Fuzzy Topology of Phase Space and Gauge Fields

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Motivations:

Study of geometric structures can be important for the construction

of quantum space-time

Axioms of Set theory and Topology are the basis

of any particular geometric structure

Examples:

Discrete space-time (Snyder, 1947)

Noncommutative geometry (Connes, 1991)

Sets, Topology and Geometry

Example: 1-dimensional Euclidian geometry is constructed on ordered set of elements $X = \{x_l\}$; x_l - points

$$\forall x_i, x_j \qquad x_i \leq x_j . or . x_j \leq x_i \qquad x_j \qquad x_j \qquad X$$

Partial ordered set - P



 u_1 , x_k are incomparable P elements

Fuzzy ordered set (foset) - $F = \{f_i\}$

 f_i - fuzzy points, (Zeeman, 1968)

$$f_i \sim f_k$$
, $w_{i,k} > 0$, $\Sigma w_{jk} = 1$

Example: $F_T = X \cup F$; $F = \{f_1\}$



Continuous fuzzy ordered sets

Foset F*= O*UP' 0x - is continious R1 = {xa} P'= {x: } i=1, N discrete set ∀x; ~ w;(x)≥0 ; Sw;(x)dx =1 x_i $w_i(x)$ $w_i \text{ support } \mathcal{O}_s^{\mathsf{x}}$ $\mathcal{O}_s^{\mathsf{x}} \in \mathcal{O}^{\mathsf{x}}$ VXaGOX, XII Xa ∀ A1, A2 € O3; Xi € A1 and Ki € A2 Topological structure of FX F' is nonprababilistic StRHerture!

Classical Mechanics particle is ordered point x(t) in Ox it's state: 1m3 = (x(+), x(+)) $\mathbf{x}(t)$ FUZZY Mechanics (FM) Particle is fuzzy point m(t) in OF Fuzzy state 1m3=(W(x,t),...?) $\mathcal{P} = \mathcal{Q}_1(x), \dots, \mathcal{Q}_n(x); \mathcal{Q}_n(x, x^{\prime}), \dots; \mathcal{Q}_n^{\prime\prime}(x, x^{\prime}, x^{\prime\prime})$ Evolution : $N(t)/m_{0} = |m(t)|_{3}$ Walk) m, wat minimal FM x

Fundamental laws of dynamics

a) Classical Mechanics: Hinimal action $S = \int_{q_1}^{q_2} L(q, q) dt - min$ q_1

Too complicated to be truly fundamental ?!

Fuzzy mechanics – space symmetry restoration as the general low of free motion

Global (and local) symmetries are very important in microphysics



Fuzzy *m* motion – topological diffusion

Low of free *m* evolution: space symmetry of *m* state is restored: *w₀(x)* → *const* at very large *t*Free *m* evolution *U(t)* : *w₀(x)* → *const*; as fast as possible
Problem: if |g }= w(x), then <*V_x*> = 0, for any *m* state |g}

Fuzzy (virtual) motion

Fuzzy state $g : m // \Delta_i$. and $m \parallel \Delta_{i+1}$... Even if dw(x,t) = 0, there is virtual *m* motion



m flow between Δ_i and $\Delta_2 : f(x_1, x_2) \sim dw(x_1) - dw(x_2)$ In the simple case, if $w(x_1) = w(x_2)$ then $f(x_1, x_2) = 0$,

New parameter $\alpha(x)$, it can result in effective w flow:

$$f(x_1, x_2) = \mathbf{a}(x_1) - \mathbf{a}(x_2) \neq \mathbf{0}$$

As the result *m* can move with $\langle V_x \rangle \neq 0$, if $\alpha(x) \neq const$



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New parameter $\alpha(x)$, it results in effective w flow:

$$f(x+dx, x) = \alpha(x+dx) - \alpha(x) \neq 0$$

m Velocity as the result of space symmetry violation for |g|

 $\alpha(x)$ is analog of quantum phase



\alpha(x) is analog of quantum phase

m particle's state $|g| = \{ w(x), \alpha(x) \}$ $\alpha(x)$ is analog of quantum phase

The problem: to find dynamical |g| representation g(x,t):

$$\frac{dg}{dt} = \hat{F}g$$

We have two degrees of freedom $g = \{ w(x), \alpha(x) \}$, it can be transferred to: g(x) = a(x) + ib(x), such that a,b = 0, if w(x) = 0this is symmetric g representation

a is 193 free parenteter



 $w_i(x) = \Sigma w_i \delta(x - x_i)$

12-2 - a ~ K12 - correlation w, and w2

 $if \ k_{13} = k_{12} + k_{23}$ Then $k_{ij} = phase \ d(\mathcal{X}_{ij}, \mathcal{X}_{j})$ $k \to \infty \ |g_{2}^{2} = \{w(x), d(x)^{2}, g(x), d(x)^{2}, g(x)^{2}, g(x), d(x)^{2}, g(x)^{2}, g(x$

g(x) → 0 ← us(x) → 0

193 = {w(x), d(x, x') - Bilocal, state !

 $g(z) = \{w(x), a(x)\} \xrightarrow{\rightarrow} g_1(x) \neq i g_2(x)$ CI $g(x,t_o) = c \delta(x-x_o)$ W(x,t) g(x)~ ZC: S(x-x;)! ×o g(+) = Útg(to) ; Út - ymitary Utitz=Uti-Utz - Ut= eift t Vt H - time independent Va - space shift; Va = e = > x for free motion [Va, Ut]=0 fourier transform: P(P,t) = (g(x,t) e dx $[\hat{V}_a, \hat{H}] = 0 \rightarrow \hat{H}_p = F(p)$ for g(x,t=0)=S(x-x0) > Q(Pit)=e-iF(pt tips

 $g(x,t) \rightarrow S(x-x_0)$ $t \rightarrow t_0 +$ $\int g(x,t_j) dx = 1$ g(x, t;) - &-sequence St; 3+ to $Z = \frac{Z}{f(t)} \quad ; \quad f(t) \to 0 \quad ; \quad g(x_1t) = \frac{e^{-i\beta(t)}}{f(t)}$ if $\int e^{i \beta(\frac{2}{d})} = 1 \neq O(\frac{4}{d})$ $M(p_it) = \int g(x_it) e^{ipx} dx = e^{i\Gamma(pf(t))}$ $\varphi(p_1t) = \eta(p_1t) \rightarrow e^{-iF(p)t} = e^{-i\Gamma(pf(t))}$ $\hat{H}_{p} = F(p) = \frac{p^{s}}{2m}; m_{0} > 0$ 5=2,4,--,21,... only S=2 gives w(x,t) \$0 ! X=00 $-i\frac{\partial g}{\partial t} = H_{og} = \frac{\vec{p}^2}{2m_0}g - \frac{Schzödinger}{Equation}$

 $H_0 = \frac{P^3}{2m_0} \qquad 3 = 2, 4, 6, \ldots 2n$ P(P,t) = e - i pst - g(x,t) $w(x,t) \neq 0$ $x \to \infty$ 5=4 5=2 $\omega \sim \frac{7}{(2z^2)^{\frac{1}{6}}}$ $S = 2 \rightarrow g_0 = \delta(x - x_0) \rightarrow g(x, t) = e^{-\frac{2x^2m}{t}}$ $H_{x} = \sum a_{i}g_{i}(x_{i}t); \quad -i\frac{\partial Y}{\partial t} = \frac{1}{2\pi}\frac{\partial^{2}}{\partial x^{2}}Y$ RF: M-200 Galilean Transform. C #00, FROM 4 Cinearity $-i\frac{\partial Y}{\partial x} = (\vec{a}\vec{p} + \vec{p}\vec{m}) Y$ 4-4-Spinor

 $|g_0^3 \sim w_0(x) = \frac{1}{2} S(x - x_1) + \frac{1}{2} S(x - x_2)$ Does 1903 include other parameters q:? X for 19x3 4x2 is undefined hence if we (x,t) is solution then w ((x, +) = w (x + a, +) is solution Va; - cosasao 50, 1903 has a - parameter in addition to wolk?

Interactions on Fuzzy Manifold m, M2 interactions Wo $m_2 \rightarrow \infty$ $G_2(x) \rightarrow 0$ W(E) Hint = Qi Q2 Bint Hint perturbs g(x,t) restoration of R3 symmetry by m free evolution g(x) ~ (u(x), do (x) } components -i 29 = -i 2 (Vir e id(x)) = (Ho + Hint) 9 $\left(\begin{array}{c} \frac{\partial \sqrt{u}}{\partial t} = \frac{\sqrt{u}}{\partial x} \begin{array}{c} \frac{\partial^2 d}{\partial x} + \frac{\partial \sqrt{u}}{\partial x} \\ \frac{\partial \sqrt{u}}{\partial x} = \frac{\partial^2 d}{\partial x} \end{array}\right) + \frac{\partial \sqrt{u}}{\partial x} \cdot \frac{\partial d}{\partial x}$ $\frac{\partial d}{\partial t} = \frac{1}{2m} \frac{\partial^2 w^{\frac{1}{2}}}{\partial x^2} - \frac{V w}{2m} \left(\frac{\partial d}{\partial x}\right)^2 + \hat{H}_{int}$ $\hat{H}_{int} = Q_{f} \cdot Q_{z} \cdot F(\boldsymbol{z}_{12}, t)$ De = (De)free + Qi Qe F(Erzgt)

* Hist = Q, Q, F(212) $\frac{\partial \mathcal{L}(x)}{\partial t} = \left(\frac{\partial \mathcal{L}(x)}{\partial t}\right) \int_{\text{Free}} + \varphi_1 \cdot \varphi_2 F(z_1 z)$ scee 1 Hint of K 20 Relativistic case mz m × $Q_2 \rightarrow J_4 \sim \left(\frac{Q_2}{V_{1-V_2}}, \frac{Q_2V}{V_{1-V_2}}\right)$ Hint ~ P2 F(Z12) -> An = {Ao(x), A(x)?

A.G.), A(x) ~ Q2 Q2V Then JRF'(V) ACA - A'(x)=0 for $m: \vec{p} \rightarrow \vec{P}' = \vec{P} - m\vec{v}$ hence: P -> P + QA(x) $\frac{\partial X}{\partial t} \rightarrow \frac{\partial R}{\partial t} + \frac{\partial R}{\partial t} + \frac{\partial X}{\partial t} \rightarrow \frac{\partial X}{\partial t} + \frac{\partial R}{\partial t} +$ $-i\frac{\partial Y}{\partial t} = \left[\vec{x}\left(\vec{p} + q,\vec{A}(x)\right) + \beta m + q,\vec{A}(x)\right)Y$ Local U(1) gauge invariance - QED

SU(2) Gauge Invariance $\Psi = \begin{pmatrix} \Psi_{i}(x) \\ \Psi_{i}(x) \end{pmatrix} = Vu(x) e^{i\lambda(x) + i\theta(x)\overline{\theta}} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $\alpha(x) \vec{\theta}(x)$ J & D 3 phase Parameters · R³ SU(2) $-i\frac{\partial \Psi}{\partial t} = -i\frac{\partial}{\partial t}\left(\operatorname{Vur} e^{i\frac{\partial}{\partial t} + \frac{\partial}{\partial t}} \left(\frac{i}{\partial t} \right) \right) = \frac{1}{2\pi} \frac{\partial^2}{\partial t} + \frac{1}{$ $\begin{cases} \frac{\partial \mathcal{A}(w)}{\partial t} = \left(\frac{\partial w}{\partial t}\right) scer \\ \frac{\partial \mathcal{A}(w)}{\partial t} = \left(\frac{\partial w}{\partial t}\right) scer \\ \frac{\partial \mathcal{A}(w)}{\partial t} = \frac{\partial \mathcal{A}(w)}{\partial t} \left(\frac{w}{\partial t} + \overline{\mathbf{G}}^{2}\right) free^{\frac{1}{2}H^{2}} dt$ Hint 2 Q. Q A (A,t) = \vec{s}_{0} \vec{s}_{2} \vec{s}_{1} \vec{s}_{2} \vec{s}_{1} \vec{s}_{2} \vec{s}_{1} \vec{s}_{2} \vec{s}_{2} \vec{s}_{1} \vec{s}_{2} \vec{s}_{1} \vec{s}_{2}

Conclusions

- 1. Fuzzy topology is the most simple and natural formalism for introduction of quantization into physical theory
- 2. Shroedinger equation is obtained from simple assumptions
- 3. Gauge invariance of fields corresponds to dynamics on fuzzy manifold

Fuzzy ERdered SEt - Foset FX FX~PX, but Yx; Z; > Wij 20 Example: F*= O*UP' Wij - - ! 30; 11 2; - Wij $\sum w_{ij} = 1$ · · · · · if 0x - is continueum?

Fuzzy Geometry is consistent theory (terman 1968 Ledson 1974)

Fuzzy points z: - are particles with uncertain coordinate z in 0x

Law of motion in Fuzzy Mechanics

a) Classical Mechanics: Minimal action $S = S = \int L(q_1 \dot{q}) dt - min$

b) Quantum Mechanics - Path Integral $S(\frac{1}{1}) q_2 = A(q_1, q_2) = e^{i \int_{-\infty}^{q_2} S[dq]}$ Y(t) = U1 4-



2 slits experiments W_ = 8/00 - \$ \$ 00 Stochastic mixture 4 Was い(えっきょ, も) L:= M ∈ A1. OR. M ∈ A2 ↔ g=9, . BR. 9=92 $U_c.(x_it) = w_i(x_it) + w_2(x_it)$ ∀ x, we(x,t)>0 42 Topologica C STRucture of Imoz x; X X-T+1 LEI=MEDI.and. MEDZ - LEALC = 0 $w_{F}(\mathbf{x},t) = w_{n}(\mathbf{x},t) + \kappa \left(w_{1}(\mathbf{x},t) + w_{2}(\mathbf{x},t) \right) \Rightarrow \kappa \simeq 0$ I x; , W=(x,t)=0

n=2: W1,2(x,t) - Schwartz distributions $(w_{1,2}(x,t) \neq 0)$ $x \rightarrow \pm \infty$ X ... - undefined Z MEAL, and MEAZ; So $w_3(x_it) = w_n(x_it) \Rightarrow \exists x_j ; w(x_j_2t) = 0$ Wn (x,t) = 0 x = ±00 S.A Xi+1 if us (x, t) is solution, I - undefined then ws'(x,t) = ws(x+a,t) is also solution ta, - 20 5 a 5 a

Fuzzy mechanics – space symmetry restoration as the general low of free motion



