Stringy Differential Geometry, beyond Riemann

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Stringy Differential Geometry, beyond Riemann

- In Riemannian geometry, the fundamental object is the metric, $g_{\mu\nu}$.
- String theory puts $g_{\mu\nu}$, $B_{\mu\nu}$ and ϕ on an equal putting.
- This may suggests the existence of a veiled unifying description of them, beyond Riemann.

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in collaboration with Imtak Jeon and Kanghoon Lee

Differential geometry with a projection: Application to double field theory

JHEP 1104:014 (2011),

arXiv:1011.1324

Double field formulation of Yang-Mills theory

Phys. Lett. B 701:260 (2011), arXiv:1102.0419

Stringy differential geometry, beyond Riemann

arXiv: 1105.6294

- guides the structure of Lagrangians.
- organizes the physical laws into simple forms.
- for example, in Maxwell theory,
 - U(1) gauge symmetry forbids $m^2 A_{\mu} A^{\mu}$
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Essence of Riemannian geometry

- Diffeomorphism: $\partial_{\mu} \longrightarrow \nabla_{\mu} = \partial_{\mu} + \Gamma_{\mu}$
- $\nabla_{\lambda}g_{\mu\nu} = 0 \longrightarrow \Gamma^{\lambda}_{\mu\nu} = \frac{1}{2}g^{\lambda\rho}(\partial_{\mu}g_{\nu\rho} + \partial_{\nu}g_{\mu\rho} \partial_{\rho}g_{\mu\nu})$
- Curvature: $[\nabla_{\mu}, \nabla_{\nu}] \longrightarrow R_g$.

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• $g_{\mu\nu}, B_{\mu\nu}, \phi$ are on an equal footing completing the massless sector.

• Low energy effective action of them:

$$S_{\rm eff.} = \int dx^D \sqrt{-g} e^{-2\phi} \left(R_g + 4 \partial_\mu \phi \partial^\mu \phi - \frac{1}{12} H_{\lambda\mu\nu} H^{\lambda\mu\nu} \right)$$

• Diffeomorphism and one-form gauge symmetry are manifest

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• Redefine the dilaton,

$$e^{-2d} = \sqrt{-g}e^{-2\phi}$$

• Set a $2D\times 2D$ symmetric matrix,

$$\mathcal{H}_{AB}=\left(egin{array}{cc} g^{-1}&-g^{-1}B\ Bg^{-1}&g-Bg^{-1}B\ \end{array}
ight)$$

• A, B, \dots : 2D-dimensional vector indices.

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• T-duality is realized by an $\mathsf{O}(D,D)$ rotation,

$$\mathcal{H}_{AB} \longrightarrow L_A{}^C L_B{}^D \mathcal{H}_{CD} , \qquad d \longrightarrow d ,$$

where

 $L \in \mathbf{O}(D, D)$.

• **O**(*D*, *D*) metric,

$$\mathcal{J}_{AB} := \left(\begin{array}{cc} 0 & 1 \\ & \\ 1 & 0 \end{array} \right)$$

freely raises or lowers the 2D -dimensional vector indices.

• Hull and Zwiebach , later with Hohm

$$S_{\mathrm{DFT}} = \int \mathrm{d}y^{2D} \; e^{-2d} \, \mathcal{R}(\mathcal{H}, d) \, ,$$

where

$$\begin{split} \mathcal{R}(\mathcal{H},d) &= \mathcal{H}^{AB} \left(4 \partial_A \partial_B d - 4 \partial_A d \partial_B d + \frac{1}{8} \partial_A \mathcal{H}^{CD} \partial_B \mathcal{H}_{CD} - \frac{1}{2} \partial_A \mathcal{H}^{CD} \partial_C \mathcal{H}_{BD} \right) \\ &+ 4 \partial_A \mathcal{H}^{AB} \partial_B d - \partial_A \partial_B \mathcal{H}^{AB} \,. \end{split}$$

• Spacetime is formally doubled, $y^{A} = (\tilde{x}_{\mu}, x^{\nu}).$

• Yet,

$$\frac{\partial}{\partial \tilde{x}_{\mu}} \equiv 0.$$

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$$\partial_A \partial^A \Phi = 2 rac{\partial^2}{\partial ilde{x}_\mu \partial x^\mu} \Phi \equiv 0 \,, \qquad \partial_A \Phi_1 \partial^A \Phi_2 \equiv 0 \,.$$

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Closed string

$$X_L(\sigma^+) = \frac{1}{2}(\mathbf{x} + \tilde{\mathbf{x}}) + \frac{1}{2}(\mathbf{p} + \mathbf{w})\sigma^+ + \cdots,$$

$$X_R(\sigma^-) = \frac{1}{2}(\mathbf{x} - \tilde{\mathbf{x}}) + \frac{1}{2}(\mathbf{p} - \mathbf{w})\sigma^- + \cdots.$$

• Under T-duality,

$$X_L + X_R \longrightarrow X_L - X_R$$

such that

$$(x, \tilde{x}, p, w) \longrightarrow (\tilde{x}, x, w, p).$$

• Level matching condition for the massless sector,

$$p \cdot w \equiv 0 \quad \Longleftrightarrow \quad \partial_A \partial^A = 2 \frac{\partial^2}{\partial \tilde{x}_\mu \partial x^\mu} \equiv 0 \,.$$

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• Thus, in the DFT formulation of the effective action by Hull, Zwiebach and Hohm, the O(D, D) T-duality structure is manifest.

What about the diffeomorphism and the one-form gauge symmetry?

• Thus, in the DFT formulation of the effective action by Hull, Zwiebach and Hohm, the O(D, D) T-duality structure is manifest.

• What about the diffeomorphism and the one-form gauge symmetry?

Diffeomorphism & one-form gauge symmetry

• Introduce a unifying parameter,

$$\boldsymbol{X}^{\boldsymbol{A}} = (\boldsymbol{\Lambda}_{\boldsymbol{\mu}}, \boldsymbol{\delta} \boldsymbol{x}^{\boldsymbol{\nu}})$$

• Unifying transformation rule, upon the level matching constraint,

$$\begin{split} \delta_{X}\mathcal{H}_{AB} &\equiv X^{C}\partial_{C}\mathcal{H}_{AB} + 2\partial_{[A}X_{C]}\mathcal{H}^{C}{}_{B} + 2\partial_{[B}X_{C]}\mathcal{H}_{A}{}^{C} \,, \\ \delta_{X}\left(e^{-2d}\right) &\equiv \partial_{A}\left(X^{A}e^{-2d}\right) \,. \end{split}$$

• In fact, these coincide with the generalized Lie derivative,

$$\delta_X \mathcal{H}_{AB} = \hat{\mathcal{L}}_X \mathcal{H}_{AB}, \qquad \qquad \delta_X(e^{-2d}) = \hat{\mathcal{L}}_X(e^{-2d}) = -2(\hat{\mathcal{L}}_X d)e^{-2d}.$$

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Generalized Lie derivative

• Definition, Siegel, Courant, Grana ...

$$\hat{\mathcal{L}}_X T_{A_1 \cdots A_n} := X^B \partial_B T_{A_1 \cdots A_n} + \omega \partial_B X^B T_{A_1 \cdots A_n} + \sum_{i=1}^n (\partial_{A_i} X_B - \partial_B X_{A_i}) T_{A_1 \cdots A_{i-1}}{}^B_{A_{i+1} \cdots A_n}.$$

• cf. ordinary one,

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• Commutator of the generalized Lie derivatives,

$$[\hat{\mathcal{L}}_X, \hat{\mathcal{L}}_Y] \equiv \hat{\mathcal{L}}_{[X,Y]_{\mathsf{C}}},$$

where $[X, Y]_{c}$ denotes the Courant bracket,

$$[X, Y]_{c}^{A} := X^{B} \partial_{B} Y^{A} - Y^{B} \partial_{B} X^{A} + \frac{1}{2} Y^{B} \partial^{A} X_{B} - \frac{1}{2} X^{B} \partial^{A} Y_{B}$$

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Diffeomorphism & one-form gauge symmetry

• Brute force computation shows that

$$\begin{split} \hat{\mathcal{L}}_{X}\mathcal{H}_{AB} &\equiv X^{C}\partial_{C}\mathcal{H}_{AB} + 2\partial_{[A}X_{C]}\mathcal{H}^{C}{}_{B} + 2\partial_{[B}X_{C]}\mathcal{H}_{A}{}^{C} \,, \\ \hat{\mathcal{L}}_{X}\left(e^{-2d}\right) &\equiv \partial_{A}\left(X^{A}e^{-2d}\right) \,, \end{split}$$

are symmetry of the action by Hull, Zwiebach and Hohm,

$$S_{\rm DFT} = \int \mathrm{d} y^{2D} \, e^{-2d} \, \mathcal{R}(\mathcal{H},d) \, , \label{eq:SDFT}$$

where

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• What is the underlying geometry?

- treats the three objects of the massless sector in a unified manner,
- manifests not only diffeomorphism and one-form gauge symmetry but also O(D, D) T-duality,
- and enables us to rewrite the low energy effective action of them as a single term,

$$\mathsf{S}_{ ext{eff.}} = \int \mathrm{d} x^{D} \; e^{-2d} \, \mathcal{H}^{AB} \mathsf{S}_{AB} \, \mathcal{H}^{AB}$$

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• Motivated by the observation that,

$$\mathcal{H}=\left(egin{array}{ccc} g^{-1}&-g^{-1}B\ Bg^{-1}&g-Bg^{-1}B\ \end{array}
ight)$$

is of the most general form to satisfy

$$\mathcal{H}_{A}{}^{C}\mathcal{H}_{C}{}^{B}=\delta_{A}{}^{B}, \qquad \mathcal{H}_{AB}=\mathcal{H}_{BA},$$

and the upper left $D \times D$ block of $\mathcal H$ is non-degenerate,

• we focus on a symmetric projection,

$$P_A{}^B P_B{}^C = P_A{}^C \qquad P_{AB} = P_{BA},$$

which is related to \mathcal{H} by

$$P_{AB} = \frac{1}{2} (\mathcal{J}_{AB} + \mathcal{H}_{AB}).$$

• Motivated by the observation that,

$$\mathcal{H}=\left(egin{array}{cc} g^{-1}&-g^{-1}B\ Bg^{-1}&g-Bg^{-1}B\end{array}
ight)$$

is of the most general form to satisfy

$$\mathcal{H}_{A}{}^{C}\mathcal{H}_{C}{}^{B}=\delta_{A}{}^{B}, \qquad \mathcal{H}_{AB}=\mathcal{H}_{BA},$$

and the upper left $D \times D$ block of \mathcal{H} is non-degenerate,

• we focus on a symmetric projection,

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as for the unifying description of the massless modes $(cf. \nabla_{\lambda} g_{\mu\nu} = 0 \text{ in Riemannian geometry}).$

• Further we require,

$$\Gamma_{CAB} + \Gamma_{CBA} = 0$$
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• Then, we may replace ∂_A by ∇_A in $\hat{\mathcal{L}}_X$ and also in $[X, Y]^A_c$,

$$\begin{aligned} \hat{\mathcal{L}}_X T_{A_1 \cdots A_n} &= X^B \nabla_B T_{A_1 \cdots A_n} + \omega \nabla_B X^B T_{A_1 \cdots A_n} + \sum_{i=1}^n 2 \nabla_{[A_i} X_{B]} T_{A_1 \cdots A_{i-1}}{}^B_{A_{i+1} \cdots A_n} \,, \\ [X, Y]^A_{\mathbf{C}} &= X^B \nabla_B Y^A - Y^B \nabla_B X^A + \frac{1}{2} Y^B \nabla^A X_B - \frac{1}{2} X^B \nabla^A Y_B \,. \end{aligned}$$

• cf. In Riemannian geometry, torsion free condition implies

 $\mathcal{L}_X T_{\mu_1 \cdots \mu_n} = X^{\nu} \nabla_{\nu} T_{\mu_1 \cdots \mu_n} + \omega \nabla_{\nu} X^{\nu} T_{\mu_1 \cdots \mu_n} + \sum_{i=1}^n \nabla_{\mu_i} X^{\nu} T_{\mu_1 \cdots \mu_{i-1} \nu \mu_{i+1} \cdots \mu_n} ,$ $[X, Y]^{\mu} = X^{\nu} \nabla_{\nu} Y^{\mu} - Y^{\nu} \nabla_{\nu} X^{\mu} .$ • Then, we may replace ∂_A by ∇_A in $\hat{\mathcal{L}}_X$ and also in $[X, Y]^A_c$,

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• Explicitly, the connection is

$$\Gamma_{CAB} = 2(P\partial_C P\bar{P})_{[AB]} + 2(\bar{P}_{[A}{}^D\bar{P}_{B]}{}^E - P_{[A}{}^DP_{B]}{}^E)\partial_D P_{EC}$$
$$-\frac{4}{D-1}(\bar{P}_{C[A}\bar{P}_{B]}{}^D + P_{C[A}P_{B]}{}^D)(\partial_D d + (P\partial^E P\bar{P})_{[ED]}).$$

where \bar{P} is the complementary projection,

$$\bar{P} = \frac{1}{2}(1-\mathcal{H})$$
.

• Further, we set

$$\begin{split} \mathcal{P}_{CAB}{}^{DEF} &:= P_{C}{}^{D}P_{[A}{}^{[E}P_{B]}{}^{F]} + \frac{2}{D-1}P_{C[A}P_{B]}{}^{[E}P^{F]D} , \\ \bar{\mathcal{P}}_{CAB}{}^{DEF} &:= \bar{P}_{C}{}^{D}\bar{P}_{[A}{}^{[E}\bar{P}_{B]}{}^{F]} + \frac{2}{D-1}\bar{P}_{C[A}\bar{P}_{B]}{}^{[E}\bar{P}^{F]D} , \end{split}$$

which satisfy

$$\begin{split} \mathcal{P}_{CABDEF} &= \mathcal{P}_{DEFCAB} = \mathcal{P}_{C[AB]D[EF]} \;, \\ \mathcal{P}_{CAB}^{DEF} \mathcal{P}_{DEF}^{GHI} &= \mathcal{P}_{CAB}^{GHI} \;, \\ \mathcal{P}^{A}_{ABDEF} &= 0 \;, \quad \mathcal{P}^{AB} \mathcal{P}_{ABCDEF} = 0 \;, \quad \mathrm{etc.} \end{split}$$

• The connection belongs to the kernel of these rank six-projectors - uniqueness

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and

$$(\delta_X - \hat{\mathcal{L}}_X) \nabla_C T_{A_1 \cdots A_n} \equiv \sum_i 2(\mathcal{P} + \bar{\mathcal{P}})_{CA_i} \partial_F \partial_{[D} X_{E]} T_{\cdots B \cdots}.$$

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• However, the characteristic property of our derivative, ∇_A , is that, combined with the projections, it can generate various O(D, D) and double-gauge covariant quantities:

$$\begin{split} & \mathcal{P}_{C}{}^{D}\bar{\mathcal{P}}_{A_{1}}{}^{B_{1}}\bar{\mathcal{P}}_{A_{2}}{}^{B_{2}}\cdots\bar{\mathcal{P}}_{A_{n}}{}^{B_{n}}\nabla_{D}\mathcal{T}_{B_{1}B_{2}\cdots B_{n}}, \\ & \bar{\mathcal{P}}_{C}{}^{D}\mathcal{P}_{A_{1}}{}^{B_{1}}\mathcal{P}_{A_{2}}{}^{B_{2}}\cdots\mathcal{P}_{A_{n}}{}^{B_{n}}\nabla_{D}\mathcal{T}_{B_{1}B_{2}\cdots B_{n}}, \\ & \mathcal{P}^{AB}\nabla_{A}\mathcal{T}_{B}, \qquad \bar{\mathcal{P}}^{AB}\nabla_{A}\mathcal{T}_{B}, \\ & \mathcal{P}^{AB}\bar{\mathcal{P}}_{C_{1}}{}^{D_{1}}\cdots\bar{\mathcal{P}}_{C_{n}}{}^{D_{n}}\nabla_{A}\nabla_{B}\mathcal{T}_{D_{1}\cdots D_{n}}, \\ & \bar{\mathcal{P}}^{AB}\mathcal{P}_{C_{1}}{}^{D_{1}}\cdots\mathcal{P}_{C_{n}}{}^{D_{n}}\nabla_{A}\nabla_{B}\mathcal{T}_{D_{1}\cdots D_{n}}. \end{split}$$

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• The usual curvature,

$$R_{CDAB} = \partial_A \Gamma_{BCD} - \partial_B \Gamma_{ACD} + \Gamma_{AC}{}^E \Gamma_{BED} - \Gamma_{BC}{}^E \Gamma_{AED} \,,$$

satisfying

$$[\nabla_A, \nabla_B] T_{C_1 C_2 \cdots C_n} = -\Gamma_{DAB} \nabla^D T_{C_1 C_2 \cdots C_n} + \sum_{i=1}^n R_{C_i DAB} T_{C_1 \cdots C_{i-1}} {}^D_{C_{i+1} \cdots C_n},$$

is NOT double-gauge covariant,

$$\delta_X R_{ABCD} \neq \hat{\mathcal{L}}_X R_{ABCD}$$
.

Image: A matrix and a matrix

• Instead, we define, as for a key quantity in our formalism,

$$S_{ABCD} := \frac{1}{2} \left(\mathcal{R}_{ABCD} + \mathcal{R}_{CDAB} - \Gamma^{E}_{AB} \Gamma_{ECD} \right) \,.$$

• This is related to a commutator,

$$P_I^{A} \bar{P}_J^{B} [\nabla_A, \nabla_B] T_C \equiv 2 P_I^{A} \bar{P}_J^{B} S_{CDAB} T^D.$$

• It can be shown, by brute force computation, to meet

• just like the Riemann curvature,

$$S_{ABCD} = \frac{1}{2}(S_{[AB][CD]} + S_{[CD][AB]}) \equiv S_{\{ABCD\}}, \qquad S_{A[BCD]} = 0,$$

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$$P_{I}^{A}P_{J}^{B}\bar{P}_{K}^{C}\bar{P}_{L}^{D}S_{ABCD} \equiv 0, \qquad P_{I}^{A}\bar{P}_{J}^{B}P_{K}^{C}\bar{P}_{L}^{D}S_{ABCD} \equiv 0, \quad etc.$$

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• Under the double-gauge transformations, we get

$$(\delta_X - \hat{\mathcal{L}}_X) S_{ABCD} \equiv 4 \nabla_{\{A} \left[(\mathcal{P} + \bar{\mathcal{P}})_{BCD} \right]^{EFG} \partial_E \partial_{[F} X_{G]} .$$

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- Nevertheless, contracting indices we can obtain covariant quantities.

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Covariant curvature

• Double-gauge covariant rank two-tensor,

$$P_I^A \overline{P}_J^B S_{AB}$$
.

• Double-gauge covariant scalar,

$$\mathcal{H}^{AB}S_{AB}$$
 .

In the above, we set

$$S_{AB} = S_{BA} := S^C_{ACB},$$

which turns out to be traceless,

$$S^{A}_{A} \equiv 0$$
.

• Especially, the covariant scalar constitutes the effective action as

$$\mathcal{H}^{AB}S_{AB}\equiv R_g+4\Box\phi-4\partial_\mu\phi\partial^\mu\phi-rac{1}{12}H_{\lambda\mu
u}H^{\lambda\mu
u}$$
 .

• It also agrees with Hull, Zwiebach and Hohm,

$$\begin{aligned} \mathcal{H}^{AB} S_{AB} &\equiv \quad \mathcal{H}^{AB} \left(4 \partial_A \partial_B d - 4 \partial_A d \partial_B d + \frac{1}{8} \partial_A \mathcal{H}^{CD} \partial_B \mathcal{H}_{CD} - \frac{1}{2} \partial_A \mathcal{H}^{CD} \partial_C \mathcal{H}_{BD} \right) \\ &+ 4 \partial_A \mathcal{H}^{AB} \partial_B d - \partial_A \partial_B \mathcal{H}^{AB} \,. \end{aligned}$$

• Under arbitrary infinitesimal transformations of the dilaton and the projection, we get

$$\delta S_{ABCD} = \nabla_{[A} \delta \Gamma_{B]CD} + \nabla_{[C} \delta \Gamma_{D]AB},$$

where explicitly

$$\begin{split} \delta\Gamma_{CAB} &= 2P_{[A}^{\ D}\bar{P}_{B]}^{\ E}\nabla_{C}\delta P_{DE} + 2(\bar{P}_{[A}^{\ D}\bar{P}_{B]}^{\ E} - P_{[A}^{\ D}P_{B]}^{\ E})\nabla_{D}\delta P_{EC} \\ &- \frac{4}{D-1}(\bar{P}_{C[A}\bar{P}_{B]}^{\ D} + P_{C[A}P_{B]}^{\ D})(\partial_{D}\delta d + P_{E[G}\nabla^{G}\delta P_{D]}^{E}) \\ &- \Gamma_{FDE}\,\delta(\mathcal{P}+\bar{\mathcal{P}})_{CAB}^{\ FDE}\,. \end{split}$$

• With $\nabla_A d = 0$, from the manipulation,

$$\delta S_{\mathrm{eff.}} \equiv \int \mathrm{d}y^{2D} 2e^{-2d} \left(\delta P^{AB} S_{AB} - \delta d \, \mathcal{H}^{AB} S_{AB}
ight) \, ,$$

and the relation,

$$\delta P = P \delta P \bar{P} + \bar{P} \delta P P,$$

it is now very easy to derive the equations of motion:

$$P_{(I}{}^{A}\bar{P}_{J)}{}^{B}S_{AB} = 0, \qquad \mathcal{H}^{AB}S_{AB} = 0.$$

Double-vielbein

• \mathcal{J}_{AB} and \mathcal{H}_{AB} can be simultaneously diagonalized,

$$\begin{aligned} \mathcal{J} &= \left(\begin{array}{cc} \mathbf{V} & \mathbf{\bar{V}} \end{array} \right) \left(\begin{array}{cc} \eta^{-1} & \mathbf{0} \\ \mathbf{0} & -\bar{\eta} \end{array} \right) \left(\begin{array}{cc} \mathbf{V} & \mathbf{\bar{V}} \end{array} \right)^t, \\ \mathcal{H} &= \left(\begin{array}{cc} \mathbf{V} & \mathbf{\bar{V}} \end{array} \right) \left(\begin{array}{cc} \eta^{-1} & \mathbf{0} \\ \mathbf{0} & \bar{\eta} \end{array} \right) \left(\begin{array}{cc} \mathbf{V} & \mathbf{\bar{V}} \end{array} \right)^t. \end{aligned}$$

Here η and $\bar{\eta}$ are two copies of the *D*-dimensional Minkowskian metric. Both *V* and \bar{V} are $2D \times D$ matrices which we name 'double-vielbein '.

• They must satisfy

$$\begin{split} &V = PV, \qquad V\eta^{-1}V^t = P, \qquad V^t \mathcal{J} V = \eta, \quad V^t \mathcal{J} \bar{V} = 0, \\ &\bar{V} = \bar{P}\bar{V}, \qquad \bar{V}\bar{\eta} \ \bar{V}^t = -\bar{P}, \qquad \bar{V}^t \mathcal{J} \bar{V} = -\bar{\eta}^{-1}. \end{split}$$

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$$\begin{split} \mathbf{V} &= \mathbf{P}\mathbf{V} \,, \qquad \mathbf{V}\eta^{-1}\mathbf{V}^t = \mathbf{P} \,, \qquad \mathbf{V}^t\mathcal{J}\mathbf{V} = \eta \,, \qquad \mathbf{V}^t\mathcal{J}\bar{\mathbf{V}} = 0 \,, \\ \bar{\mathbf{V}} &= \bar{\mathbf{P}}\bar{\mathbf{V}} \,, \qquad \bar{\mathbf{V}}\bar{\eta}\,\bar{\mathbf{V}}^t = -\bar{\mathbf{P}} \,, \qquad \bar{\mathbf{V}}^t\mathcal{J}\bar{\mathbf{V}} = -\bar{\eta}^{-1} \,. \end{split}$$

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• Double-vielbein is of the following general form, Siegel, Hassan

$$V_{Am} = \frac{1}{\sqrt{2}} \begin{pmatrix} (e^{-1})_m^{\mu} \\ (B+e)_{\nu m} \end{pmatrix}, \quad \bar{V}_A{}^{\bar{n}} = \frac{1}{\sqrt{2}} \begin{pmatrix} (\bar{e}^{-1})^{\bar{n}\mu} \\ (\bar{B}-\bar{e})_{\nu}{}^{\bar{n}} \end{pmatrix}.$$

• Here, $e_{\mu}{}^{m}$ and $\bar{e}_{\nu}{}^{\bar{n}}$ are two copies of the *D*-dimensional vielbein corresponding to the same spacetime metric,

$$\mathbf{e}_{\mu}{}^{m}\mathbf{e}_{
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• We set $B_{\mu m} = B_{\mu \nu} (e^{-1})_m{}^{\nu}, \ \bar{B}_{\mu \bar{n}} = B_{\mu \nu} (\bar{e}^{-1})_{\bar{n}}{}^{\nu}, \ etc.$

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• We may identify $(B + e)_{\mu}{}^{m}$ and $(\bar{B} - \bar{e})_{\nu}{}^{\bar{n}}$ as two copies of the vielbein for the winding mode coordinate, \tilde{X}_{μ} , since

$$(B+e)_{\mu}{}^{m}(B+e)_{\nu m}=(ar{B}-ar{e})_{\mu}{}^{ar{n}}(ar{B}-ar{e})_{
uar{n}}=(g-Bg^{-1}B)_{\mu
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• Internal symmetry group is

$$SO(1, D-1) \times \overline{SO}(1, D-1)$$
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of which the former and the latter rotates each unbarred and barred small Roman alphabet index.

- O(D, D) acts only on the capital indices.
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- Hence, both V_{Am} and $\overline{V}_A{}^{\overline{n}}$ are $\mathbf{O}(D, D)$ vectors.

• Further, V_{Am} and $\bar{V}_A{}^{\bar{n}}$ are double-gauge covariant vectors,

$$\begin{split} \delta_X V_{Am} &\equiv X^B \partial_B V_{Am} + 2 \partial_{[A} X_{B]} V^B{}_m = \hat{\mathcal{L}}_X V_{Am} \,, \\ \delta_X \bar{V}_A{}^{\bar{n}} &\equiv X^B \partial_B \bar{V}_A{}^{\bar{n}} + 2 \partial_{[A} X_{B]} \bar{V}^{B\bar{n}} = \hat{\mathcal{L}}_X \bar{V}_A{}^{\bar{n}} \,. \end{split}$$

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- Double-vielbein can pull back the chiral and the anti-chiral 2D indices to the more familiar D-dimensional ones without losing any information, since it is an invertible process.
- We pull back the double-gauge covariant rank two-tensor to obtain,

$$S_{AB}V^{A}{}_{m}\bar{V}^{B}{}_{\bar{n}} = R_{m\bar{n}} + 2D_{m}D_{\bar{n}}\phi - \frac{1}{4}H_{m\mu\nu}H_{\bar{n}}^{\mu\nu} + (\partial^{\lambda}\phi)H_{\lambda m\bar{n}} - \frac{1}{2}\nabla^{\lambda}H_{\lambda m\bar{n}}.$$

• As expected, its symmetric and the anti-symmetric parts correspond to the equations of motion of the effective action for $g_{\mu\nu}$ and $B_{\mu\nu}$ respectively.

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• As expected, its symmetric and the anti-symmetric parts correspond to the equations of motion of the effective action for $g_{\mu\nu}$ and $B_{\mu\nu}$ respectively. • We may construct a rank four tensor:

$$R_{mnpq} + D_{(p}H_{q)mn} - \frac{1}{4}H_{mn}{}^rH_{pqr} - \frac{3}{4}H_{m[n}{}^rH_{pq]r},$$

which may provide a powerful tool to organize the higher derivative corrections to the effective action \longrightarrow Vanhove's talk

${\ensuremath{\bullet}}$ We postulate a vector potential, $\mathcal{V}_A,$ which is

- O(D, D) and double-gauge covariant,
- and transforms under non-Abelian gauge symmetry, $\mathbf{g} \in \mathbf{G}$,

$$\mathcal{V}_A \longrightarrow \mathbf{g} \mathcal{V}_A \mathbf{g}^{-1} - i(\partial_A \mathbf{g}) \mathbf{g}^{-1}$$
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• The usual field strength,

$$F_{AB} = \partial_A \mathcal{V}_B - \partial_B \mathcal{V}_A - i \left[\mathcal{V}_A, \mathcal{V}_B \right] \,,$$

is YM gauge covariant, but it is NOT double-gauge covariant,

$$\delta_X F_{AB} \neq \hat{\mathcal{L}}_X F_{AB}$$

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Application to Yang-Mills

• Instead, we consider with the semi-covariant derivative,

$$\mathcal{F}_{AB} := \nabla_A \mathcal{V}_B - \nabla_B \mathcal{V}_A - i \left[\mathcal{V}_A, \mathcal{V}_B \right] = \mathcal{F}_{AB} - \Gamma^C_{AB} \mathcal{V}_C \,.$$

• While this is neither YM gauge nor double-gauge covariant,

$$\mathcal{F}_{AB} \longrightarrow \mathbf{g} \mathcal{F}_{AB} \mathbf{g}^{-1} + i \Gamma^{C}{}_{AB} (\partial_{C} \mathbf{g}) \mathbf{g}^{-1} ,$$

$$\delta_{X} \mathcal{F}_{AB} \neq \hat{\mathcal{L}}_{X} \mathcal{F}_{AB} ,$$

• if projected properly, it can be made so,

$$P_{A}{}^{C}\bar{P}_{B}{}^{D}\mathcal{F}_{CD} \longrightarrow P_{A}{}^{C}\bar{P}_{B}{}^{D}g\mathcal{F}_{CD}g^{-1},$$

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That is to say, $P_A{}^C \bar{P}_B{}^D \mathcal{F}_{CD}$ is fully covariant with respect to

- **O**(*D*, *D*) T-duality
- Gauge symmetry
 - Double gauge = Diffeomorphism + one form gauge symmetry
 - Yang-Mills gauge

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• Our double field formulation of Yang-Mills action is

$$S_{\rm YM} = g_{\rm YM}^{-2} \int {\rm d}y^{2\text{D}} \; e^{-2\text{d}} \, {\rm Tr} \left(\textbf{\textit{P}}^{\text{AB}} \bar{\textbf{\textit{P}}}^{\text{CD}} \mathcal{F}_{\text{AC}} \mathcal{F}_{\text{BD}} \right) \,, \label{eq:SYM}$$

• Manifestly, O(D, D) T-duality, double-gauge and Yang-Mills gauge covariant.

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• Decompose the vector potential into chiral and anti-chiral ones,

$$\mathcal{V}_A = V_A^+ + V_A^- \,,$$

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• Turning off the \tilde{x} -dependence reduces the action to

$$S_{\rm YM} \equiv g_{\rm YM}^{-2} \int \mathrm{d}x^D \; \sqrt{-g} e^{-2\phi} \operatorname{Tr}\left(-\frac{1}{4} \hat{f}^{\mu\nu} \hat{f}_{\mu\nu}\right) \,,$$

where

$$\hat{f}_{\mu\nu} := f_{\mu\nu} - D_{\mu}\phi_{\nu} - D_{\nu}\phi_{\mu} + i[\phi_{\mu},\phi_{\nu}] + H_{\mu\nu\lambda}\phi^{\lambda},$$

and

$$\begin{aligned} \operatorname{Tr} \left(\hat{f}_{\mu\nu} \hat{f}^{\mu\nu} \right) &= \operatorname{Tr} \left(f_{\mu\nu} f^{\mu\nu} + 2 D_{\mu} \phi_{\nu} D^{\mu} \phi^{\nu} + 2 D_{\mu} \phi_{\nu} D^{\nu} \phi^{\mu} - [\phi_{\mu}, \phi_{\nu}] [\phi^{\mu}, \phi^{\nu}] \right. \\ &\left. + 2 i \, f_{\mu\nu} [\phi^{\mu}, \phi^{\nu}] + 2 \left(f^{\mu\nu} + i [\phi^{\mu}, \phi^{\nu}] \right) H_{\mu\nu\sigma} \phi^{\sigma} + H_{\mu\nu\sigma} H^{\mu\nu} {}_{\tau} \phi^{\sigma} \phi^{\tau} \right). \end{aligned}$$

• Similar to topologically twisted Yang-Mills, but differs in detail.

• Curved *D*-branes are known to convert adjoint scalars into one-form,

$$\phi^a \to \phi_\mu$$
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• Turning off the \tilde{x} -dependence reduces the action to

$$S_{\rm YM} \equiv g_{\rm YM}^{-2} \int \mathrm{d}x^D \; \sqrt{-g} e^{-2\phi} \operatorname{Tr}\left(-\frac{1}{4} \hat{f}^{\mu\nu} \hat{f}_{\mu\nu}\right) \,,$$

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- Supersymmetrization, Higher derivative corrections in progress.
- Application to 'doubled sigma model' and generalization to *M*-theory are of interest Ivanov, Hull, Berman, Perry, Bergshoeff
- Perhaps, our formalism may provide some clue to a new framework for string theory, beyond Riemann.

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Thank you.

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