

Plan

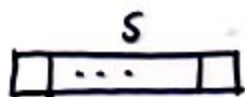
I.

1. Introduction
2. Gravity as a gauge theory
- > 3. Young tableaux and Howe duality
4. Frame-like formulation of free higher-spin dynamics
5. $(A)dS_d$ higher-spin algebras
- > 6. Star product

II.

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 - a. example of gravity
 - b. any spin (free theory)
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11. Nonlinear higher spin equations in detail
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Higher Spin Gauge Fields



C. Fronsdal (1978)

$$\varphi_{n_1 \dots n_s}(x)$$

$$\varphi^m_m{}^\tau{}_{n_5 \dots n_s} = 0$$

HS symmetry

$$\delta \varphi_{n_1 \dots n_s}(x) = \partial_{[n_1} \varepsilon_{n_2 \dots n_s]}(x) \quad \varepsilon^n{}_{n m_3 \dots m_{s-1}} = 0$$

Invariant action

$$\begin{aligned}
 S^s = & \frac{(-1)^s}{2} \int d^d x \left\{ \partial_n \varphi_{m_1 \dots m_s} \partial^n \varphi^{m_1 \dots m_s} \right. \\
 & - \frac{1}{2} s(s-1) \partial_n \varphi^\tau{}_{m_3 \dots m_s} \partial^n \varphi^\kappa{}_{m_3 \dots m_s} \\
 & + s(s-1) \partial_n \varphi^\tau{}_{m_3 \dots m_s} \partial_\kappa \varphi^{n \kappa m_3 \dots m_s} \\
 & - s \partial_n \varphi^n{}_{m_2 \dots m_s} \partial_2 \varphi^\tau{}_{m_2 \dots m_s} \\
 & \left. - \frac{1}{4} s(s-2)(s-2) \partial_n \varphi^\tau{}_{m_4 \dots m_s} \partial_p \varphi^\sigma{}_{m_4 \dots m_s} \right\}
 \end{aligned}$$

$s=1$ Maxwell

$s=2$ Einstein

$s>2$ Unifying gauge principle ?!

HS fermions are described

analogously

Fang, Fronsdal (78)

Motivation

HS symmetries

$$\text{SUGRA: } \quad d \leq 11 \quad \Leftrightarrow \quad s \leq 2 \\ (\mathcal{N} \leq 8)$$

Superstring:

Stueckelberg symmetries as spontaneously broken HS symmetries

$$\delta \varphi_{n_1, n_2, n_3} = \partial_{n_1} \epsilon_{n_2, n_3 \dots} + \partial_{n_2} \epsilon_{n_1, n_3 \dots} + \dots$$

$$\delta \zeta_{n_1, n_2 \dots} = \epsilon_{n_1, n_2 \dots}$$

Stueckelberg fields

HS gauge theory as a symmetric phase of superstring !!

Sundborg-Witten limit

$$\lambda = g^2 N \rightarrow 0$$

$$l_{\text{str}}^2 \Lambda_{\text{dS}} \rightarrow \infty$$

Sundborg (2002)
Witten (2002)
Klebanov, Polyakov (2002)

Infinite set of currents in the conformal boundary theory \sim HS symmetries in the bulk !!

Anomalous currents - broken HS symmetries

Higher Spin Problem

To find a nonlinear HS gauge theory

- Correct free field limit
- Unbroken HS gauge symmetries
- Non-Abelian global HS symmetry of a vacuum solution

Difficulties

- Coleman-Mandula S-matrix argument
Coleman, Mandula (1967)
- HS-gravity interaction problem

Aragon, Deser (1979)

$$\partial_n \rightarrow D_n = \partial_n - \Gamma_n \quad [D_n, D_m] = R_{nm} \dots$$

$$\delta \varphi_{nm\dots} \rightarrow D_n \epsilon_{m\dots}$$

$$\delta S = \int R \dots D \dots \varphi \dots \epsilon \dots \neq 0 \quad ?!$$

↑
Weyl tensor for $s > 2$

Resolution

- Some consistent cubic HS interactions (no gravity)
A. Bengtsson, I. Bengtsson, L. Brink (1983)
Berends, Burgers, van Dam (1984, 1985)
- $\Lambda \neq 0$ allows consistent HS theory with gravity included
E. S. Fradkin, M. V. (1987)

AdS background:

- resolves Coleman - Mandula argument (no S-matrix in AdS)
- allows new interactions with dimensionful coupling constant built from Λ :
higher spins - higher derivatives
- fits the AdS/CFT conjecture

AdS Background and HS Interactions

$$R_{nm,uv} = R_{nm,uv} - \Lambda (g_{nu} g_{mv} - g_{nv} g_{mu})$$

$$(A) dS: R_{nm,uv} = 0$$

Fluctuations

$R_{nm,uv}$ is small

$$R_{nm,uv} = \Lambda (g_{nu} g_{mv} - g_{nv} g_{mu}) + o(1)$$

$$[D_n, D_m] \sim \Lambda \neq 0(1)$$

Action

$$S = S_2^{cov} + \Delta S^S$$

$$\Delta S^S = \sum_{\substack{p, q \\ p+q \leq S}} \Lambda^{-\left[\frac{p+q}{2}\right]} \underbrace{(D)^p \varphi (D)^q \varphi R}_{\text{cubic}}$$

$$\delta \varphi = D \varepsilon + R^{HS} \varepsilon$$

$$\delta S^S = O(\varphi^3)$$

Coefficients of ΔS^S are fixed uniquely modulo total derivatives

Towards HS Algebras

HS algebras are certain \ast -product algebras (algebras of oscillators)

M.V. (1988)

- AdS subalgebra (\sim vacuum solution)
- Infinite towers of spins
- Higher derivatives in interactions as a result of \ast -product quantum-mechanical nonlocality

How to find?

HS gauge fields are 1-form connections for a HS algebra cf

Lower spin examples

$S = 1$ A_n $n=0, 1, \dots, d-1$ 1-form

$S = 3/2$ $\Psi_{n\alpha}$ 1-form carrying a spinor index α

$S = 2$

$$g_{nm} = g_{mn} \Rightarrow e_n^\alpha dx^n$$

$$\square \Rightarrow \square \otimes \square = \square \oplus \square$$

general symm. asymm.

Antisymmetric part \square ($e_{n\alpha} - e_{\alpha n}$)

is unphysical and should be pure gauge: extra gauge symmetry

with antisymmetric gauge parameters

$$\xi^{\alpha\beta}(x) = -\xi^{\beta\alpha}(x) \quad \delta e_n^\alpha(x) = \xi^\alpha{}_\beta(x) e_n^\beta(x)$$

Local Lorentz symmetry.

Gauge field - Lorentz connection 1 form

$$dx^n \omega_n{}^{\alpha\beta} = -dx^n \omega_n{}^{\beta\alpha}$$

$$S=2 : e_n^\alpha, \omega_n{}^{\alpha\beta}$$

$$g_{nm} = e_n^c e_m^\alpha \eta_{ca}$$

Cartan formulation of gravity

$$\left. \begin{array}{l} dx^n e_n^\alpha \quad \rho^\alpha \\ dx^n \omega_n^{ab} \quad M^{ab} \end{array} \right\} \text{Poincare}$$

$$R^\alpha = de^\alpha + \omega^\alpha{}_\beta e^\beta \stackrel{d}{=} D^\alpha e^\alpha$$

$$R^{ab} = d\omega^{ab} + \omega^a{}_c \wedge \omega^{cb}$$

R^α, R^{ab} Yang-Mills field strengths
for the Poincare algebra

$R^\alpha = 0$ - "zero torsion condition"

$\square \otimes \square$ expresses $\omega^{ab} \Rightarrow \omega^{ab}(e, \partial e)$
 $\square \otimes \square$

$$R^{ab}(\omega(e)) = dx^n \wedge dx^m R_{nm}{}^{ab}(\omega(e))$$

Riemann tensor

$$\det |e_n^\alpha| \neq 0$$

$$g_{nm} = e_n^\alpha e_m^\beta \eta_{\alpha\beta}$$

$\left. \begin{array}{l} R^\alpha = 0 \\ R^{ab} = 0 \end{array} \right\}$ Flat space-time

Poincare symmetry is by
construction

Gravity via gauging of $(A)dS$ group

e^a , $\omega^{\alpha\beta} \Rightarrow W^{AB} = -W^{BA}$

frame, *Lorentz* $A, B, \dots = 0, \dots, d$
1-form *connection* $a, b, \dots = 0, \dots, d-1$

$W^{AB} = dX^n W_n^{AB} \in \begin{matrix} O(d-1, 2) & AdS \\ O(d, 1) & dS \end{matrix}$

Field strength

$R^{AB} = dW^{AB} + W^{AC} \wedge W^{DB} \eta_{CD}$

$\eta_{AB} = \begin{matrix} (+ - - \dots - +) & AdS_d \\ (+ - - \dots -) & dS_d \end{matrix}$

Compensator

$V^A(x) [L]$

$V^A V^B \eta_{AB} = \begin{Bmatrix} \tau^2 & AdS \\ -\tau^2 & dS \end{Bmatrix} = -\Lambda^{-1}$

$AdS \quad \Lambda < 0$

$dS \quad \Lambda > 0$

Length of V^A = radius of $(A)dS$ space-time

Standard gauge

$V^A = \tau \delta_d^A$

L^0

L^{-1}

L

$e^a = W^{\alpha B} V_B$

L^{-1}

$\omega^{\alpha\beta} = \pm W^{AB}$

$\pm W^{AB} V_B = 0$

Covariant definitions

$$E^A = \mathcal{D}V^A = dV^A + W^A_B V^B$$

$$E^A V_A = 0 \quad (V^A V_A \equiv \text{const})$$

$$g_{nm} = E_n^A E_m^B \eta_{AB}$$

Lorentz connection

$$\omega^{LAB} = W^{AB} + \Lambda (E^A V^B - E^B V^A)$$

$$\mathcal{D}^L V^A = dV^A + \omega^{LAB} V^B \equiv 0$$

In the standard gauge $V^A = r \delta_d^A$
one recovers usual definitions

Curvature decomposition:

$$R^A = R^{AB} V_B \quad (R^A V_A = 0) \quad \text{torsion}$$

$${}^L R^{AB} : {}^L R^{AB} V_B = 0 \quad \text{shifted Riemann}$$

In the standard gauge

$$R_{nm}^\alpha = \partial_n e_m^\alpha + \omega_n^{\alpha\beta} e_m^\beta - n \leftrightarrow m$$

$$R_{nm}^{\alpha\beta} = \partial_n \omega_m^{\alpha\beta} + \omega_n^{\alpha c} \omega_m^{\beta c} + \Lambda e_n^\alpha e_m^\beta - (n \leftrightarrow m)$$

$$R^A = 0 \Rightarrow \omega = \omega(E, \partial E)$$

$${}^L R^{AB} = 0, \quad \text{rank } |E_n^A| = d \Rightarrow (A)dS_d$$

Vacuum Symmetry

Any vacuum solution

$$R^{AB}(W_0) = 0$$

describes $(A)dS_d$ provided that

$$\text{rank} |E_0^n{}^A| = d$$

YM curvature R^{AB} transforms homogeneously under the gauge transformation

$$* \quad \delta W^{AB} = \mathcal{D} \varepsilon^{AB} \quad \delta R^{AB} = \varepsilon^A{}_c R^{cB} + \varepsilon^B{}_c R^{Ac}$$

and diffeomorphisms.

Generically $*$ maps one solution to another

Vacuum symmetry

$$\delta W_0 = \mathcal{D}_0 \varepsilon_{ge}^{AB}(x) = 0$$

The equation

$$\frac{\partial}{\partial x^n} \varepsilon_{ge}^{AB}(x) + W_0^n{}^A{}_c \varepsilon_{ge}^{cB}(x) + W_0^n{}^B{}_c \varepsilon_{ge}^{Ac}(x) = 0$$

is consistent because $\mathcal{D}_0^2 = R(W_0) = 0$

It fixes $\varepsilon_{ge}^{AB}(x)$ in terms of

$\varepsilon_{ge}^{AB}(x_0)$ at any x_0

$\varepsilon_{ge}^{AB}(x)$ are $o(d-2, 1)$ ($o(d, 1)$) global symmetry parameters

Einstein - Hilbert action in the
MacDowell - Mansouri - Stelle - West form

$$d = 4$$

MacDowell, Mansouri (78)
Stelle, West (1980)

$$S = -\frac{1}{4\kappa^2 |\Lambda|^{1/2}} \int_{M^4} \epsilon_{ABCDE} V^A R^{BC} \wedge R^{DE}$$

Symmetries

- (i) diffeomorphisms
- (ii) local $O(d-1, 2)$ (or $O(d, 1)$)

Compensator transforms as

$$\delta V^A = \xi^\mu \partial_\mu V^A + \epsilon^A_B V^B = \xi^\mu D_\mu V^A + \epsilon'^A_B V^B$$

$$\epsilon^{AB} = \epsilon'^{AB} + \xi^\mu W_\mu^{AB}$$

$$\delta V^A = \xi^\mu E_\mu^A + \epsilon'^A_B V^B$$

V^A is pure gauge

Using (A)dS symmetry V^A can be fixed
arbitrarily. Leftover gauge symmetry
diffeomorphisms + local Lorentz

Standard gauge $V^A = r \delta^A_d$

$$S = +\frac{1}{4\kappa^2 \Lambda} \int_{M^4} \epsilon_{abcd} R^{ab} \wedge R^{cd}$$

MacDowell,
Mansouri (1977)

$$S = \frac{1}{4\kappa^2 \Lambda} \epsilon^{abcd} \times$$

$$\times \int_{M^4} (d\omega_{ab} + \omega_{ae} \wedge \omega^e_b + \Lambda e_a \wedge e_b) \wedge (d\omega_{cd} + \omega_{cf} \wedge \omega^f_d + \Lambda e_c \wedge e_d)$$

$$S = \Lambda^{-1} S_{-1} + \Lambda^0 S_0 + \Lambda S_1$$

• $S_{-1}(\omega) : \frac{\delta S_{-1}}{\delta \omega} \equiv 0$ topological inv.

• $S_0 = \frac{1}{2\kappa^2} \int \epsilon^{abcd} e_c \wedge e_d \wedge \underbrace{(d\omega_{ab} + \omega_{ae} \wedge \omega^e_b)}_{\text{Riemann tensor}}$

$\sim \frac{1}{\kappa^2} \int |e| R$ Einstein action

• $S_1 = \frac{1}{4\kappa^2} \Lambda \int_{M^4} \epsilon^{abcd} e_a \wedge e_b \wedge e_c \wedge e_d$
Cosmological term

Λ - cosmological constant

Equations of motion

$$S = -\frac{1}{4\kappa^2 |\Lambda|^{1/2}} \int \epsilon_{ABCDE} V^A R^{BC} \wedge R^{DE}$$

$$\delta R^{AB} = \mathcal{D}(\delta W^{AB}) \quad \text{general variation}$$

$$\mathcal{D}R^{AB} = 0 \quad \text{Bianchi identities}$$

$$\delta S = \frac{1}{4\kappa^2 |\Lambda|^{1/2}} \int \epsilon_{ABCDE} \mathcal{D}V^A \wedge R^{BC} \wedge \delta W^{DE}$$

Taking into account

$$\mathcal{D}V^A = E^A$$

Equations of motion

$$R^{AB} = 0$$

$$\epsilon_{ABCDE} E^A \wedge R^{BC} = 0 \quad \text{(A) dS vacuum}$$

Variation with respect to Lorentz connection: V -transversality with respect to \mathcal{D}, E is equivalent to the zero torsion condition $R^{BC} V_C = 0$

Lorentz connection is auxiliary field expressed in terms of $e, \mathcal{D}e$ by virtue of its field equations

$$\mathcal{D} \epsilon_{ABCDE} V^E E^A \wedge R^{BC} = 0$$

Einstein equations

Towards HS symmetries

Idea: to find an algebra

$$\mathfrak{g} \supset \mathfrak{h} = (A)dS \text{ algebra}$$

such that the gauge fields

$$W \in \mathfrak{g} \quad R = dW + W \wedge W$$

allow for a MacDowell-Mansouri type formulation

$$S = \int_{M^d} V R_1 \wedge R_1 \wedge E \wedge E \dots$$

equivalent to Fronsdal formulation in the free field limit

$$W = W_0 + W_1 \quad R(W_0) = 0$$

$W_0 \in \mathfrak{h}$ background (A)dS field

$W_1 \in \mathfrak{g}$ HS fields

$$R_1 = \mathcal{D}_0 W_1$$

Manifest HS gauge invariance

$$\delta W_1 = \mathcal{D}_0 \varepsilon \quad \mathcal{D}_0^2 = 0 \quad \varepsilon \in \mathfrak{g}$$

\mathfrak{g} is the HS vacuum algebra symmetry

Young Tableaux

gl_M tensors

$$A^{a_1; a_2; a_3 \dots} \quad a_i = 1, \dots, M$$

Different symmetry properties

Rank -2 symmetric:

$$A^{a_1; a_2} - A^{a_2; a_1} = 0 \quad \square \square$$

Rank -2 antisymmetric:

$$A^{a_1; a_2} + A^{a_2; a_1} = 0 \quad \square$$

General case: symmetric basis

$$A^{a_1 \dots a_{n_1}, b_1 \dots b_{n_2}, c_1 \dots c_{n_3}, \dots}$$

$$n_1 \geq n_2 \geq n_3 \geq \dots$$

$$\begin{cases} A^{a_1 \dots a_{n_1}, a_{n_1+1} b_2 \dots b_{n_2}, c_1 \dots c_{n_3}, \dots} = 0 \\ A^{a_1 \dots a_{n_1}, b_1 \dots b_{n_2}, b_{n_2+1} c_2 \dots c_{n_3}, \dots} = 0 \\ \vdots \end{cases}$$

$Y(n_1, n_2, n_3, \dots) :$



A number of rows $\leq M$

Bosonic generating function

$$A(Y) = \sum_{n_1, n_2, \dots} A^{\alpha_1 \dots \alpha_{n_1} \beta_1 \dots \beta_{n_2} \gamma_1 \dots \gamma_{n_3}} \times Y_{\alpha_1}^1 \dots Y_{\alpha_{n_1}}^1 Y_{\beta_1}^2 \dots Y_{\beta_{n_2}}^2 Y_{\gamma_1}^3 \dots Y_{\gamma_{n_3}}^3 \dots$$

Symmetrization is manifest

$$[Y_{\alpha}^d, Y_{\beta}^d] = 0 \quad \begin{array}{l} \alpha = 1, \dots, M \\ d = 1, \dots, P \end{array}$$

Young conditions

$$* \left\{ \begin{array}{l} Y_{\alpha}^d \frac{\partial}{\partial Y_{\alpha}^{\beta}} A = 0 \quad d < \beta \\ Y_{\alpha}^d \frac{\partial}{\partial Y_{\alpha}^{\beta}} A \Big|_{d=\beta} = n_{\alpha} A \end{array} \right.$$

Howe dual algebras

$$gl_M: \quad t_{\alpha}^{\beta} = Y_{\alpha}^d \frac{\partial}{\partial Y_{\alpha}^{\beta}}$$

$$gl_P: \quad \ell_{\beta}^d = Y_{\alpha}^d \frac{\partial}{\partial Y_{\alpha}^{\beta}}$$

$$[\ell, t] = 0$$

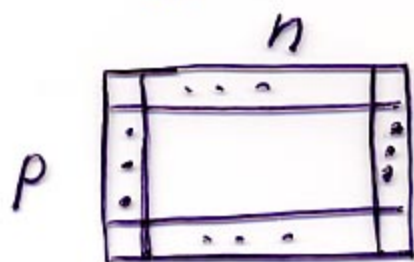
Young conditions * are

highest weight conditions

with respect to Howe dual gl_P

Blocks

Rectangular tableaux



$$n_d \equiv n$$

are invariants of Howe dual
slp

$$\left(\gamma^{\alpha} \frac{\partial}{\partial \gamma^{\beta}} - \frac{1}{p} \delta^{\alpha}_{\beta} \gamma^{\gamma} \frac{\partial}{\partial \gamma^{\gamma}} \right) A(\gamma) = 0$$

$$\gamma^{\gamma} \frac{\partial}{\partial \gamma^{\gamma}} A(\gamma) = n A(\gamma)$$

$n_d = n$ implies that weights of
slp are zero

Rows in the block tableaux can be
interchanged with the sign factor
 $(-1)^n$

For the block tableaux, the slp
lowest weight conditions are
consequences of the slp highest
weight conditions because
polynomials $A(\gamma)$ form finite-dimensional
modules over slp

$O(M)$ invariant traceless tensors

$$A(Y) = \sum_{n_1, n_2, \dots} A^{a_1 \dots a_{n_1}, b_1 \dots b_{n_2}, c_1 \dots c_{n_3} \dots} x$$

$$Y_{a_1}^1 \dots Y_{a_{n_1}}^1 Y_{b_1}^2 \dots Y_{b_{n_2}}^2 Y_{c_1}^3 \dots Y_{c_{n_3}}^3$$

Contraction of any two indices with the $O(M)$ invariant metric

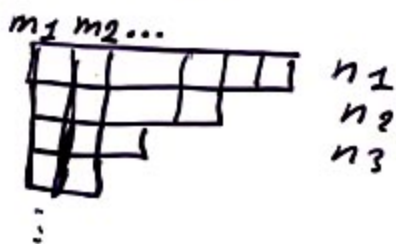
η_{ab} gives zero:

In addition to Young condition one imposes

$$\eta_{ab} \frac{\partial^2}{\partial Y_a^\alpha \partial Y_b^\beta} A(Y) = 0$$

Traceless Young tableaux

$$Y^{tr}(n_1, n_2, n_3, \dots)$$



$$n_1 \geq n_2 \geq n_3 \dots$$

$$m_1 + m_2 \leq M$$

$$\in \alpha_1 \dots \alpha_n \in \beta_1 \dots \beta_n = \eta^{\alpha_1 \beta_1} \dots \eta^{\alpha_n \beta_n} + \dots$$

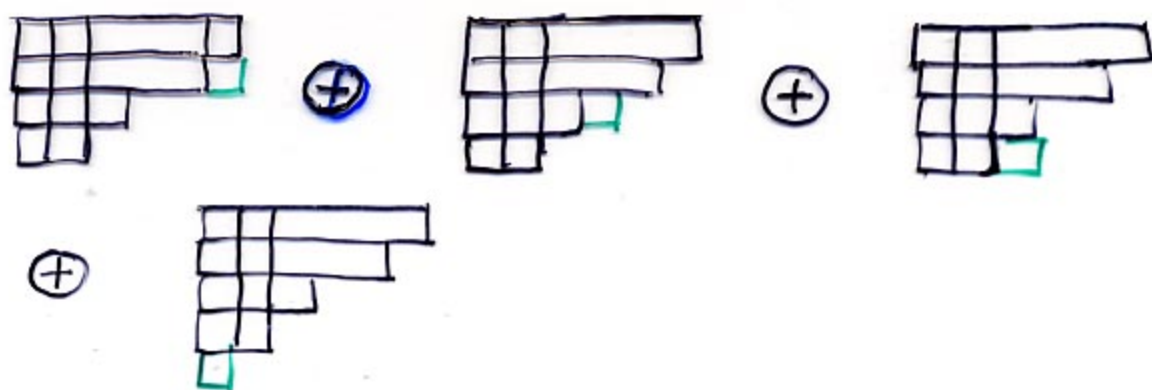
are highest weights of $sp(2p)$ which is Howe dual to $O(M)$

$$L^\alpha_\beta = Y^\alpha_a \frac{\partial}{\partial Y^\beta_a}$$

$$L^{\alpha\beta} = \eta^{\alpha\gamma} Y^\gamma_a Y^\beta_b$$

$$L_{\alpha\beta} = \eta_{\alpha\gamma} \frac{\partial^2}{\partial Y^\alpha_a \partial Y^\beta_b}$$

Multiplication rule



All admissible tableaux with one cell added

$$Y(1, 0, 0, \dots) \otimes Y(n_1, n_2, \dots) =$$

$$Y(n_1+1, n_2, \dots) \oplus Y(n_1, n_2+1, \dots) \oplus \dots$$

For traceless tableaux

$$Y(1, 0, 0, \dots) \otimes Y^{tr}(n_1, n_2, n_3, \dots) =$$

$$= Y^{tr}(n_1+1, n_2, n_3, \dots) + Y^{tr}(n_1-1, n_2, n_3, \dots)$$

$$+ Y^{tr}(n_1, n_2+1, n_3, \dots) + Y^{tr}(n_1, n_2-1, n_3, \dots)$$

$$+ Y^{tr}(n_1, n_2, n_3+1, \dots) + Y^{tr}(n_1, n_2, n_3-1, \dots)$$

For example

$$\square \otimes \square = \begin{matrix} \square \\ \square \end{matrix} \oplus \begin{matrix} \square \\ \square \\ \square \end{matrix} \oplus \dots$$

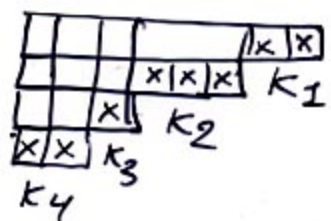
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Reduction rule

$\Upsilon_M^{(tr)}(n_1, n_2, n_3, \dots)$ is $sl_M(O(M))$ representation

Its content as the $sl_{M-1}(O(M-1))$ representation

$$\Upsilon_M^{(tr)}(n_1, n_2, n_3, \dots) = \sum_{k_i=0}^{n_i - n_{i-1}} \oplus \Upsilon_{M-1}^{(tr)}(n_2 + k_1, n_3 + k_2, \dots)$$



One can cut any number of crossed cells

Let $O(M-1)$ be stability algebra of some $O(M)$ vector V^α

Reduction implies decomposition of a tensor into V -transversal and V parallel components.

V -transversal components form representations of $O(M-1)$

Crossed cells denote V -parallel components of tensor indices

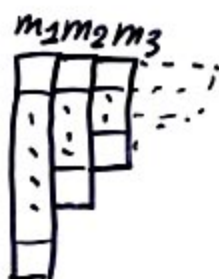
General case: antisymmetric basis

$$A[\alpha_1 \dots \alpha_{m_1}], [b_1 \dots b_{m_2}], [c_1 \dots c_{m_3}]$$

$$M \geq m_1 \geq m_2 \geq m_3 \geq \dots$$

$$\left\{ \begin{array}{l} A[\alpha_1 \dots \alpha_{m_1}, \alpha_{m_1+1}], [b_1 \dots b_{m_2}], [c_1 \dots c_{m_3}] = 0 \\ A[\alpha_1 \dots \alpha_{m_1}], [b_1 \dots b_{m_2}, b_{m_2+1}], [c_1 \dots c_{m_3}] = 0 \\ \vdots \end{array} \right.$$

$$Y[m_1, m_2, m_3, \dots]$$



Fermionic generating function

$$A(\varphi) = A[\alpha_1 \dots \alpha_{m_1}], [b_1 \dots b_{m_2}], [c_1 \dots c_{m_3}], \dots$$

$$\varphi_{\alpha_1}^1 \dots \varphi_{\alpha_{m_1}}^1 \quad \varphi_{b_1}^2 \dots \varphi_{b_{m_2}}^2 \quad \varphi_{c_1}^3 \dots \varphi_{c_{m_3}}^3 \dots$$

$$\varphi_{\alpha}^d \varphi_{\beta}^b = -\varphi_{\beta}^b \varphi_{\alpha}^d$$

$$t_{\alpha}^{\beta} = \varphi_{\alpha}^d \frac{\partial}{\partial \varphi_{\beta}^d}$$

$$l_{\beta}^d = \varphi_{\alpha}^d \frac{\partial}{\partial \varphi_{\beta}^d}$$

gl_M

gl_p

} Howe
dual

Young tableau is a highest weight of gl_p

Frame-like formulation of HS Dynamics

Flat space-time

M.V. (1980)
Lopatin, M.V (1988)

$$\varphi_{n_1 \dots n_s} \rightarrow e_n^{\alpha_1 \dots \alpha_{s-1}}$$

$$e^{\alpha_1 \dots \alpha_{s-1}} = dX^n e_n^{\alpha_1 \dots \alpha_{s-1}}$$

$$e_{n, \beta}^{\alpha_1 \dots \alpha_{s-1}} = 0$$

$$\varphi_{n_1 \dots n_s} = e_{\{n_1, n_2 \dots n_s\}} \quad \varphi_n^m m_{k_1 \dots k_s} = 0$$

Antisymmetric part in $e_n^{\alpha_1 \dots \alpha_{s-1}}$

should be pure gauge analogously to the antisymmetric part of the usual frame $e_{n, \alpha}$

$$\square \otimes \begin{array}{|c|c|c|} \hline & \dots & \\ \hline \end{array}^{s-1} = \begin{array}{|c|c|c|} \hline & \dots & \\ \hline \end{array}^s \oplus \begin{array}{|c|c|c|} \hline & \dots & \\ \hline \end{array}^{s-2} \oplus \text{Fronsdal}$$

Traceless
tableaux

$$\begin{array}{|c|c|c|} \hline & \dots & \\ \hline \end{array}^{s-1}$$

Lorentz-type

Gauge transformation law

$$\delta e_n^{\alpha_1 \dots \alpha_{s-1}} = \partial_n \xi^{\alpha_1 \dots \alpha_{s-1}} + \overset{\text{traceless}}{h_n^\beta} \xi_{\alpha_1 \dots \alpha_{s-2}, \beta}$$

Fronsdal Lorentz

$$h_n^\beta = \delta_n^\beta \text{ frame}$$

$$\xi_{\{\alpha_1 \dots \alpha_{s-2}, \alpha_s\}} = 0 \quad \xi_{\alpha_1 \dots \alpha_{s-2} \beta}{}^\beta = 0$$

Lorentz connection - type gauge field

$$dX^n \omega_{n, \alpha_1 \dots \alpha_{s-1}, b}$$



Torsion - type curvature form

$$R_{nm, \alpha_1 \dots \alpha_{s-1}} = \partial_n e_{m, \alpha_1 \dots \alpha_{s-1}} + \hbar_n^c \omega_{m, \alpha_1 \dots \alpha_{s-1}, c} - (n \leftrightarrow m)$$

is reconstructed from the transformation law for $e_{n, \alpha_1 \dots \alpha_{s-1}}$

It is invariant under

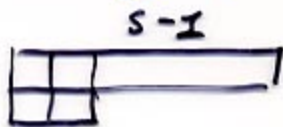
$$\delta e_{n, \alpha_1 \dots \alpha_{s-1}} = \partial_n \epsilon_{\alpha_1 \dots \alpha_{s-1}} + \hbar_n^b \epsilon_{\alpha_1 \dots \alpha_{s-1}, b}$$

$$\delta \omega_{n, \alpha_1 \dots \alpha_{s-1}, b} = \partial_n \epsilon_{\alpha_1 \dots \alpha_{s-1}, b} + \hbar_n^c \epsilon_{\alpha_1 \dots \alpha_{s-1}, bc}$$

where $\epsilon_{\alpha_1 \dots \alpha_{s-1}, b_1 b_2}$ is second-level

Lorentz-type symmetry parameter

$$\epsilon_{\alpha_1 \dots \alpha_{s-1}, b_1 b_2}$$



traceless + antisymmetric

$$\epsilon_{\{\alpha_1 \dots \alpha_{s-1}, \alpha_s\} b} = 0$$

Zero-torsion constraint

$$R_{nm, \alpha_1 \dots \alpha_{s-1}} = 0$$

expresses the Lorentz-type field $\omega_{n, \alpha_1 \dots \alpha_{s-1}, b}$ via first derivatives of $e_{n, \alpha_1 \dots \alpha_{s-1}}$ modulo pure gauge part with the level -2 local Lorentz symmetry

$$\begin{array}{c}
 \square \otimes \overline{\square} \otimes \overline{\square}^{\otimes s-1} \\
 R_{nm, \alpha_1 \dots \alpha_{s-1}}
 \end{array}
 = \overline{\square}^{\otimes s-1} \oplus \overline{\square}^{\otimes s} \oplus \underbrace{\overline{\square}^{\otimes s-2} \oplus \overline{\square}^{\otimes s-1}}_{\text{traces}}$$

$$\begin{array}{c}
 \square \otimes \overline{\square}^{\otimes s-1} \\
 \omega_{n, \alpha_1 \dots \alpha_{s-1}, b}
 \end{array}
 = \overline{\square}^{\otimes s-1} \oplus \overline{\square}^{\otimes s-1} \oplus \underbrace{\overline{\square}^{\otimes s-2} \oplus \overline{\square}^{\otimes s-1}}_{\text{traces}}$$

← gauge part

Extra cell (index) in

$$\omega_{n, \alpha_1 \dots \alpha_{s-1}, b} \sim (\partial e) \dots$$

is for one derivative applied to the dynamical field $e_{n, \alpha_1 \dots \alpha_{s-1}}$

Introducing level -2 Lorentz fields

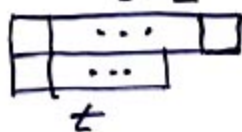
$$\omega_n, \alpha_1 \dots \alpha_{s-1}, b_1 b_2$$

the process continues leading to the linearized curvatures

$$R_{nm}^1, \alpha_1 \dots \alpha_{s-1}, b_1 \dots b_t = \partial_n \omega_m, \alpha_1 \dots \alpha_{s-1}, b_1 \dots b_t + h_n^c \omega_m, \alpha_1 \dots \alpha_{s-1}, b_1 \dots b_{t+c} - (n \leftrightarrow m)$$

for the set of gauge fields

$$\omega_n, \alpha_1 \dots \alpha_{s-1}, b_1 \dots b_t \quad 0 \leq t \leq s-1$$



traceless in fiber indices a, b

$t=0$: frame field $e_n, \alpha_1 \dots \alpha_{s-1}$

- Linearized curvatures are invariant under the gauge transformations

$$\delta \omega_n, \alpha_1 \dots \alpha_{s-1}, b_1 \dots b_t = \partial_n \epsilon_{\alpha_1 \dots \alpha_{s-1}, b_1 \dots b_t} + h_n^c \epsilon_{\alpha_1 \dots \alpha_{s-1}, b_1 \dots b_{t+c}}$$

$$\delta R^1 = 0$$

- $\omega_n, \alpha_1 \dots \alpha_{s-1}, b_1 \dots b_t$ are expressed in terms of order t derivatives of $e_n, \alpha_1 \dots \alpha_{s-1}$ by appropriate invariant constraints

(A)dS Higher Spin Curvatures

The set of HS 1 forms

$$\omega_{a_1 \dots a_{s-1}, b_1 \dots b_t} \quad 0 \leq t \leq s-1$$

of $o(d-1, 1)$ Lorentz tensors

$$\begin{array}{|c|c|c|c|c|} \hline & & & & \\ \hline & \dots & & & \\ \hline & & & & \\ \hline & & & & \\ \hline \end{array} \quad 0 \leq t \leq s-1 \quad \text{traceless}$$

is equivalent to a single 1 form

$$W^{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}} \quad A, B, \dots = 0, \dots, d$$

taking values in the irreducible representation

$$\begin{array}{|c|c|c|c|} \hline & & & \\ \hline \circ & \dots & & \circ \\ \hline \circ & \dots & & \circ \\ \hline \end{array} \quad \text{traceless} \quad s=2 : \begin{array}{|c|} \hline \circ \\ \hline \end{array}$$

$$W^{A_1 \dots A_{s-1}, A_s} B_2 \dots B_{s-1} = 0 \quad W_c^{A_3 \dots A_{s-1}, B_3 \dots B_{s-1}} = 0$$

of AdS algebra $o(d-2, 2)$ or dS algebra $o(d, 1)$

Lorentz decomposition

$$\begin{array}{|c|c|c|c|} \hline & & & \\ \hline \circ & \dots & & \circ \\ \hline \circ & \dots & & \circ \\ \hline \end{array} = \sum_{t=0}^{s-1} \oplus \begin{array}{|c|c|c|c|} \hline & & & \\ \hline & & & \\ \hline & & \times \times \times & \\ \hline & & & \\ \hline \end{array} \quad \begin{array}{l} \boxed{\times} - \text{contraction with } V^A \\ \boxed{} - V^A \text{ transversal} \end{array}$$

V^A - compensator

$$e^{A_1 \dots A_{s-1}} = W^{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}} V_{B_1} \dots V_{B_{s-1}}$$

is automatically V^A - transversal

Linearised (A)dS HS curvatures

$$R^1_{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}} = dW_{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}} + (s-1) \left(W_{0A_1}{}^C \wedge W_{CA_2 \dots A_{s-1}, B_1 \dots B_{s-1}} + W_{0B_1}{}^C \wedge W_{A_1 \dots A_{s-1}, CB_2 \dots B_{s-1}} \right)$$

$W_{0AB} = -W_{0BA}$ is background (A)dS gravitational field which satisfies (A)dS equation

$$*R_0 = dW_{0AB} + W_{0A}{}^C \wedge W_{CB} = 0$$

$$R^1 = \mathcal{D}_0 W$$

$$\delta_0 W_{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}} = \mathcal{D}_0 (\varepsilon_{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}})$$

$$\delta R^1 = \mathcal{D}_0^2 \varepsilon = 0 \quad \mathcal{D}_0^2 = 0 \quad *$$

\mathcal{D}_0 is the covariant derivative of $o(d-1, 2)_{s-1}$ or $o(d, 1)$ in the representation

0	...	0
0	...	0

Lorentz invariant decomposition in terms of compensator

$$W_0^{AB} = \omega_0^{L AB} - \Lambda (E_0^A V^B - E_0^B V^A)$$

$$D_0 W_{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}} = D_0^L W_{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}}$$

$$\Lambda^0 + \Lambda (s-1) (V_{A_1} E_0^C \wedge W_{C A_2 \dots A_{s-1}, B_1 \dots B_{s-1}} \\ + V_{B_1} E_0^C \wedge W_{A_1 \dots A_{s-1}, C B_2 \dots B_{s-1}})$$

$$\Lambda^1 - \Lambda (s-1) V^C (E_{0 A_1} \wedge W_{C A_2 \dots A_{s-1}, B_1 \dots B_{s-1}} \\ + E_{0 B_1} \wedge W_{A_1 \dots A_{s-1}, C B_2 \dots B_{s-1}})$$

By appropriate field rescaling the dependence on Λ in the first term can be rescaled away.

Then the limit $\Lambda \rightarrow 0$, $D_0^L \rightarrow d$ reproduces the Minkowski space-time H \check{S} curvatures we started with

- Without rescaling

$$W_{a_1 \dots a_{s-1}, b_1 \dots b_t} \sim [(\Lambda^{-1/2} \partial)^t e_{a_1 \dots a_{s-2}}]$$

$t \geq 2$ - "extra fields" carry higher derivatives and negative powers of Λ . "Extra fields" appear for $s > 2$

HS Invariant Action

$$S_2^S = \frac{1}{2} \sum_{p=0}^{s-2} \alpha(s,p) \epsilon_{A_1 \dots A_{d+1}} \int_{M^d} E_0^{A_1} \dots \wedge E_0^{A_{d+1}} V^{d+1} \times$$

$$V_{C_1 \dots C_{2(s-2-p)}} \wedge R_1^{A_2 B_1 \dots B_{s-2}, A_2 C_1 \dots C_{s-2-p} D_1 \dots D_p}$$

$$\wedge R_1^{A_3 B_1 \dots B_{s-2}, A_4 C_1 \dots C_{2(s-2-p)} D_1 \dots D_p}$$

where the coefficients $\alpha(s,p)$ are fixed by the condition

$$\frac{\delta S}{\delta W_{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}}} V^{B_1} V^{B_2} \equiv 0$$

as

$$\alpha(s,p) = \tilde{\alpha}(s) \Lambda^{-\left(s-p-\frac{3}{2}\right)} \frac{(d-5+2(s-p-2))!! (s-p-2)}{(d-3+2(s-2))!! (s-p-2)!}$$

to guarantee that S_2^S depends only on the dynamical field $e^{\alpha_1 \dots \alpha_{s-1}}$ and auxiliary field $\omega^{\alpha_1 \dots \alpha_{s-1}, b}$

By construction, the action is gauge invariant under

$$\delta e^{\alpha_1 \dots \alpha_{s-1}} = d \xi^{\alpha_1 \dots \alpha_{s-1}} + h_b \xi^{\alpha_1 \dots \alpha_{s-1}, b}$$

and is, therefore, equivalent to the Fronsdal's action ↑ Lorentz type background frame

HS Algebras

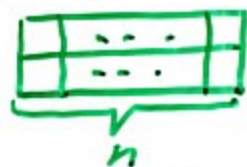
Generic element

$$f = \sum_{n=0}^{\infty} f^{A_1 \dots A_n, B_1 \dots B_n} T_{A_1 \dots A_n, B_1 \dots B_n}$$

Generators $T_{A_1 \dots A_n, B_1 \dots B_n}$

$$T_{\{A_1 \dots A_n, A_{n+1}\} B_1 \dots B_n} = 0 \quad T^{C A_3 \dots A_n, B_1 \dots B_n} = 0$$

$$T_{A, B} = -T_{B, A} : \text{odd } (d-1, 2)$$



$$[T_{A, B}, T_{C_1 \dots C_n, D_1 \dots D_n}] = 2BC_1 T_{AC_2 \dots C_n, D_1 \dots D_n} + \dots$$

What is a non Abelian algebra with these properties?!

Are there global symmetries of this type in field theories?

Conserved currents?

Yes!

§ Konstein, M.V.
V. Zaikin (2000)

Bosonic HS Algebra in AdS_d

\hat{Y}_i^A : AdS_d symplectic pair

$$[\hat{Y}_i^A, \hat{Y}_j^B] = \epsilon^{ij} \eta^{AB} \quad \begin{matrix} A, B = 0 \dots d \\ i, j = 1, 2 \end{matrix}$$

η^{AB} is $O(n, m)$ invariant metric
 $n=2, m=d-1$ for $AdS_d \dots$

$\epsilon^{ij} = -\epsilon^{ji}$ is $sp(2)$ symplectic form

Symplectic pair $\hat{Y}_1^A = \hat{Y}^A, \hat{Y}_2^A = \hat{P}^A$

$O(n, m)$ ($AdS_d \sim CFT_{d-2}$) generators

$$\tau^{AB} = -\tau^{BA} = \frac{1}{2} \{ \hat{Y}_i^A, \hat{Y}_j^B \} \epsilon^{ji}$$

$sp(2)$ generators

$$t_{ij} = t_{ji} = \frac{1}{2} \{ \hat{Y}_i^A, \hat{Y}_{jA} \}$$

Key fact

$$[\tau^{AB}, t_{ij}] = 0 \quad \dots \text{Howe duality}$$

HS algebra - t_{ij} quotient of the centralizer of $sp(2) \sim sl_2$

Eastwood (2002)

Generic element

$$f(\hat{Y}) = \sum_{m,n} f_{A_1 \dots A_m, B_1 \dots B_n} \hat{Y}_1^{A_1} \dots \hat{Y}_1^{A_m} \hat{Y}_2^{B_1} \dots \hat{Y}_2^{B_n}$$

$$S: [t_{ij}, f] = 0$$

$$t_{ij} = t_{ji} = \frac{1}{2} \{ \hat{Y}_i^A, \hat{Y}_{jA} \}$$

$sp(2) \sim sl_2$ - Howe dual 

Ideal

$$I: g(\hat{Y}) = t_{ij} g^{ij}(\hat{Y})$$

$$[t_{ij}, g^{ke}] = \delta_i^k g_j^e + \delta_j^k g_i^e + \delta_i^e g_j^k + \delta_j^e g_i^k$$

$$g \in I, [t_{ij}, f] = 0$$

\Downarrow

$$fg \in I$$

$$gf \in I$$

I is two-sided ideal

The factor algebra S/I consists of generators described by

traces two-row Young tableaux

Lie HS algebra $hu(1/sp(2)[n, m])$

$$n=2, m=d-1 \rightarrow AdS$$

$$n=1, m=d \rightarrow dS$$

Star-product

Let \hat{Y}_α $\alpha=1 \dots 2p$ be oscillators

$$* \quad [\hat{Y}_\alpha, \hat{Y}_\beta] = 2 C_{\alpha\beta} \quad C_{\alpha\beta} = -C_{\beta\alpha}$$

non-degenerate

$$\hat{f}(\hat{Y}) = \sum_n f^{d_1 \dots d_n} \hat{Y}_{d_1} \dots \hat{Y}_{d_n}$$

Using $*$ one can achieve that

$f^{d_1 \dots d_n}$ is totally symmetric:

Weyl ordering

Let Y_α be usual commuting variables

$$[Y_\alpha, Y_\beta] = 0$$

$f(Y) = \sum_n f^{d_1 \dots d_n} Y_{d_1} \dots Y_{d_n}$ is Weyl symbol
of $\hat{f}(\hat{Y})$

$(f * g)(Y)$ is the symbol of $\hat{f}(\hat{Y}) \hat{g}(\hat{Y})$

The star product is associative
by construction $(f * g) * h = f * (g * h)$

A form of $(f * g)(Y)$ is non-trivial
because the Weyl re-ordering is
to be performed in $\hat{f}(\hat{Y}) \hat{g}(\hat{Y})$

Triangle formula

$$(f * g)(Y) = \frac{1}{(2\pi)^{2p}} \int ds dt \exp(-s_\alpha t_\beta C^{\alpha\beta}) f(Y+s) g(Y+t)$$

$$C^{\alpha\beta} C_{\gamma\beta} = \delta_\gamma^\alpha \quad C^{\alpha\beta} = -C^{\beta\alpha}$$

To derive: $\hat{f}_W(Y) = \int ds e^{i\hat{Y}_\alpha s^\alpha} \hat{f}(s)$

$$f_W(Y) = \int ds e^{iY_\alpha s^\alpha} \hat{f}(s)$$

+ Campbell-Hausdorff formula

$$e^A e^B = e^{A+B} e^{\frac{1}{2}[A,B]} \quad \text{if } [[A,B], A] = 0 \\ [[A,B], B] = 0$$

Moyal product formula

$$(f * g)(Y) = \exp\left[\frac{\partial^2}{\partial Y_{1\alpha} \partial Y_{2\beta}} C_{\alpha\beta}\right] f(Y_1) g(Y_2)$$

$Y = Y_1 = Y_2$

Properties

(i) associativity

(ii) $1 * g = g * 1 = g$

(iii) $Y_\alpha * f = (Y_\alpha + \frac{\partial}{\partial Y_\alpha}) f$

$$f * Y_\alpha = (Y_\alpha - \frac{\partial}{\partial Y_\alpha}) f$$

$$[Y_\alpha, f]_* = 2 \frac{\partial}{\partial Y_\alpha} f$$

$$A^\alpha = C^{\alpha\beta} Y_\beta \\ A_\alpha = A^\beta C_{\beta\alpha}$$

(iv) $\text{str}(f * g) = (-1)^{\pi(f)\pi(g)} \text{str}(g * f)$

$$\text{str}(f) = f(0)$$

$$f(-Y) = (-1)^{\pi(f)} f(Y)$$

Summary of Lecture I

(i) Gravity as $o(d-1, 2)$ ($o(d, 1)$)
gauge field

$$\boxed{\text{e}} \quad W^{A, B} = -W^{B, A}$$

$$W^{A, B} = dx^n W_n^{A, B}$$

V^A - compensator

$$V^A V_A = -\Lambda^{-1}$$

Standard gauge

$$V^A = \tau \delta_d^A$$

Usual gravity

$$\boxed{\text{a}} \quad e^a = W^{a, B} V_B$$

$$a, b, c, \dots = 0-d-1$$

$$\boxed{\text{b}} \quad \omega^{ab} = W^{a, b}$$

are V -transverse

$$E^A = \mathcal{D}V^A$$

$$\mathcal{D}V^A = dV^A + W^A_B V^B$$

(AdS) geometry

$$R^{AB} = 0$$

$$\text{rank } |E_n^A| = d$$

$$R = dW^{AB} + W^A_C \wedge W^{CB}$$

A particular vacuum W_0

$$R(W_0) = 0$$

$\mathbb{1}$ has by construction (A)dS symmetry

Summary of Lecture I

(ii) Spin - S (totally symmetric)

HS fields belong to irreps of $O(d-1, 2)$ ($O(d, 1)$)



$$W^{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}}$$

$$W^{A_1 \dots A_{s-1}, A_s} B_2 \dots B_{s-1} = 0$$

$$W^{A_1 \dots A_{s-1}, B_1 \dots B_{s-3} C} = 0$$

$$R_1^{A_1 \dots A_{s-1}, B_1 \dots B_{s-2}} = \mathcal{D}_0 W^{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}}$$

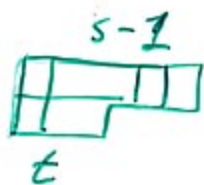
$$\delta_0 W^{A_1 \dots A_{s-1}, B_1 \dots B_{s-2}} = \mathcal{D}_0 \epsilon^{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}}$$

Abelian

$$\delta_0 R_1 = 0$$

$$W^{\alpha_1 \dots \alpha_{s-1}, b_1 \dots b_t b_{t+1} \dots b_{s-2}} V_{b_{t+1}} \dots V_{b_{s-1}}$$

a, b - V -transverse



- Lorentz HS fields

$$e^{\alpha_1 \dots \alpha_{s-1}} = W^{\alpha_1 \dots \alpha_{s-1}, B_1 \dots B_{s-2}} V_{B_1} \dots V_{B_{s-2}}$$

dynamical

$$W^{\alpha_1 \dots \alpha_{s-2}, b_1 \dots b_t} \quad t > 0 \quad \text{auxiliary}$$

$$1^{-t} \partial^t e$$

$$S = \int V^{p+2} (E)^{d-4} R_1 \ddot{a} R_1 \dots \quad \frac{\delta S}{\delta W} = 0 \quad t > 1$$

Summary of Lecture I

Bosonic HS algebra as star-product algebra

$$f(Y) = \sum_{m,n} f_{A_1 \dots A_m, B_1 \dots B_n} Y_1^{A_1} \dots Y_1^{A_m} Y_2^{B_1} \dots Y_2^{B_n}$$

$$f * g(Y) = \frac{1}{(2\pi)^{2(d+1)}} \int dS' dT' f(Y+S') g(Y+T') \exp(-2 S_i'^A T_j'^B \epsilon^{ij} \eta_{AB})$$

$$[Y_i^A, Y_j^B]_* = \epsilon_{ij} \eta^{AB} \quad i, j = 1, 2$$
$$\epsilon_{ij} = -\epsilon_{ji}$$

$O(n, m)$ generators

$$\pi^{AB} = -\pi^{BA} = Y_i^A Y_j^B \epsilon^{ji}$$

$Sp(2)$ generators

$$t_{ij} = t_{ji} = Y_i^A Y_{jA}$$

$$[t_{ij}, t_{ke}]_* = \epsilon_{ik} t_{je} + \epsilon_{ie} t_{jk} + \epsilon_{ik} t_{ie} + \epsilon_{je} t_{ik}$$

Howe dual pair

$$[t_{ii}, \pi^{AB}]_* = 0$$

Summary of Lecture I

HS algebra is built in two steps

(i) subalgebra of $sp(2)$ singlets

$$S: [f, t_{ij}]_* = 0$$

equivalent to

$$\left(Y^{Ai} \frac{\partial}{\partial Y^{Aj}} - Y^{Aj} \frac{\partial}{\partial Y^{Ai}} \right) f(Y) = 0$$

$$Y^{1A} \frac{\partial}{\partial Y^{A2}} = 0$$

$i=1, j=1$

$$Y^{2A} \frac{\partial}{\partial Y^{1A}} = 0$$

$i=2, j=2$

$$Y_1^A \frac{\partial}{\partial Y_1^A} - Y_2^A \frac{\partial}{\partial Y_2^A} = 0$$

$i=1, j=2$

$$f(Y) = \sum_{m=0}^{\infty} f_{A_1 \dots A_m, B_1 \dots B_m} Y_1^{A_1} \dots Y_1^{A_m} Y_2^{B_1} \dots Y_2^{B_m}$$

$$f_{\{A_1 \dots A_m, A_{m+1}\} B_1 \dots B_m} = 0$$

○	○	○
○	○	○

Every tableau appears just once!

(ii) To factor out the two-sided ideal

$$I: g(Y) = t_{ij} * g^{ij}(Y)$$

$$[t_{ij}, g^{ke}]_* = \delta_i^k g_{j,e} + \delta_j^k \delta_i^e + \delta_i^e g_{j,k} + \delta_j^e g_{i,k}$$

$$g \in I, [t_{ij}, f]_* = 0$$

\Downarrow

$$f * g \in I \quad g * f \in I$$

The factor-algebra

$$S/I = hu(1/sp(2)[n, m])$$

Signature
of η

has a representative

$$f(Y) = \sum_{n=0}^{\infty} f_{A_1 \dots A_n, B_1 \dots B_n} Y_1^{A_1} \dots Y_1^{A_n} Y_2^{B_1} \dots Y_2^{B_n}$$

traceless

$$f_{A_1 \dots A_n, B_1 \dots B_{n-2} C^C} = 0$$

traceless 

$$f_{A_1 \dots A_n, A_{n+2} B_2 \dots B_n} = 0$$

because

$$t_{ij} = Y_i^A Y_{j,A}$$

contain traces (contractions of (A) as indices

Higher Spin Gauge Fields

$$\omega(Y|x) = \sum_n \omega_{A_1 \dots A_n, B_1 \dots B_n}(x) Y_1^{A_1} \dots Y_1^{A_n} Y_2^{B_1} \dots Y_2^{B_n}$$

$$\omega_{\{A_1 \dots A_n, A_{n+1}\} B_1 \dots B_n} = 0 \quad \omega_{A_1 \dots A_n, B_1 \dots B_{n-2} C} = 0$$

$$\mathcal{R}\omega(Y|x) = d\omega(Y|x) + (\omega \wedge * \omega)(Y|x)$$

* acts on Y_i^A

$$(f * g)(Y) = \frac{1}{(2\pi)^{2(d+1)}} \int dS' dT' f(Y+S') g(Y+T') \exp(-2 S_i^A T_j^B \epsilon^{ij} \eta_{AB})$$

sp(2) invariance condition

$$D t_{ij} \equiv d t_{ij} + [\omega, t_{ij}]_* = 0 \quad t_{ij} = Y_i^A Y_j^B \eta_{AB}$$

Every integer spin $s \geq 1$ appears just once!

$hu(1/sp(2)[0, d-1])$ admits indeed a unitary representation in which all massless fields of integer spins $s = 0, 1, 2, \dots$ appear just once!

(a nontrivial consistency check!)

Unfolded Dynamics: example of gravity

Riemann + torsion tensors

$$R^{A,B} = dx^n \wedge dx^m R_{nm}; \quad \begin{matrix} A, B & n, m = 0 \dots d-1 \\ & A, B = 0, \dots, d \end{matrix}$$

$$R^{A,B} + R^{B,A} = 0 \quad \square \quad O(d-1, 2) \text{ or } O(d, 1)$$

Equivalently

$$R^{A,B} = E_c \wedge E_D \tau^{c,D}; A, B$$

$$\tau^{c,D}; A, B = -\tau^{D,c}; A, B = -\tau^{c,D}; B, A$$

V^A - transversality conditions

$$(i) \quad V_c \tau^{c,D}; A, B = 0 \quad \text{because } E_c V^c = 0$$

V - parallel components do not contribute

$$(ii) \quad \tau^{c,D}; A, B V_B = 0 \Leftrightarrow R^{A,B} V_B = 0$$

zero-torsion condition

(i) + (ii): $\tau^{c,D}; A, B$ is V - transversal,
i.e. Lorentz $(O(d-1, 1))$ tensor

$$(iii) \quad \text{Bianchi identities: } R^{A,B} \wedge E_B = 0$$

$$\tau^{[c,D]; A]B} = 0 \quad \square$$

(iv) Einstein equations

$$\tau^{c,A}; c, B = 0 \quad \text{traceless}$$

Einstein equations

$$\bullet R^{A,B} = E_C \wedge E_D C^{AC, BD}$$

$C^{AC, BD}$ is Weyl tensor in the symmetric basis

$$C^{AB, CD} = C^{BA, CD} = C^{AB, DC}$$

(i) ∇ - transversal

$$(ii) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline \end{array} : C^{[AB, C]D} = 0$$

$$(iii) C^A_{A, BC} = 0$$

It is useful to treat $C^{AB, CD}(x)$ as an independent field variable expressed via the gravitational connections (i.e. frame and Lorentz connection) by \bullet

Bianchi Identities


$$\bullet R^{A,B} = E_c \wedge E_D C^{Ac, BD}$$


$$\Downarrow$$

$$E_c \wedge E_D \wedge [D^L C^{Ac, BD}] = 0 \quad D^L - \text{Lorentz}$$

$$\Downarrow$$

$$\bullet D^L C^{A_1 A_2, B_1 B_2} = E_c (C^{A_1 A_2 C, B_1 B_2} + C^{A_1 A_2 \{B_1, C B_2\}})$$

$C^{A_1 A_2 A_3, B_1 B_2}$ - any traceless, V^A transversal tensor of the symmetry type 

Bianchi impose differential conditions on $C^{A_1 A_2 A_3, B_1 B_2}$. These are solved in terms of $C^{A_1 \dots A_4, B_1 B_2}$ 

$$\bullet \bullet D^L C^{A_1 A_2 A_3, B_1 B_2} = E_c \left(C^{A_1 A_2 A_3 C, B_1 B_2} + \frac{2}{3} C^{A_1 A_2 A_3 B_1, C B_2} \right) + \dots$$

Nonlinear corrections due to \bullet

Continuation leads to an infinite system of equations on

$$C^{A_1 \dots A_p, B_1 B_2}(x) \quad \begin{array}{|c|c|c|c|} \hline & & P & \\ \hline & & \dots & \\ \hline S & & & \\ \hline \end{array}$$

$$\tilde{D}(C) = O(C^2)$$

$C^{A_1 \dots A_p, B_1 B_2}(x)$ forms some infinite

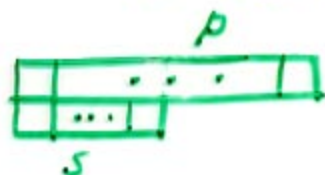
D_{40} dimensional representation of $O(2, d-2)$
 $O(2, d)$ c19

Any Spin

Weyl 0-forms

$$C^{A_1 \dots A_p, B_1 \dots B_s}(x) \quad p \geq s \quad s\text{-spin}$$

$$C^{A_1 \dots A_p, A_{p+1} B_2 \dots B_s}(x) = 0$$



$$C^{A_1 \dots A_{p-2} C, B_1 \dots B_s}(x) = 0 \quad \text{traceless}$$

$$\nabla_{A_1} C^{A_1 \dots A_p, B_1 \dots B_s}(x) = 0 \quad \text{Lorentz tensors}$$

Unfolded Field Equations

$$\left\{ \begin{aligned} R^{A_1 \dots A_{s-1}, B_1 \dots B_{s-1}} &= E_{A_s} \wedge E_{B_s} C^{A_1 \dots A_s, B_1 \dots B_s} \\ &\quad + \text{nonlinear corrections} \\ \tilde{D}(C^{A_1 \dots A_p, B_1 \dots B_s}) &= \text{nonlinear corrections} \end{aligned} \right.$$

$$\begin{aligned} \tilde{D}(C^{A_1 \dots A_p, B_1 \dots B_s}) &= \mathcal{D}^L(C^{A_1 \dots A_p, B_1 \dots B_s}) + \\ &+ E_C (C^{A_1 \dots A_p C, B_1 \dots B_s} + \frac{s}{(p+2-s)} C^{A_1 \dots A_p \{B_1, C B_2 \dots B_s\}}) \\ &+ O(\Lambda) + \text{nonlinear corrections} \end{aligned}$$

$S=0$ - scalar field equation O. Shaynkman, M.V. (200)

$$\partial_n C^{A_1 \dots A_p}(x) + E_n^C C^{A_1 \dots A_p C}(x) = 0$$

$$\partial_n C(x) = C_n(x) \quad \nabla\text{-transversality}$$

$$\partial_n C_m(x) = C_{nm}(x) \Rightarrow \square C = 0 \quad \text{tracelessness}$$

Free differential algebras

Unfolded HS field equations have a form

$$d\omega + \omega * \omega = -F_2(\omega, C)$$

$$dC + (\omega \circ C) = -F_1(\omega, C)$$

$$\omega = \omega_0 + \omega_1 \quad 1\text{-form}$$

$$C \quad 0\text{-form}$$

From now on the wedge symbol \wedge is omitted

It is a particular case of the system of the form

$$\bullet \quad R^\Lambda = 0$$
$$R^\Lambda \stackrel{d}{=} dW^\Lambda + F^\Lambda(W)$$

W^Λ - some set of p -forms ($p \geq 0$)

F^Λ contains wedge products of W^Λ

\bullet is consistent if

$$F^\Lambda \frac{\delta F^\Lambda}{\delta W^\Lambda} \equiv 0$$

generalized
Jacobi identity

Any F^Λ - some FDA

Properties of FDA's

(i) invariance under diffeomorphisms because of exterior algebra formalism

(ii) gauge invariance

$$\delta W^\Lambda = d\varepsilon^\Lambda - \varepsilon^\Omega \frac{\delta F^\Lambda}{\delta W^\Omega}$$

W^Λ - p -form

ε^Λ - $p-1$ -form

is a consequence of the generalized Jacobi identity

(iii) the equations

$$R^\Lambda = 0$$

are formally consistent as a consequence of the generalized Jacobi identities and gauge invariant because

$$\delta R^\Lambda = -R^\Omega \frac{\delta}{\delta W^\Omega} \left(\varepsilon^\Phi \frac{\delta F^\Lambda}{\delta W^\Phi} \right)$$

As a result, once free field dynamics of massless fields is reformulated in the "unfolded form" of some linearized FDA, any its consistent nonlinear deformation will describe consistent interaction

Particular examples

(i) if W^Λ consists of only 1-forms w^i , then

$$F^i(w) = f_{jk}^i w^j \wedge w^k$$

and the generalized Jacobi identity amounts to the usual Jacobi identity for a Lie algebra \mathfrak{g} with structure coefficients $f_{jk}^i = -f_{kj}^i$

$$f_{[ij}^e f_{k]e}^n = 0$$

The equation

$$\circ 0 = R^i \stackrel{\text{def}}{=} d w^i + f_{jk}^i w^j \wedge w^k$$

is the zero-curvature condition for the Lie algebra \mathfrak{g} . In applications \mathfrak{g} is the (A)dS space-time symmetry algebra $\mathfrak{o}(d-1, 2)$ or $\mathfrak{o}(d, 1)$ or some its extension: superextension, higher spin extension, etc.

A solution of \circ describes some vacuum of the theory

(ii) If W^A contains in addition some p -forms C^d (for example Weyl 0-forms in the HS case) and the function F^d is linear in C^d

$$F^d = 2t_i^d{}_\beta w^i C^\beta$$

the generalized Jacobi identities demand $t_i^d{}_\beta$ to form some representation of \mathfrak{g}

$$[t_i, t_j]^d{}_\beta = f_{ij}^k t_k^d{}_\beta$$

As a result, the equations

$$D C^d = d C^d + 2 t_i^d{}_\beta w^i C^\beta = 0$$

are covariant constancy condition for C^d taking values in an appropriate module over \mathfrak{g} .

D is covariant derivative in the representation t .

$$D^2 = 0 \iff d w^i + f_{jk}^i w^j w^k = 0$$

What is a representation t for

Twisted Adjoint Representation

\mathcal{T} - some automorphism

$$\mathcal{T}(ab) = \mathcal{T}(a) \mathcal{T}(b)$$

\mathcal{T} - twisted representation covariant derivative:

$$\hat{D}(C) = dC + \omega C - C \mathcal{T}(\omega)$$

In HS theories

$$\mathcal{T}(P^\alpha) = -P^\alpha \quad \mathcal{T}(L^{\alpha\beta}) = L^{\alpha\beta}$$

for the $(A)dS_d$ subalgebra

$$P^\alpha = M^{\alpha B} V_B$$

$$L^{\alpha\beta} = M^{\alpha\beta}$$

V^A transversal part
of M^{AB}

\mathcal{T} reflection with respect to V^A

$$\mathcal{T}(f(Y)) = \tilde{f}(\bar{Y}) \equiv f(\hat{Y})$$

$$\tilde{A}^A = A^A - \frac{2}{V^2} V^A V_B A^B$$

\mathcal{T} reflection is a symmetry of the metric η^{AB}

$$\tilde{\eta}^{AB} = \eta^{AB}$$

As a result \mathcal{T} preserves the defining commutation relations

$$[Y_i^A, Y_j^B]_* = \epsilon_{ij} \eta^{AB}$$

as well as the $sp(2)$ generator

$$t_{ij} = Y_i^A Y_{jA} \quad \mathcal{T}(t_{ij}) = t_{ij}$$

Thus \mathcal{T} is automorphism of the star product

$$f * g(Y) = \frac{1}{(2\pi)^{2(d+2)}} \int dS' dT' \exp(-2S_i^A T_j^B \epsilon_{ij}^{AB}) f(Y+S') g(Y+T')$$

as well as of the HS subalgebra formed by $sp(2)$ singlets (two row rectangular Young tableaux of the $(A)dS$ symmetry) modulo the ideal \mathcal{I} formed by the elements proportional to t_{ij}

Covariant derivatives in the adjoint and twisted adjoint representations

$$W^{AB} = \omega^{LAB} - \Lambda(E^A V^B - E^B V^A)$$

Lorentz connection ω^{LAB} is

V-transversal in A and B

E-dependent term is V-transversal in one index and V-parallel in another ($E^A V_A = 0$).

$$D_0 = D_0^L + 2 \left["Y_i^A V_A^\perp Y_j^B E_B, \right]_*$$

$$\tilde{D}_0 = D_0^L + 2 \left\{ "Y_i^A Y_j^B V_A^\perp E_B, \right\}_*$$

where D_0^L is the local Lorentz derivative

$$D_0^L = d + \left[\omega^{LAB} Y_{A_i}^\perp Y_{B_j} E^{ij}, \right]_*$$

and we use notations

$$A^A = "A^A + \perp A^A$$

$$"A^A = \frac{1}{\sqrt{2}} V^A V_B A^B, \quad \perp A^A = A^A - \frac{1}{\sqrt{2}} V^A V_B A^B$$

V-reflection acts as follows

$$\widetilde{"A^A} = - "A^A \quad \widetilde{\perp A^A} = \perp A^A$$

Using simple formulas

$$Y_i^A * = Y_i^A + \frac{1}{2} \frac{\partial}{\partial Y_A^i}$$

$$Y_A^i = \eta_{AB} \epsilon^{ij} Y_j^B$$

$$* Y_i^A = Y_i^A - \frac{1}{2} \frac{\partial}{\partial Y_A^i}$$

one gets

$$\mathcal{D}_0 = \mathcal{D}_0^4 - \Lambda E_0^A V^B \left(\overset{\perp}{Y}_{A^i} \frac{\partial}{\partial \overset{\parallel}{Y}_i^B} - \overset{\parallel}{Y}_{B^i} \frac{\partial}{\partial \overset{\perp}{Y}_i^A} \right)$$

$$\tilde{\mathcal{D}}_0 = \mathcal{D}_0^4 - 2\Lambda E_0^A V^B \left(\overset{\perp}{Y}_A^i \overset{\parallel}{Y}_{B^i} - \frac{1}{4} \epsilon^{ij} \frac{\partial^2}{\partial \overset{\perp}{Y}_A^i \partial \overset{\parallel}{Y}_{B^j}} \right)$$

\mathcal{D}_0 acts on finite-dimensional subspaces spanned by homogeneous polynomials

Invariant subspaces of $\tilde{\mathcal{D}}_0$ are infinite-dimensional because they involve polynomials of arbitrary high degrees

$$[N^{ad}, \mathcal{D}_0] = 0 \quad N^{ad} = Y_i^A \frac{\partial}{\partial Y_i^A}$$

$$[N^{tw}, \tilde{\mathcal{D}}_0] = 0 \quad N^{tw} = \overset{\perp}{Y}_i^A \frac{\partial}{\partial \overset{\perp}{Y}_i^A} - \overset{\parallel}{Y}_i^A \frac{\partial}{\partial \overset{\parallel}{Y}_i^A}$$

Unfolded Form of Free Equations

$$\begin{cases} R_1(Y) = E_0^A \wedge E_0^B \frac{\partial^2}{\partial Y_i^A \partial Y_j^B} \epsilon_{ij} C(Y) \Big|_{Y=0} \\ \tilde{D}_0 C(Y) = 0 \end{cases}$$

Free equations for all totally symmetric massless fields

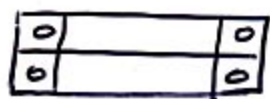
$$R_1(Y) = D_0 \omega_1$$

The field equations describe a set of subsystems

$$(N^+ + N'') \omega = N^{ad} \omega = 2(s-1) \omega$$

$$(N^+ - N'') C = N^{tw} C = 2s C$$

ω and C are $sp(2)$ singlets



$$\square : A = 0 \dots d$$

$N^+ \geq N'' \Rightarrow s \geq 0$ since otherwise the tensor is zero

Sets of Lorentz tensors

ω :

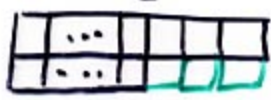


$$0 \leq t \leq s-1$$

t
 t

□ - v-parallel

C :



$$s \leq t < \infty$$

s

$t = s$: Weyl tensors

Examples

$$s=0$$



O. Shaynkman, N.V.
(2000)

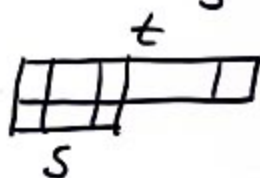
$$s=2$$



Lowest components



Weyl tensors



$t > s$: $(t-s)^{th}$ derivatives
of the Weyl tensors

Towards interactions

$$R(Y) = E^A{}_\lambda E^B{}^\lambda \frac{\partial^2}{\partial Y_i^A \partial Y_j^B} \epsilon_{ij} C(Y) \Big|_{Y=0} + \dots$$

$$\hat{D} C(Y) = 0 + \dots$$

where

$$R(Y) = d\omega(Y) + \omega(Y) \wedge \omega(Y)$$

$$\hat{D} C(Y) = dC(Y) + \omega(Y) * C(Y) - C(Y) * \omega(Y)$$

+... denote non-linear corrections

According to general properties of FDAs, once formal consistency is achieved, the system describes gauge invariant HS interactions

Deformed oscillator algebra

The key element of the construction is the $Sp(2)$ invariance condition which singles out appropriate tensor representations for higher spin fields.

To keep $Sp(2)$ invariance at the interaction level it is useful to use the properties of the following algebra

$$[q_i, q_j] = \epsilon_{ij} (1 + \nu k)$$

$$k q_i = -q_i k \quad k^2 = \underline{1}$$

ν - some parameter

(More generally $\nu k \Rightarrow Q$, $Q q_i = -q_i Q$)

Introduce

$$t_{ij} = \frac{1}{2} \{q_i, q_j\}$$

$$\bullet [t_{ij}, q_k] = \epsilon_{jk} q_i + \epsilon_{ik} q_j$$

for any ν

$$[t_{ij}, q_k] = \frac{1}{2} \{q_i, 1 + \nu k\} \epsilon_{jk} + \frac{1}{2} \{q_j, 1 + \nu k\} \epsilon_{ik}$$

the ν -dependent terms cancel out because $\{q_i, k\} = 0$

As a result, for any ν ,

q_i transforms as $sp(2)$ vector and, therefore, t_{ij} form $sp(2)$ algebra

$$\left\{ \begin{array}{l} t_{ij} = \frac{1}{2} \{q_i, q_j\} \\ [t_{ij}, q_k] = \epsilon_{jk} q_i + \epsilon_{ik} q_j \\ [t_{ij}, t_{kl}] = \epsilon_{ik} t_{jl} + \epsilon_{il} t_{jk} + \epsilon_{jl} t_{ik} + \epsilon_{il} t_{kj} \end{array} \right.$$

Алгебра $osp(1, 2)$

q_i - supercharges

A particular representation was found by Wigner in 1950 who was looking for most general commutation relations for oscillators a^\pm such that

$$[H, a^\pm] = \pm a^\pm, \quad H = \frac{1}{2} \{a, a^\dagger\}$$

$$a^\pm : q_{1,2}$$

$$H = t_{12}$$

2-body Calogero model: ν -coupling constant

Parameter ν is related to the quadratic Casimir operator of $osp(1,2)$

$$C_2 = \frac{1}{2} (t_{ij} t^{ij} - q_i q^i) = \frac{1}{4} (1 - \nu^2)$$

Deformed oscillator algebra allows one to describe a large class of representations of $osp(1,2)$ ($sp(2)$) including all lowest (highest) weight representations

$$q_2 |0\rangle = 0, \quad K |0\rangle = |0\rangle$$

$$H |0\rangle = \frac{1}{2} (1 + \nu) |0\rangle \quad H = t_{12} = \frac{1}{2} \{q_2, q_1\}$$

Deformed oscillator algebra is a useful realization of the fuzzy hyperboloid

$sp(2)$

$O(1,2)$

t_{ij}

$$X_\alpha = \delta_\alpha^{ij} t_{ij}$$

$$[X_\alpha, X_\beta] = \epsilon_{\alpha\beta\gamma} X^\gamma$$

$$C_2 = \frac{1}{2} X_\alpha X^\alpha = \frac{1}{2} R^2$$

$$R = R(\nu)$$

$$R \xrightarrow{\nu \rightarrow \infty} \infty$$

Nonlinear HS dynamics

hep-th/0304049

Idea to describe complicated nonlinear corrections as a solution of some simply formulated "differential equations" with respect to additional variables Z^A :

$$W = dx^n W_n(Z, Y|x) \quad \text{gauge fields}$$

$$B = B(Z, Y|x)$$

HS Weyl tensors +
 $s=0$ matter field

$$S = dZ^A S_A^i(Z, Y|x) \quad Z\text{-connection}$$

Dynamical HS fields used to formulate free field dynamics:

"initial data" for the evolution in Z -directions

$$W(0, Y|x) = \omega(Y|x)$$

$$B(0, Y|x) = C(Y|x)$$

$$S = dZ^A Z_A^i + \dots$$

Star-product of the form

$$(f * g)(Z, Y) = \frac{1}{\pi^{2(d+1)}} \int dS dT \exp -2 S_i^A T_A^i \\ \times f(Z+S, Y+S) g(Z-T, Y+T)$$

Oscillator algebra

$$[Y_i^A, Y_j^B]_* = \epsilon_{ij} \eta^{AB}$$

$$[Z_i^A, Z_j^B]_* = -\epsilon_{ij} \eta^{AB}$$

$$[Y_i^A, Z_j^B]_* = 0$$

$\overleftarrow{(Z-Y)} \overrightarrow{(Z+Y)}$ normal ordered

$$f(\overleftarrow{Z-Y}) * g(\overrightarrow{Z+Y}) = f(\overleftarrow{Z-Y}) g(\overrightarrow{Z+Y})$$

$$f(\overrightarrow{Z+Y}) * g(\overleftarrow{Z-Y}) = f(\overrightarrow{Z+Y}) g(\overleftarrow{Z-Y})$$

This star product admits
inner Klein operator

$$K = \exp\left(-\frac{2}{\sqrt{2}} V_A Z_i^A V_B Y^{Bi}\right)$$

$$K * f(Z, Y) = \tilde{f}(Z, Y) * K$$

$$\tilde{f}(Z, Y) = f(\tilde{Z}, \tilde{Y})$$

$$\widehat{(\overleftarrow{A^A})} = - \overleftarrow{A^A} \quad \widehat{(\overrightarrow{A^A})} = \overrightarrow{A^A}$$

Full Nonlinear System of HS equations in any dimension

$$* \begin{cases} dW + W * W = 0 \\ dS + W * S + S * W = 0 \\ dB + W * B - B * \tilde{W} = 0 \end{cases} \quad \begin{array}{l} \text{zero-curvature} \\ + \text{covariant} \\ \text{constancy} \\ \text{conditions} \end{array}$$

$$d = dx^n \frac{\partial}{\partial x^n}$$

$$** \begin{cases} S * B = B * \tilde{S} \\ S * S = -\frac{1}{2} dZ_i^A dZ^{B i} (\eta_{AB} - 4 \underbrace{V_A V_B}_{\Lambda^{-1}} B * K) \end{cases} \quad \tilde{S}(dZ, Z, Y) = S(d\hat{Z}, \hat{Z}, \hat{Y})$$

The differentials dZ_i^A, dx^n anticommute with themselves but commute with $f(Z, Y | x)$

K is inner Klein operator

$$K * f(Z, Y) = \tilde{f}(Z, Y) * K$$

The system is invariant under HS gauge transformations

$$\delta W = d\varepsilon + [W, \varepsilon]_* \quad \text{adjoint}$$

$$\delta S = [S, \varepsilon]_* \quad \text{adjoint}$$

$$D57 \quad \delta B = B * \tilde{\varepsilon} - \varepsilon * B \quad \text{twisted adjoint}$$

Formal Consistency

Usual gauge fields

$$\Omega = d + W$$

$$R = \Omega^2 = \{d, W\} + W^2 \quad d^2 = 0$$

Bianchi identities

$$0 = [\Omega, R] \equiv \Omega(\Omega\Omega) - (\Omega\Omega)\Omega$$

\equiv associativity

Gauge transformations are similarity transformations

$$\Omega' = U \Omega U^{-1}$$

If some conditions on the curvature R are imposed, they should respect Bianchi identities and be gauge invariant

Non commutative connection

$$\mathcal{S} = dZ^A \mathcal{S}_A^i (Z, Y | x)$$

can be decomposed

$$\mathcal{S} = \mathcal{S}_0 + \mathcal{S}_1$$

$$\mathcal{S}_0 = dZ^A Z_A^i \quad \text{differentiale}$$

$$\mathcal{S}_1 \quad \text{gauge field}$$

$$[\mathcal{S}_0,] = -dZ^A \frac{\partial}{\partial Z^A} \quad \text{analogue of de Rham differential}$$

$$\mathcal{S}_0 * \mathcal{S}_0 = -\frac{1}{2} dZ^A dZ_A^i$$

Bianchi identities = associativity

$$(\mathcal{S} * \mathcal{S}) * \mathcal{S} = \mathcal{S} * (\mathcal{S} * \mathcal{S})$$

+ analogous conditions between X-sector and Z-sector

In terms of the universal connection

$$\mathcal{W} = d + W + S'$$

$$d = dx^n \frac{\partial}{\partial x^n}$$

$$W = dx^n W_n$$

$$S' = dZ^A; S'_A$$

the full system of HS equations takes the following simple form

$$\begin{cases} * \mathcal{W} * \mathcal{W} = -\frac{1}{2} dZ^A_i dZ^i_A + 2 dZ_i dZ^i B * K \\ * \mathcal{W} * B = B * \widetilde{\mathcal{W}} \\ * \end{cases}$$

* means that non-zero curvature components appear only in $dZ dZ$ - sector

$$dZ_i = V_A dZ^A_i \quad - \quad V \text{ parallel components of } dZ^A_i$$

$$\widetilde{(dZ_i)} = -(dZ_i)$$

Because inner Klein operator K acts only on Z^A_i, Y^A_i but not on dZ^A_i

* implies

$$\mathcal{W} * (B * K) = (B * K) * \mathcal{W}'$$

$$\mathcal{W}'(dZ, Z, Y|x) = \mathcal{W}(d\widetilde{Z}, Z, \widetilde{Y}|x)$$

Consistent because $(dZ_i)^3 = 0 \quad (i=1,2)$

HS equations and deformed oscillator

The nontrivial curvature proportional to the field B (to be proportional to HS Weyl tensors) is in the sector of V -parallel components of $S_A^{i'}$

Let

$$S^i = \frac{1}{\sqrt{V^2}} V^A S_A^{i'}$$

The nontrivial part of equations

$$\begin{cases} [S^i, S^j]_* = -\epsilon^{ij} (1 + 4\Lambda^{-1} B * k) \\ S^i * (B * k) = -(B * k) * S^i \end{cases}$$

Deformed oscillator algebra

$$\tilde{T}_{ij} = -\frac{1}{2} \{S_i^A, S_{jA}\}_* = -\frac{1}{2} (\{S_i, S_j\}_* + \{S_i^A, S_{jA}\})$$

\tilde{T}_{ij} form $sp(2)$ for any B ordinary oscillators

How dual $sp(2)$ generators for non-linear theory

$$t_{ij}^{int} = Y_i^A Y_{jA} - Z_i^A Z_{jA} - \tilde{T}_{ij} \quad \text{with } t_{ij}^{int} = t_{ij}^{int}$$

HS equations: fuzzy hyperboloid

of radius

$$r = \Lambda^{-1} B * k$$

$\Lambda^{-1}: R^2_{AdS}$

$r \rightarrow \infty$ in the flat space-time limit

Perturbative Analysis

Simplest vacuum solution

$$B_0 = 0, \quad S'_0 = dZ^A; Z^i_A$$

$$W_0 = \frac{1}{4} \omega_0^{AB}(x) \{Y^i_A, Y^i_B\}_*$$

where $\omega_0^{AB}(x)$ describes $(A)dS_d$
to satisfy $R(W_0) = 0$

Expanding

$$W = W_0 + W_1, \quad S' = S'_0 + S'_1, \quad B = B_1$$

one solves the equations which
contain $\frac{\partial}{\partial Z}$ (i.e. S')

Modulo gauge ambiguity, all fields
are expressed in terms of "initial data"

$$C(Y|x) = B(0, Y|x)$$

$$\omega(Y|x) = W(0, Y|x)$$

The S' -independent equations

$$dW + W * W = 0, \quad dB + W * B - B * \tilde{W} = 0$$

reproduce the free massless
equations with all nonlinear
connections

Linearized equations

(i) Solve

$$S_0 * B_1 = B_1 * S_0$$

$$\tilde{S}_0 = S_0$$

$$\Downarrow$$
$$dZ^A \frac{\partial}{\partial Z^A} B_1 = 0$$

$$\Downarrow$$
$$B_1(Z, Y|x) = C(Y|x)$$

(ii) Since all components of the curvature in ${}^{\perp}Z^A$ directions are zero, the components ${}^{\perp}S_A^i$ can be gauge fixed to ${}^{\perp}S_{0A}^i$. The leftover symmetry parameters $\mathcal{E}(Z, Y|x)$ satisfy $[{}^{\perp}S_{0A}^i, \mathcal{E}]_* = 0$, i.e. \mathcal{E} is independent of ${}^{\perp}Z^A$.

$$\mathcal{E} = \mathcal{E}(Z, Y|x)$$

Analogously, from

$$dS + \{W, S\}_* = 0$$

in the sector of dZ^A , it follows

$$W = W(Z, Y|x)$$

As a result, Z^A dependence enters only via $\tilde{Z}_i = \frac{1}{\sqrt{V^2}} V_A Z^A$

(iii) To solve the fuzzy hyperboloid equation one first uses

$$(f * \kappa)(Z; Y) = \exp -2z_i y^i f(-Y, Z^{\perp}, Z^{\perp} Y)$$

$$\kappa = \exp -2z_i y^i$$

i.e. κ interchanges " Y " and " Z "

(elementary to check using the $*$ product)

Then, the fuzzy hyperboloid equation

$$\frac{\partial}{\partial z_i} S_1^i - \frac{\partial}{\partial z_j} S_1^j = -4\Lambda^{-1} \epsilon^{ij} C(-Z, Y) \exp(-2z_k y^k)$$

solves to

$$S^j = \frac{\partial}{\partial z_j} \epsilon_1 + 2\Lambda^{-1} z^j \int_0^1 dt t C(-tZ, Y) \times \exp(-2t z_k y^k)$$

(General formula: if $\partial^i S^j - \partial^j S^i = -2\epsilon^{ij} f(z)$
then $S^i = \partial^i \epsilon + z^j \int_0^1 dt t f(tz)$)

The ambiguity in ϵ_1 manifests the gauge ambiguity $\delta S_1^i = [S_0^i, \epsilon_1]$

Convenient gauge: $\frac{\partial}{\partial z_j} \epsilon_1 = 0$

$$\epsilon_1 = \epsilon_2(Y|x) - HS \text{ gauge}$$

parameters of dynamical degrees of freedom.

As a result \mathcal{S} is expressed in terms of $B_1 = C(Y)$: non-commutative connection is expressed via non-comm. curvature modulo gauge ambiguity.

It remains to analyse the equations with space-time differentials

$$\bullet dW + W * W = 0$$

$$\bullet\bullet dS + W * S + S * W = 0$$

$$\bullet\bullet\bullet dB + W * B - B * \widehat{W} = 0$$

(v) The nontrivial part (i.e. V -parallel) reads

$$\frac{\partial}{\partial z_i} W_1 = dS_1^i + W_0 * S_1^i - S_1^i * W_0$$

Using that the equation $\frac{\partial}{\partial z_i} \varphi = \chi^i$

solves as $\varphi(z) = \text{const} + \int_0^1 dt z_i \chi^i(tz)$

provided that $\frac{\partial}{\partial z_i} \chi^i = 0$ ($i=1,2$) one gets

$$W_1(Z, Y|x) = \omega(Y|x) - Z_A^i V^A \int_0^1 dt (1-t) \times e^{-2t z_i y^i} E^B \frac{\partial}{\partial Y^j B} C(-t^2 Z, Y^\perp)$$

$\omega(Y|x)$ is the dynamical HS gauge field.

It remains to plug this expression into \bullet and $B = C(Y|x)$ into $\bullet\bullet\bullet$

Because the dependence on Z is fixed by the equations consistent with $\bullet, \bullet\bullet, \bullet\bullet\bullet$ equations, it is enough to consider $\bullet, \bullet\bullet\bullet$ say at $Z=0$

As a result

$$dW + W * W = 0$$

$$dB + W * B - B * \tilde{W} = 0$$

give at $Z=0$

$$\begin{cases} R_1(Y|x) = E_0^A \wedge E_0^B \frac{\partial^2}{\partial^+ Y^A \partial^+ Y^B} \epsilon_i; C(Y|x) + \dots \\ \tilde{D}_0 C(Y|x) = 0 + \dots \end{cases}$$

"Y=0
because "Z=0"

$$R_1 = \tilde{D}_0 \omega(Y|x)$$

where ... denote all non-linear corrections which can be systematically reconstructed using the same procedure.

Comment: Klein operator $K = \exp(-2Z_i Y^i)$ is non-polynomial and it is necessary to prove that all star products are well-defined (finite). This is indeed true within the star-product used. All higher-order corrections are well-defined.

Internal Symmetries

$$W_{\nu}^{\mu}(Z, Y|x), S_{\nu}^{\mu}(Z, Y|x), B_{\nu}^{\mu}(Z, Y|x)$$

$$\nu, \mu = 1 \dots p$$

Equations: associative structure

Reality conditions

$$W^{\dagger}(Z, Y|x) = -W(-iZ, i\bar{Y}|x)$$

HS algebra $\mathfrak{h}(\mathfrak{u}(p) | \mathfrak{sp}(2)[2, d-1])$
AdS

All fields in $\mathfrak{u}(p)$ - YM algebra

Orthogonal and symplectic reductions

$$W_{\nu}^{\mu}(Z, Y|x) = -\rho^{\mu\mu'} W_{\mu'}^{\nu'}(-iZ, i\bar{Y}|x) \rho_{\nu'\nu}$$

$$\rho^{\nu\mu} = \rho^{\mu\nu} : \mathfrak{h}(\mathfrak{o}(p) | \mathfrak{sp}(2)[2, d-1])$$

YM: $\mathfrak{o}(p)$

$$\rho^{\nu\mu} = -\rho^{\mu\nu} : \mathfrak{h}(\mathfrak{usp}(p) | \mathfrak{sp}(2)[2, d-1])$$

YM: $\mathfrak{usp}(p)$

Odd spins: in YM algebra
YM sector

Even spins: in opposite symmetry

graviton second rank representation which contains YM singlet

267 Minimal model - only even spins $\mathfrak{h}(\mathfrak{o}(1) | \mathfrak{sp}(2)[2, d-1])$

Interaction Ambiguity

No ambiguity modulo nonlinear field redefinitions!

$$g^2 = |\Lambda| \frac{d-2}{2} \kappa^2$$

YM constant can be rescaled away for the classical HS model

(Different from 4d model that has a freedom in one function distinguishing between self-dual and anti self-dual sectors. Lagrangian)

Nontrivial part of the system is fixed by the condition

$$t_{ij} = \frac{1}{2} \{Y^A_i, Y_{jA}\}_* \rightarrow t_{ij}^{int} \text{ forms } SP(2)$$

and allows

$$D(t_{ij}^{int}) = 0 \quad [S, t_{ij}^{int}]_* = 0$$

$$B * \hat{t}_{ij}^{int} - t_{ij}^{int} * B = 0$$

reduction of the space of fields

to

 and factorization $|\underline{T}^{int}$

Discussion

5

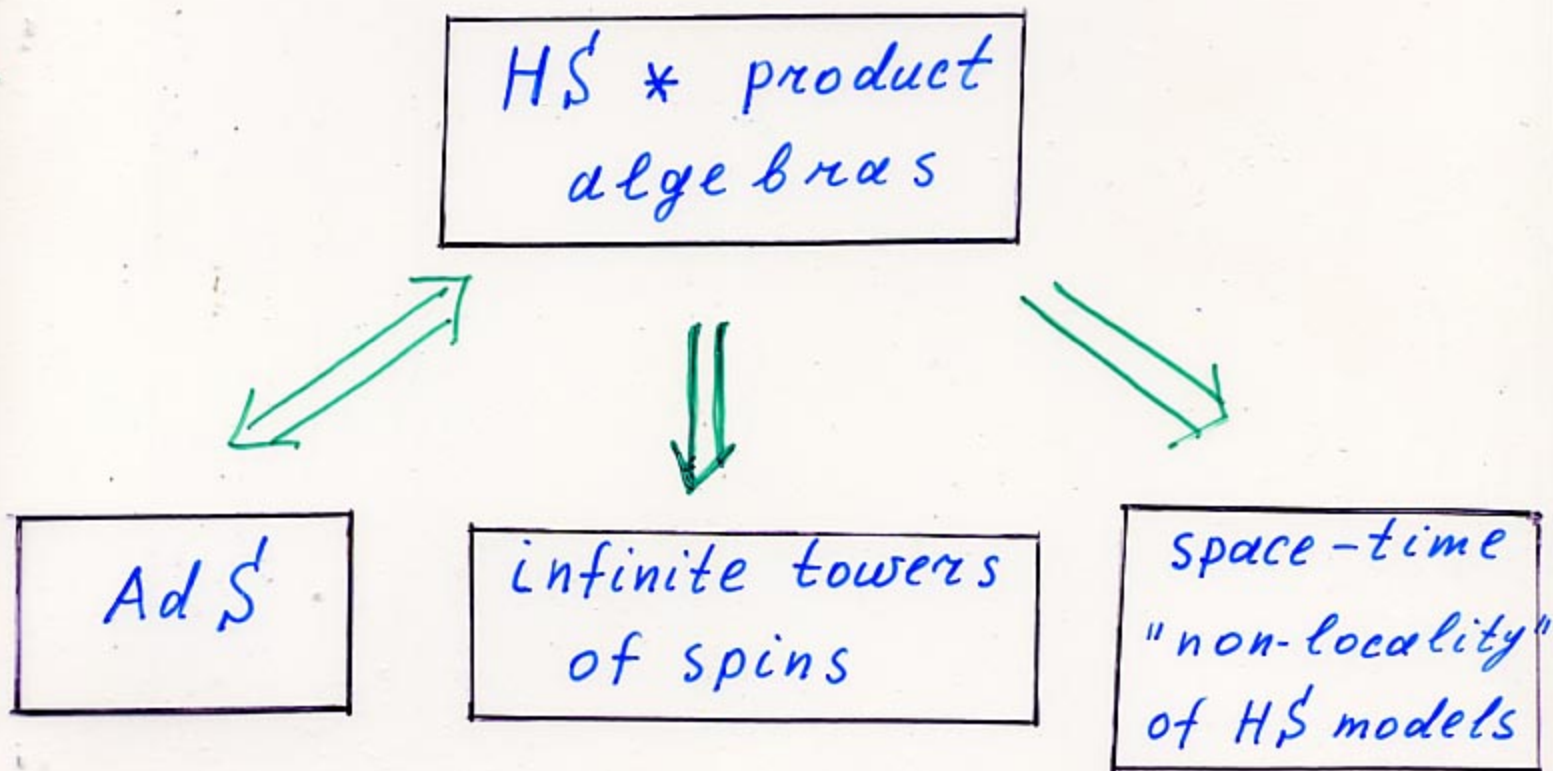
Quantum mechanical nonlocality of the star-product gives rise to higher derivatives in higher spin interactions via field equations

For example

$$\tilde{D}_0 C = 0$$

$$\tilde{D}_0 = D_0^4 - 2\Lambda E_0^A V^B (\gamma_A^{i\pi} \gamma_{Bj} - \frac{1}{4} \epsilon^{ij} \frac{\partial^2}{\partial Y^A i \partial Y^B j})$$

links $\frac{\partial}{\partial x}$ with $\frac{\partial^2}{\partial Y \partial Y}$



The part of the nonlinear system that contains space-time derivatives

$$\begin{cases} dW + W * W = 0 \\ dS + W * S + S * W = 0 \\ dB + W * B - B * \tilde{W} = 0 \end{cases}$$

admits a solution (locally)

$$W = g^{-1} * dg$$

$$S = g^{-1} * s * g$$

$$B = g^{-1} * b * \tilde{g}$$

where

$g = g(Z, Y | x)$ is an arbitrary gauge function

$$\left. \begin{aligned} s = s(Z, Y) = dZ^A, s^i_A(Z, Y) \\ b = b(Z, Y) \end{aligned} \right\} \begin{array}{l} \text{arbitrary} \\ x\text{-independent} \\ \text{elements} \end{array}$$

Because of gauge invariance, one is left with the equations

$$\begin{cases} s * b = b * \tilde{s} \\ s * s = -\frac{1}{2} dZ^A, dZ^B, (\eta_{AB} - 4V_A V_B) b * k \end{cases}$$

which do not contain x

Hence nonlinear dynamics is reformulated as the fuzzy hyperboloid equation

270 in a non-commutative space-time!
Local events!!

Conclusions

- o A class of non-linear HS gauge theories in $(A)dS_d$ exists.

So far - totally symmetric HS gauge fields.

SUSY in AdS₄

Different Chan-Paton structures =
= Yang-Mills algebras

- o HS equations describe a noncommutative hyperboloid in the "auxiliary" noncommutative space

$$R_{H^2}(\Lambda^{-2} B(Z, Y | x))$$

^p
HS curvatures

Minkowski coordinates x allow visualization (local events)

- o Higher derivatives in x ~~allow~~ result from Moyal non-locality in the "fuzzy" fiber.

Open Problems

- Extension to mixed symmetry massless fields



Labastida (2009)

Free mixed symmetry fields in AdS_d are different from (irreducible) fields in Minkowski

Brink, Metsaev, N.V. (2000)

- Action in all orders
- To find nontrivial solutions with massive modules m to define a low-energy expansion in $(\frac{\partial}{m})^p$

$$\Lambda : (\Lambda^{-\frac{1}{2}} D)^p \sim 1 \quad [D, D] \sim \Lambda$$

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strings

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