r},s} F_{(\mathbf{n}),(\mathbf{m}),(\mathbf{k})}^{(\mathbf{r}),s} \partial_{(\mathbf{r})} \partial^{2s} \delta(x),$$

where $F_{(n),(m),(k)}^{(r),s}$ are numerical coefficients, defined by

$$F_{(\mathbf{n}),(\mathbf{m}),(\mathbf{k})}^{(\mathbf{r}),s} = f_{nmk}^{(\mathbf{r}),s} \left[\int_{X} \frac{\mathbf{x}^{(\mathbf{n})+(\mathbf{m})+(\mathbf{k})+(\mathbf{r})}}{x^{3+2(n+m+k-s)}} \right]$$

where

$$f_{nmk}^{(\mathbf{r}),s} = (-1)^{n+m+k} (2n-1)!! (2m-1)!! (2k-1)!! \alpha^{(\mathbf{r}),s}$$

and the factors $\alpha^{(\mathbf{n}),r}$ are the trace-reduced coefficients of Taylor expansion,

$$V_{x} = \sum_{(\mathbf{n}), r} \alpha^{(\mathbf{n}), r} \mathbf{x}^{(\mathbf{n})} x^{2r} \partial_{(\mathbf{n})} \partial^{2r} V_{0}.$$
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One-vertex level coefficients

The evaluation of Fs in dimensional regularization scheme and with IR cut-off μ , produces the following relevant contribution

$$\frac{2^{-(n+m+k+1)}(n+m+k)!\pi^{D/2}}{\Gamma\left(\frac{D+n+m+k}{2}\right)}g^{(\mathbf{n})+(\mathbf{m})+(\mathbf{k})}\mu^{-\epsilon}\Gamma(\epsilon)$$

This yields,

$$F_{(\mathbf{n}),(\mathbf{m}),(\mathbf{k})}^{(\mathbf{r}),s} = -\delta_{n+m+k-r-2s,0} f_{nmk}^{(\mathbf{r}),s} g^{(\mathbf{n})+(\mathbf{m})+(\mathbf{k})} \frac{2^{-\frac{n+m+k}{2}}\pi}{(n+m+k+1)!!}$$

The Dilatation operator at one vertex level is given by,

$$H_{1-\text{vertex}} = \frac{1}{(4\pi)^3} \sum_{\{\mathbf{nmk}\}} F_{(\mathbf{n}),(\mathbf{m}),(\mathbf{k})}^{(\mathbf{r}),s} \partial_{(\mathbf{r})} \partial^{2s} \check{s}_{(\mathbf{n})} \check{s}_{(\mathbf{m})} \check{s}_{(\mathbf{k})}[V]$$

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Two-vertex level

Two vertex level is given by the second term of the expansion of interaction exponent

$$H_{2-\text{vertex}} = \frac{1}{2!} \int_{X} \int_{Y} \left[e^{\check{\Phi}_{x} \cdot \mathbf{D}_{xy} \cdot \check{\Phi}_{y} + \check{\Phi}_{x} \cdot \mathbf{D}_{x} \cdot \check{\Phi} + \check{\Phi}_{y} \cdot \mathbf{D}_{y} \cdot \check{\Phi}} \right] V_{x} V_{y}$$

Restrict to the two loop part

$$\begin{aligned} H_{2-\text{vertex}} &= \int_{X} \int_{Y} \left(\frac{1}{2} \Delta_{(\mathbf{n}_{1})(\mathbf{n}_{2});(\mathbf{m});(\mathbf{k})}(x,y) \check{s}_{x}^{(\mathbf{n}_{1})} \check{s}_{x}^{(\mathbf{n}_{2})} \check{s}_{y}^{(\mathbf{m})} \check{s}_{xy}^{(\mathbf{k})} \right. \\ &+ \frac{1}{4} \Delta_{(\mathbf{n});(\mathbf{m});(\mathbf{k}_{1})(\mathbf{k}_{2})}(x,y) \check{s}_{x}^{(\mathbf{n})} \check{s}_{y}^{(\mathbf{m})} \check{s}_{xy}^{(\mathbf{k}_{1})} \check{s}_{xy}^{(\mathbf{k}_{2})} \right) V_{x} V_{y}, \end{aligned}$$

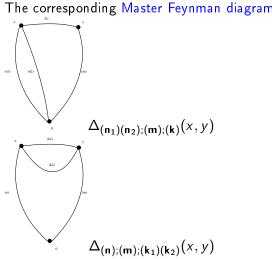
with

$$\Delta_{(\mathbf{n}_{1})(\mathbf{n}_{2});(\mathbf{m});(\mathbf{k})}(x,y) = \frac{1}{(4\pi)^{4}} \left[\partial_{(\mathbf{n}_{1})} \frac{1}{x} \partial_{(\mathbf{n}_{2})} \frac{1}{x} \partial_{(\mathbf{m})} \frac{1}{y} \partial_{(\mathbf{k}_{1})}^{x} \frac{1}{|x-y|} \right],$$

$$\Delta_{(\mathbf{n});(\mathbf{m});(\mathbf{k}_{1})(\mathbf{k}_{2})}(x,y) = \frac{1}{(4\pi)^{4}} \left[\partial_{(\mathbf{n})} \frac{1}{x} \partial_{(\mathbf{m})} \frac{1}{y} \partial_{(\mathbf{k}_{1})}^{x} \frac{1}{|x-y|} \partial_{(\mathbf{k}_{2})}^{x} \frac{1}{|x-y|} \right],$$

$$\Box \mapsto \langle \Box \rangle \langle \Box \rangle$$

Two-vertex level



The corresponding Master Feynman diagrams are

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Two-vertex level

Duality relates these factors

$$\Delta_{(\mathbf{n});(\mathbf{m});(\mathbf{k}_1)(\mathbf{k}_2)}(x,y) = (-1)^m \Delta_{(\mathbf{k}_1)(\mathbf{k}_2);(\mathbf{m});(\mathbf{n})}(x-y,-y)$$

Evaluation of the general structure reveals

$$\Delta_{(\mathbf{n}_1),(\mathbf{n}_2);(\mathbf{m});(\mathbf{k})}(x,y) = \frac{1}{(4\pi)^4} \sum_{\substack{\mathbf{p},r\\\mathbf{s},t}} F_{(\mathbf{n}_1),(\mathbf{n}_2);(\mathbf{m});(\mathbf{k})}^{(\mathbf{p})} \partial_{(\mathbf{p})}^{2r} \delta(x) \partial_{(\mathbf{s})} \partial^{2t} \delta(y)$$

$$F_{(\mathbf{n}_1),(\mathbf{n}_2);(\mathbf{m});(\mathbf{k})}^{(\mathbf{p}),r;(\mathbf{s}),t} = f_{n_1n_2mk} \int_X \int_Y \left[\frac{\mathbf{x}^{(\mathbf{n}_1)+(\mathbf{n}_2)+(\mathbf{p})}}{x^{2+2(n_1+n_2-r)}} \frac{\mathbf{y}^{(\mathbf{m})+(\mathbf{s})}}{y^{1+2(m-t)}} \frac{(\mathbf{x}-\mathbf{y})^{(\mathbf{k})}}{|x-y|^{1+2k}} \right]$$

.

B> B

where,

$$f_{n_1n_2mk} = (-1)^{n_1+n_2+m+k} (2n_1-1)!!(2n_2-1)!!(2m-1)!!(2k-1)!!\alpha^{(\mathbf{p}),r}\alpha^{(\mathbf{s}),t}$$

Two-vertex level coefficients

We can apply a "trick" to simplify the three-point coefficient function. Method of 'Uniqueness' [Kazakov et al.].

$$\xrightarrow{n,\alpha} \underbrace{m,\beta} \longrightarrow v_{nm}(\alpha,\beta) \times \underbrace{n+m,\alpha+\beta-D}$$

or

$$\int_{y} \frac{(\mathbf{x} - \mathbf{y})^{\mathbf{m}}}{|\mathbf{x} - \mathbf{y}|^{\beta}} \frac{\mathbf{y}^{\mathbf{n}}}{y^{\alpha}} = v_{nm}(\alpha, \beta) \frac{\mathbf{x}^{\mathbf{n} + \mathbf{m}}}{x^{\alpha + \beta - D}}$$
$$v_{nm}(\alpha, \beta) = \pi^{D/2} 2^{-2(n+m)} \frac{\Gamma(\frac{D-\alpha}{2} + n)\Gamma(\frac{D-\beta}{2} + m)\Gamma(\frac{\alpha + \beta - D}{2})}{\Gamma(\frac{\alpha}{2})\Gamma(\frac{\beta}{2})\Gamma(D - \frac{\alpha + \beta}{2} + m + n)}$$

Then we can remove one integration and reduce the regularized three point function to two point functions \times some factor.

No additional singularities compared to derivative-free exchange!

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Two-vertex level result

The two-point function coefficients are given by

$$F_{(\mathbf{n}_{1}),(\mathbf{n}_{2});(\mathbf{m});(\mathbf{k})}^{(\mathbf{p}),r;(\mathbf{s}),t} = -\delta_{(n_{1}+n_{2}+m+k),(p+s+2r+2t)} f_{n_{1}n_{2}mk} \times v_{k,m+s} (1+2(m-t),1+2k)\beta^{(\mathbf{n}_{1})+(\mathbf{n}_{2})+(\mathbf{m})+(\mathbf{k})+(\mathbf{p})+(\mathbf{s})}\Big|_{D=3}$$

where,

$$\beta^{\mathbf{n}} = \int_{\hat{\mathbf{x}}^2 = 1} \mathrm{d}\hat{\mathbf{x}} \, \hat{\mathbf{x}}^{\mathbf{n}} = \frac{2^{-(n+1)} n! \pi^{D/2}}{\Gamma\left(\frac{D+n}{2}\right)} g^{\mathbf{n}},$$

with $g^{n} = 0$ for odd *n* while for even *n* it is the symmetrized product of metric tensors,

$$g^{\mathbf{n}}\mapsto \frac{1}{|S_n|}\sum_{p\in S_n}g^{\mu_{p(1)}\mu_{p(2)}}\cdots g^{\mu_{p(n-1)}\mu_{p(n)}}.$$

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Three-vertex level

The three-vertex contribution is given by,

$$H_{3V} = \int_{1} \int_{2} \int_{3} \left(3 \left[\check{D}_{1} \check{D}_{2} \check{D}_{12} \check{D}_{13} \check{D}_{23} \right] + 3 \left[\check{D}_{1} \check{D}_{2} \check{D}_{3} \check{D}_{12} \check{D}_{23} \right] \right) V_{1} V_{2} V_{3}$$
$$\check{D}_{xy} \equiv \sum_{\mathbf{n}} D_{xy}^{(\mathbf{n})} \check{s}^{(\mathbf{n})}$$

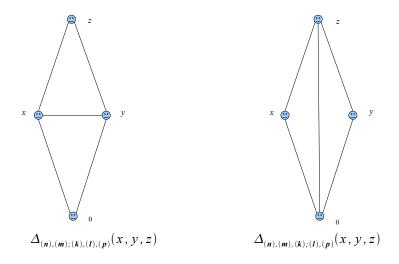
Therefore, we face to the evaluation of two scale factors,

$$\begin{split} \Delta_{(\mathbf{n}),(\mathbf{m});(\mathbf{k}),(\mathbf{l}),(\mathbf{p})}(x,y,z) &= \\ & \left[\partial_{(\mathbf{n})}\frac{1}{x}\partial_{(\mathbf{m})}\frac{1}{y}\partial_{(\mathbf{k})}\frac{1}{|x-y|}\partial_{(\mathbf{l})}\frac{1}{|x-z|}\partial_{(\mathbf{p})}^{y}\frac{1}{|y-z|}\right], \\ \Delta_{(\mathbf{n}),(\mathbf{m}),(\mathbf{k});(\mathbf{l}),(\mathbf{p})}(x,y,z) &= \left[\partial_{(\mathbf{n})}\frac{1}{x}\partial_{(\mathbf{m})}\frac{1}{y}\partial_{(\mathbf{k})}\frac{1}{z}\partial_{(\mathbf{l})}\frac{1}{|x-y|}\partial_{(\mathbf{p})}^{y}\frac{1}{|y-z|}\right]. \end{split}$$

...again duality relates these factors...

Three-vertex level

Graphically the Master diagrams are



Three-vertex level

Duality relates

$$\Delta_{(\mathbf{n}),(\mathbf{m}),(\mathbf{k});(\mathbf{l}),(\mathbf{p})}(x,y,z) = \Delta_{(\mathbf{n}),(\mathbf{l});(\mathbf{k}),(\mathbf{m}),(\mathbf{p})}(-z,-y,-x)$$

The general structure is given by

$$\begin{split} \Delta_{(\mathbf{n}),(\mathbf{m});(\mathbf{k}),(\mathbf{l}),(\mathbf{p})}(x,y,z) &= \\ \frac{1}{(4\pi)^5} \sum_{\substack{\mathbf{p},r\\\mathbf{s},t\\\mathbf{u},v}} F_{(\mathbf{n}),(\mathbf{m});(\mathbf{k}),(\mathbf{l}),(\mathbf{p})}^{(\mathbf{p})} \partial_{(\mathbf{p})} \partial^{2r} \delta(x) \partial_{(\mathbf{s})} \partial^{2t} \delta(y) \partial_{(\mathbf{u})} \partial^{2v} \delta(z), \end{split}$$

$$F_{(\mathbf{n}),(\mathbf{m});(\mathbf{k}),(\mathbf{l}),(\mathbf{q})}^{(\mathbf{p}),r;(\mathbf{s}),t;(\mathbf{u}),v} = f_{nmklq}^{(\mathbf{p}),r;(\mathbf{s}),t;(\mathbf{u}),v} \\ \times \int_{X} \int_{Y} \int_{Z} \left[\frac{\mathbf{x}^{(\mathbf{n})+(\mathbf{p})}}{x^{1+2(n-r)}} \frac{\mathbf{y}^{(\mathbf{m})+(\mathbf{s})}}{y^{1+2(m-t)}} \frac{\mathbf{z}^{(\mathbf{k})+(\mathbf{u})}}{z^{1+2(k-v)}} \frac{(\mathbf{x}-\mathbf{z})^{(\mathbf{l})}}{|x-z|^{1+2l}} \frac{(\mathbf{y}-\mathbf{z})^{(\mathbf{q})}}{|y-z|^{1+2q}} \right]$$

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Three-vertex level results

Applying the chain rule twice, we can remove two integrations and reduce the four point integral to a two point one

$$\begin{bmatrix} \frac{\mathbf{x}^{(n)+(\mathbf{p})}}{x^{1+2(n-r)}} \frac{\mathbf{y}^{(m)+(\mathbf{s})}}{y^{1+2(m-t)}} \frac{\mathbf{z}^{(\mathbf{k})+(\mathbf{u})}}{z^{1+2(k-v)}} \frac{(\mathbf{x}-\mathbf{z})^{(\mathbf{l})}}{|\mathbf{x}-\mathbf{z}|^{1+2l}} \frac{(\mathbf{y}-\mathbf{z})^{(\mathbf{q})}}{|\mathbf{y}-\mathbf{z}|^{1+2q}} \end{bmatrix} = (-1)^{q+l} \mathbf{v}_{q,m+s} (1+2q, 1+2(m-t)) \mathbf{v}_{l,n+p} (1+2l, 1+2(n-r)) \\ \times \left[\int_{z} \frac{\mathbf{z}^{(n)+(m)+(\mathbf{k})+(\mathbf{l})+(\mathbf{q})+(\mathbf{s})+(\mathbf{p})+(\mathbf{u})}}{z^{5+2(n+m+k+l+q-r-t-v)-2D}} \right]$$

which we know how to evaluate! All in one

$$F_{(\mathbf{n}),(\mathbf{m});(\mathbf{k}),(\mathbf{l}),(\mathbf{q})}^{(\mathbf{p}),r;(\mathbf{s}),t;(\mathbf{u}),v} = \delta_{n+m+k+l+q,2(r+t+v)+5} f_{nmklq}^{(\mathbf{p}),r;(\mathbf{s}),t;(\mathbf{u}),v} (-1)^{q+l} \\ \times v_{q,m+s} (1+2q,1+2(m-t)) v_{l,n+p} (1+2l,1+2(n-r)) \\ \times \beta^{(\mathbf{n})+(\mathbf{m})+(\mathbf{k})+(\mathbf{l})+(\mathbf{q})+(\mathbf{s})+(\mathbf{p})+(\mathbf{u})} \Big|_{\substack{D=3\\ n+q-k+1+q,2(r+t+v)+5}}$$

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Summary of the computation

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$$\begin{split} \Delta_{2-\text{loop}} &= H_{1-\text{vertex}} + H_{2-\text{vertx}} + H_{3-\text{vertex}} \\ H_{1-\text{vertex}} &= -\frac{1}{3!(4\pi)^3} \sum_{\substack{n,m,k \\ r,s}} (-1)^r F_{(n),(m),(k)}^{(r),s} \partial_{(r)} \partial^{2s} \check{s}_{y0}^{(m)} \check{s}_{y0}^{(m)} \check{s}_{y0}^{(k)} (V_y) \Big|_{y=0} \,, \end{split}$$

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$$\begin{split} H_{2-\text{vertex}} &= \frac{1}{2(4\pi)^4} \left\{ \sum (-1)^{p+s} F^{(p)r;(s)t}_{(n_1)(n_2);(m);(k)}(\partial_{(p)}\partial^{2r})_x (\partial_{(s)}\partial^{2t})_y \check{s}^{(n_1)}_x \check{s}^{(n_2)}_x \check{s}^{(n_2)}_y \check{s}^{(m)}_{xy} \check{s}^{(k)}_{xy} \right. \\ &\left. + \frac{1}{2} \sum (-1)^{m+p+s} F^{(p)r;(s)t}_{(k_1)(k_2);(m);(n)}(\partial_{(p)}\partial^{2r})_x (\partial_{(s)}\partial^{2t})_y \check{s}^{(n)}_x \check{s}^{(n_2)}_x \check{s}^{(m)}_y \check{s}^{(k_1)}_{xy} \check{s}^{(k_2)}_{xy} \right\} \left. V_x V_y \right|_{x=y=0} \end{split}$$

$$\begin{split} H_{3-\text{vertex}} &= -\frac{1}{2(4\pi)^5} \left\{ (-1)^{p+r+s} F_{(1),(2);(12),(13),(23)}^{(p),r;(s),t;(u),\nu} (\partial_{(p)}\partial^{2r})_1 (\partial_{(s)}\partial^{2t})_2 (\partial_{(u)}\partial^{2\nu})_3 \check{s}_1 \check{s}_2 \check{s}_{12} \check{s}_{13} \check{s}_{23} \right. \\ & \left. + (-1)^p F_{(1),(12);(2),(3),(23)}^{(p),r;(s),t;(u),\nu} (\partial_{(p)}\partial^{2r})_1 (\partial_{(s)}\partial^{2t})_2 (\partial_{(u)}\partial^{2\nu})_3 \check{s}_1 \check{s}_2 \check{s}_{12} \check{s}_{3} \check{s}_{23} \right\} V_1 V_2 V_3 |_{1=2=3=0} \end{split}$$

Corneliu Sochichiu (SKKU, Suwon) SQS'11: July 18, 2011 37 / 39 A faster way to obtain the dilatation operator?

Alternatively, consider the dilatation operator as Nöther charge corresponding to classical dilatations:

- classical dimension \longmapsto mass
- The large mass limit \longleftrightarrow perturbative expansion of the dilatation operator
- Indeed, the massive Yang–Mills mechanics reproduces the one-loop dilatation operator in the scalar sector of $\mathcal{N}=4$ SYM

Conclusion & Outlook

- Starting from a renormalizable theory one can obtain a model for which the (imaginary) time evolution coincides with RG-flows of given theory
- At least at the one-loop level the same result can be obtained by a slow roll limit of a massive extension of the model
- The approach is purely constructive, we didn't prove any existence theorem, positivity of the norms, unitarity etc.
- In the case of conformal theories the scheme coincides with the standard AdS/CFT correspondence
- For a general renormalizable gauge theory the large N limit is expected to lead to a *local* geometrical model
- Better parametrization for the LGICO would do a better job